

# Static Maxwell Type Problems: Functional A Posteriori Error Estimates and Estimates for the Maxwell Constant in 3D

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# Functional A Posteriori Error Estimates

## Part 1

# Functional A Posteriori Error Estimates for Static Maxwell Type Problems

# Introduction: (simple) Electro Static Maxwell Problem

- simple:  $\varepsilon, \mu = \text{id}$ , only hom. bc, only tang. (electric) bc, no mixed bc
- $\Omega \subset \mathbb{R}^3$  bounded domain with Lipschitz boundary  $\Gamma = \partial\Omega$
- $E : \Omega \rightarrow \mathbb{R}^3$  electric vector field
- $F : \Omega \rightarrow \mathbb{R}^3, G : \Omega \rightarrow \mathbb{R}$  given right hand side data
- $\tau$  tangential trace, i.e.,  $\tau E = n \times E|_{\Gamma} : \Gamma \rightarrow \mathbb{R}^3$  (for smooth  $E$ )
- $\perp$  orthogonality w.r.t.  $L^2(\Omega)$ -scalar product  $\langle E, H \rangle_{L^2(\Omega)} := \int_{\Omega} E \cdot H$
- $E \in \mathcal{H}_D(\Omega)$  Dirichlet field  $\Leftrightarrow E \in L^2(\Omega)$  &  $\text{rot } E = 0, \text{div } E = 0$  and  $\tau E = 0$

$$\text{rot } E = F \quad \text{in } \Omega$$

$$\text{div } E = G \quad \text{in } \Omega$$

$$\tau E = 0 \quad \text{on } \Gamma$$

$$E \perp \mathcal{H}_D(\Omega)$$

- GOAL: non-conforming estimates for error  $e := E - \tilde{E}$ ,  $\tilde{E}$  approximation of  $E$   
JUST:  $\tilde{E} \in L^2(\Omega)$

# Introduction: Dirichlet Laplace Problem

- $u \in H^1(\Omega)$  with

$$\Delta u = \operatorname{div} \nabla u = G, \quad u|_{\Gamma} = 0$$

- set  $E := \nabla u$

- note:  $\operatorname{rot} E = 0$ ,  $n \times E|_{\Gamma} = \nabla_{\Gamma} u|_{\Gamma} = 0$  (since  $d \iota^* = \iota^* d$ ) and  $E \perp \mathcal{H}_D(\Omega)$

$$\begin{aligned} \Rightarrow \operatorname{rot} E &= 0 && \text{in } \Omega \\ \operatorname{div} E &= G && \text{in } \Omega \\ \tau E &= 0 && \text{on } \Gamma \\ E &\perp \mathcal{H}_D(\Omega) \end{aligned}$$

- $\Rightarrow$  non-conforming estimates for error  $e := \nabla u - \tilde{E}$   
 JUST:  $\tilde{E} \in L^2(\Omega)$  approximation of  $E = \nabla u$
- $\Rightarrow$  non-conforming estimates of energy norm

# Introduction: rot rot-Problem

- $U \in R(\Omega)$  with

$$\operatorname{rot} \operatorname{rot} U = F, \quad n \times \operatorname{rot} U|_{\Gamma} = 0$$

- set  $E := \operatorname{rot} U$
- note:  $\operatorname{div} E = 0$ ,  $n \times E|_{\Gamma} = 0$  and  $E \perp \mathcal{H}_D(\Omega)$

$$\begin{aligned} \Rightarrow \operatorname{rot} E &= F && \text{in } \Omega \\ \operatorname{div} E &= 0 && \text{in } \Omega \\ \tau E &= 0 && \text{on } \Gamma \\ E &\perp \mathcal{H}_D(\Omega) \end{aligned}$$

- $\Rightarrow$  non-conforming estimates for error  $e := \operatorname{rot} U - \tilde{E}$   
 JUST:  $\tilde{E} \in L^2(\Omega)$  approximation of  $E = \operatorname{rot} U$
- $\Rightarrow$  non-conforming estimates of energy norm

# Solution Theory

$$\operatorname{rot} E = F \quad \text{in } \Omega$$

$$\operatorname{div} E = G \quad \text{in } \Omega$$

$$\tau E = 0 \quad \text{on } \Gamma$$

$$E \perp \mathcal{H}_D(\Omega)$$

$$\begin{array}{llll} \text{split} & & & \\ \Rightarrow & \operatorname{rot} E_{\operatorname{rot}} = F, & \operatorname{rot} E_{\nabla} = 0 & \text{in } \Omega \\ & \operatorname{div} E_{\operatorname{rot}} = 0, & \operatorname{div} E_{\nabla} = G & \text{in } \Omega \quad (2 \text{ electro static} \\ & \tau E_{\operatorname{rot}} = 0, & \tau E_{\nabla} = 0 & \text{on } \Gamma \quad \text{Maxwell problems)} \\ & E_{\operatorname{rot}} \perp \mathcal{H}_D(\Omega), & E_{\nabla} \perp \mathcal{H}_D(\Omega) & \end{array}$$

introducing scalar and vector potentials  $u$  and  $U$  solving

$$\Delta U = \operatorname{rot} \operatorname{rot} U = F, \quad \Delta u = \operatorname{div} \nabla u = G \quad \text{in } \Omega$$

$$\operatorname{div} U = 0 \quad \text{in } \Omega$$

$$\tau \operatorname{rot} U = 0, \quad u = 0 \quad \text{on } \Gamma$$

variational formulations for  $u$  and  $U$  (right Hilbert spaces)

