

Machine Learning

Maximum Likelihood Principle

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WS2013/2014, 8.11.2013



Let a parameterized class (family) of probability distributions be given, i.e. $p(x; \theta) \in \mathcal{P}$

Example – the set of Gaussians in \mathbb{R}^n

$$p(x; \mu, \sigma) = \frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left[-\frac{\|x - \mu\|^2}{2\sigma^2}\right]$$

parameterized by the mean $\mu \in \mathbb{R}^n$ and standard deviation $\sigma \in \mathbb{R}$, i.e. $\theta = (\mu, \sigma)$.

Let the training data be given, e.g. $L = (x^1, x^2, \dots, x^{|L|})$,
e.g. $x^l \in \mathbb{R}^n$ for Gaussians

One have to decide for a particular probability distribution from the given family, i.e. for a particular (the “best”) parameter, e.g. $\theta^* = (\mu^*, \sigma^*)$ for Gaussians.

Assumption: the training data is a realization of the unknown probability distribution – it is sampled according to it.

→ what is observed should have a high probability

→ maximize the probability of the training data with respect to the unknown parameter

$$p(L; \theta) \rightarrow \max_{\theta}$$

All further stuff are just examples/special cases ...

Discrete Probability Distributions

The free parameter is a “vector” of probability values

$$\theta = p(k) \in \mathbb{R}^{|K|}, \quad p(k) \geq 0, \quad \sum_k p(k) = 1$$

Training data: $L = (k^1, k^2, \dots, k^{|L|})$, $k^l \in K$

Assumption (very often): independent examples

$$P(L; \theta) = \prod_l p(k^l) = \prod_k \prod_{l:k^l=k} p(k) = \prod_k p(k)^{n(k)}$$

with the frequencies $n(k)$ in the training data

$$\ln P(L; \theta) = \sum_k n(k) \ln p(k) \rightarrow \max_p$$

or (for infinite training data)

$$\ln P(L; \theta) = \sum_k p^*(k) \ln p(k) \rightarrow \max_p$$

$$\sum_i a_i \ln x_i \rightarrow \max_x, \quad \text{s.t. } x_i \geq 0 \forall i, \quad \sum_i x_i = 1 \text{ with } a_i \geq 0$$

Method of Lagrange coefficients:

$$F = \sum_i a_i \ln x_i + \lambda \left(\sum_i x_i - 1 \right) \rightarrow \min_{\lambda} \max_x$$

$$\frac{\partial F}{\partial x_i} = \frac{a_i}{x_i} + \lambda = 0 \quad // \text{Note: } \lambda \text{ is common for all } i$$

$$x_i = c \cdot a_i \quad \text{and} \quad \sum_i c \cdot a_i = 1$$

$$x_i = \frac{a_i}{\sum_{i'} a_{i'}}$$

Solution for general discrete probability distributions:
count the frequencies of k , normalize to sum to 1.

Example – Gaussians

$$p(x; \mu, \sigma) = \frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left[-\frac{\|x - \mu\|^2}{2\sigma^2}\right],$$

i.e. $\theta = (\mu, \sigma)$, with $\mu \in \mathbb{R}^n$, $\sigma \in \mathbb{R}$.

$$\begin{aligned} \ln p(L; \mu, \sigma) &= \sum_l \left[-n \ln \sigma - \frac{\|x^l - \mu\|^2}{2\sigma^2} \right] = \\ &= -|L| \cdot n \cdot \ln \sigma - \frac{1}{2\sigma^2} \sum_l \|x^l - \mu\|^2 \rightarrow \max_{\mu, \sigma} \end{aligned}$$

$$\frac{d \ln p(L; \mu, \sigma)}{d\mu} = 0 \quad \Rightarrow \quad \mu = \frac{1}{|L|} \sum_l x^l$$

$$\frac{d \ln p(L; \mu, \sigma)}{d\sigma} = 0 \quad \Rightarrow \quad \sigma = \frac{1}{n \cdot |L|} \sum_l \|x^l - \mu\|^2$$

“Mixed” models for recognition

$p(x, k; \theta) = p(k; \theta_a) \cdot p(x|k; \theta_k)$, with $k \in K$ (classes, usually discrete) and $x \in X$ (observations, general)

Unknown parameters are $\theta_a = p(k)$ and class-specific θ_k

Training data consists of pairs $L = ((x^1, k^1), \dots, (x^{|L|}, k^{|L|}))$

$$\begin{aligned}\ln p(L; \theta) &= \sum_l \left[\ln p(k^l) + \ln p(x^l | k^l; \theta_{k^l}) \right] = \\ &= \sum_k n(k) \ln p(k) + \sum_k \sum_{l:k^l=k} \ln p(x^l | k; \theta_k) \rightarrow \max_{p(k), \theta_k}\end{aligned}$$

can be optimized **independently** with respect to $\theta_a, \theta_1 \dots \theta_{|K|}$

This was a **supervised** learning

The task:

The probability model is $p(x, k; \theta)$ as before,

training data are **incomplete**, i.e. $L = (x^1, x^2, \dots, x^{|L|})$
– classes are not observed.