$\Rightarrow E_{\operatorname{rot}} := \operatorname{rot} U$  and  $E_{\nabla} := \nabla u$  as well as  $E := E_{\operatorname{rot}} + E_{\nabla}$

# Method for Error Estimates

$$\begin{aligned}
 \operatorname{rot} E &= F && \text{in } \Omega \\
 \operatorname{div} E &= G && \text{in } \Omega \quad (\text{electro static Maxwell problem}) \\
 \tau E &= 0 && \text{on } \Gamma \\
 E &\perp \mathcal{H}_D(\Omega)
 \end{aligned}$$

- method: funct. a post. error est. for linear second order elliptic problems  
pioneering work of Sergey Repin starting 1990's  
later extended to 'all' linear and non-linear second order elliptic problems  
(Laplace, elastic, parabolic, hyperbolic, even order problems, ...)
- Maxwell system is first order! What to do?
- solution: Helmholtz decomposition  $\Rightarrow$  scalar and vector potentials  
 $\Rightarrow$  second order methods for the potentials

# Sobolev Spaces

spaces

$$R(\Omega) := \{E \in L^2(\Omega) : \operatorname{rot} E \in L^2(\Omega)\}$$

$$R_0(\Omega) := \{E \in R(\Omega) : \operatorname{rot} E = 0\}$$

$$\mathring{R}(\Omega) := \{E \in R(\Omega) : \tau E = 0\} = \overline{\mathring{C}^\infty(\Omega)}^{R(\Omega)} \quad (\text{Gauß' theorem})$$

$$\mathring{R}_0(\Omega) := \mathring{R}(\Omega) \cap R_0(\Omega)$$

analogously

$$D(\Omega), \quad D_0(\Omega), \quad \mathring{D}(\Omega), \quad \mathring{D}_0(\Omega)$$

and

$$\begin{aligned} \mathcal{H}_D(\Omega) &:= \mathring{R}_0(\Omega) \cap D_0(\Omega) \quad (\text{finite dimensionl since } \mathring{R}(\Omega) \cap D(\Omega) \hookrightarrow L^2(\Omega) \text{ compact}) \\ &= \{E \in L^2(\Omega) : \operatorname{rot} E = 0, \operatorname{div} E = 0, \tau E = 0\} \end{aligned}$$



# Results: Upper Bounds for Non-Conforming Approximations

$\tilde{E} \in L^2(\Omega)$  approximation of  $E \Rightarrow$

Theorem ('11 DP, S.I. Repin)

For all  $\tilde{E} \in L^2(\Omega)$  and all  $D \in \mathcal{H}_D(\Omega)$

$$|E - \tilde{E} - D|_{L^2(\Omega)}^2 \leq \inf_{X \in \mathring{R}(\Omega)} M_{\text{rot}}^2(\tilde{E}; X) + \inf_{Y \in D(\Omega)} M_{\text{div}}^2(\tilde{E}; Y) + |\pi(\tilde{E} - D)|_{\mathbb{R}^d}^2$$

holds. Here,  $\pi : \mathcal{H}_D(\Omega) \rightarrow \mathbb{R}^d$  (e.g. isomorphic) and

$$M_{\text{rot}}(\tilde{E}; X) := c_m |F - \text{rot } X|_{L^2(\Omega)} + |\tilde{E} - X|_{L^2(\Omega)},$$

$$M_{\text{div}}(\tilde{E}; Y) := c_{p,o} |G - \text{div } Y|_{L^2(\Omega)} + |\tilde{E} - Y|_{L^2(\Omega)}.$$

only natural and 'well known' continuity constants involved:

$$c_{p,o} \quad \boxed{\text{Poincaré constant}} \quad \forall u \in \mathring{H}^1(\Omega) \quad |u|_{L^2(\Omega)} \leq c_{p,o} |\nabla u|_{L^2(\Omega)}$$

$$c_m \quad \boxed{\text{Maxwell constant}} \quad \forall E \in \mathbb{H} \quad |E|_{L^2(\Omega)} \leq c_m |\text{rot } E|_{L^2(\Omega)}$$

here  $\mathbb{H} := R(\Omega) \cap \text{rot } \mathring{R}(\Omega) = R(\Omega) \cap \mathring{D}_0(\Omega) \cap \mathcal{H}_N(\Omega)^\perp$