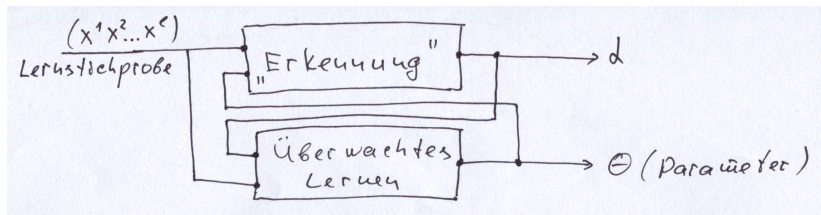
Maximum Likelihood reads:

$$\ln p(L; \theta) = \sum_l \ln p(x^l; \theta) = \sum_l \ln \sum_k p(x^l, k; \theta) \rightarrow \max_{\theta}$$

Problem – “ $\sum \ln \sum$ ”

Expectation Maximization Algorithm (idea)

An iterative approach:



1. "Recognition" (complete the data):
 $(x^1, x^2, \dots), \theta \Rightarrow$ "classes"
2. Supervised learning:
"classes", $(x^1, x^2, \dots) \Rightarrow \theta$

Note: Bayesian recognition is not possible, since there is no loss-function !!!

Expectation Maximization Algorithm (derivation)

The task:

$$\ln p(L; \theta) = \sum_l \ln p(x^l; \theta) = \sum_l \ln \sum_k p(x, k^l; \theta) \rightarrow \max_{\theta}$$

We introduce a “redundant 1” and re-write it as

$$\sum_l \left[\sum_k \alpha_l(k) \ln p(k, x^l; \theta) - \sum_k \alpha_l(k) \ln \frac{p(k, x^l; \theta)}{\sum_{k'} p(k', x^l; \theta)} \right]$$

with $\alpha_l(k) \geq 0$ and $\sum_k \alpha_l(k) = 1$ for all l .

With such α -s the two above expressions are equivalent !!!

Expectation Maximization Algorithm (derivation)

Proof of the equivalence for one example:

$$\begin{aligned} \sum_k \alpha_l(k) \ln p(k, x^l; \theta) - \sum_k \alpha_l(k) \ln \frac{p(k, x^l; \theta)}{\sum_{k'} p(k', x^l; \theta)} &= \\ &= \sum_k \left[\alpha_l(k) \ln p(k, x^l; \theta) - \right. \\ &\quad \left. - \left[\alpha_l(k) \ln p(k, x^l; \theta) - \alpha_l(k) \ln \sum_{k'} p(k', x^l; \theta) \right] \right] = \\ \sum_k \alpha_l(k) \ln \sum_{k'} p(k', x^l; \theta) &= \ln \sum_{k'} p(k', x^l; \theta) \cdot \sum_k \alpha_l(k) = \\ = \ln \sum_{k'} p(k', x^l; \theta) \end{aligned}$$

(for many x^l just sum up)

Expectation Maximization Algorithm

To summarize (shorthand) we have:

$$\ln p(L; \theta) = F(\theta, \alpha) - G(\theta, \alpha) \rightarrow \max_{\theta}$$

with

$$\begin{aligned} F(\theta, \alpha) &= \sum_l \sum_k \alpha_l(k) \ln p(k, x^l; \theta) \\ G(\theta, \alpha) &= \sum_l \sum_k \alpha_l(k) \ln \frac{p(k, x^l; \theta)}{\sum_{k'} p(k', x^l; \theta)} = \\ &= \sum_l \sum_k \alpha_l(k) \ln p(k|x^l; \theta) \end{aligned}$$

Note:

both F and G are usually concave but not their difference.

Expectation Maximization Algorithm

$$\ln p(L; \theta) = F(\theta, \alpha) - G(\theta, \alpha) \rightarrow \max_{\theta}$$

Start with an arbitrary $\theta^{(0)}$, repeat:

1. **Expectation** step: “complete the data”.
Choose $\alpha^{(t)}$ so that $G(\theta, \alpha)$ reaches its maximum with respect to θ at the actual value $\theta^{(t)}$. Note: this is **not an optimization**, this is the estimation of an **upper bound** of G !!! According to the Shannon Lemma:

$$\alpha_l^{(t)}(k) = p(k|x^l; \theta^{(t)})$$

2. **Maximization** step: “supervised learning”.

$$\theta^{(t+1)} = \arg \max_{\theta} F(\theta, \alpha^{(t)})$$

Note: as $G(\theta, \alpha)$ reaches its maximum at $\theta^{(t)}$, the second addend may only decrease (the likelihood is maximized)!!!

Some comments to the Maximum Likelihood

Maximum Likelihood estimator is not the only estimator – there are many others as well.

Maximum Likelihood is **consistent**, i.e. it gives the true parameters for infinite training sets.

Consider the following experiment for an estimator:

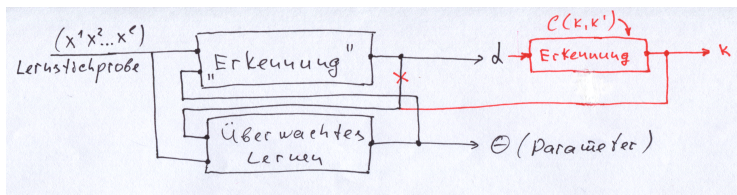
1. We generate **infinite** numbers of training sets each one being **finite**;
2. For each training set we estimate the parameter;
3. We average all estimated values.

If the average is the true parameter, the estimator is called **unbiased**. Maximum Likelihood is not always unbiased – it depends on the parameter to be estimated. Examples – the mean for a Gaussian is unbiased, the standard deviation – not.

Some comments to the EM-Algorithm

EM always converges, but not always to the global optimum :-)

A “commonly used” technique:



The expectation step is replaced by a “real” recognition. It becomes similar to the K-Means algorithm and is often called “EM-like schema”. It is **wrong!!!** It is no EM. It is an approximation of the Maximum Likelihood – the so called Saddle-Point approximation. However, it is very popular because in the practice it is often much simpler to do recognition as to compute posterior probabilities α .