## Proof: Tools

- ① Rellich's selection theorems, i.e.,  $\mathring{H}^1(\Omega), H^1(\Omega) \hookrightarrow L^2(\Omega)$  compact  
 $\Rightarrow$  Poincaré estimates, i.e.,

$$\begin{aligned} \forall u \in \mathring{H}^1(\Omega) & & |u|_{L^2(\Omega)} & \leq c_{p,o} |\nabla u|_{L^2(\Omega)} \\ \forall u \in H^1(\Omega) \cap \mathbb{R}^\perp & & |u|_{L^2(\Omega)} & \leq c_p |\nabla u|_{L^2(\Omega)} \end{aligned}$$

- ② Maxwell selection theorems, i.e.,

$$\mathring{R}(\Omega) \cap D(\Omega), R(\Omega) \cap \mathring{D}(\Omega) \hookrightarrow L^2(\Omega) \text{ compact}$$

$\Rightarrow$  Maxwell estimates, i.e.,

$$\begin{aligned} \forall E \in \mathring{\mathbb{H}} = \mathring{R}(\Omega) \cap D_0(\Omega) \cap \mathcal{H}_D(\Omega)^\perp & & |E|_{L^2(\Omega)} & \leq c_m |\operatorname{rot} E|_{L^2(\Omega)} \\ \forall E \in \mathbb{H} = R(\Omega) \cap \mathring{D}_0(\Omega) \cap \mathcal{H}_N(\Omega)^\perp & & |E|_{L^2(\Omega)} & \leq c_m |\operatorname{rot} E|_{L^2(\Omega)} \end{aligned}$$

- ③ Maxwell selection theorems  $\Rightarrow \dim \mathcal{H}_D(\Omega), \dim \mathcal{H}_N(\Omega) < \infty$  (Betti numbers)  
 ④ Helmholtz decompositions (all 6 images are closed in  $L^2(\Omega)$ )

$$\begin{aligned} L^2(\Omega) &= \nabla \mathring{H}^1(\Omega) \oplus \overbrace{\mathcal{H}_D(\Omega) \oplus \operatorname{rot} R(\Omega)}^{=D_0(\Omega)}, & \operatorname{rot} R(\Omega) &= \operatorname{rot} \mathbb{H} \\ L^2(\Omega) &= \nabla H^1(\Omega) \oplus \overbrace{\mathcal{H}_N(\Omega) \oplus \operatorname{rot} \mathring{R}(\Omega)}^{=\mathring{D}_0(\Omega)}, & \operatorname{rot} \mathring{R}(\Omega) &= \operatorname{rot} \mathring{\mathbb{H}} \end{aligned}$$

## Proof

$$e = E - \tilde{E} \in L^2(\Omega)$$

- Helmholtz decomposition of error  $\Rightarrow$

$$e = e_{\nabla} + e_{\mathcal{H}} + e_{\text{rot}} \in \nabla \mathring{H}^1(\Omega) \oplus \mathcal{H}_D(\Omega) \oplus \text{rot } \mathbb{H}$$

- $e_{\nabla} = \nabla u$  with scalar potential  $u \in \mathring{H}^1(\Omega)$
- $e_{\text{rot}} = \text{rot } U$  with vector potential  $U \in \mathbb{H}$
- $|e|_{L^2(\Omega)}^2 = |e_{\nabla}|_{L^2(\Omega)}^2 + |e_{\mathcal{H}}|_{L^2(\Omega)}^2 + |e_{\text{rot}}|_{L^2(\Omega)}^2$

## Proof...

$$\begin{aligned}
 \textcircled{1} \quad e_{\nabla} &= \nabla u, \quad u \in \mathring{H}^1(\Omega): \quad \forall \varphi \in \mathring{H}^1(\Omega) \quad \forall Y \in D(\Omega) \\
 \langle e_{\nabla}, \nabla \varphi \rangle_{L^2(\Omega)} &= \langle e, \nabla \varphi \rangle_{L^2(\Omega)} = \langle E, \nabla \varphi \rangle_{L^2(\Omega)} - \langle \tilde{E}, \nabla \varphi \rangle_{L^2(\Omega)} \\
 &= \langle \operatorname{div} Y - G, \varphi \rangle_{L^2(\Omega)} + \langle Y - \tilde{E}, \nabla \varphi \rangle_{L^2(\Omega)} \\
 &\leq |\operatorname{div} Y - G|_{L^2(\Omega)} \underbrace{|\varphi|_{L^2(\Omega)}}_{\leq c_{p,o} |\nabla \varphi|_{L^2(\Omega)}} + |Y - \tilde{E}|_{L^2(\Omega)} |\nabla \varphi|_{L^2(\Omega)}
 \end{aligned}$$

$$\varphi := u \quad \Rightarrow \quad |e_{\nabla}|_{L^2(\Omega)} \leq c_{p,o} |\operatorname{div} Y - G|_{L^2(\Omega)} + |Y - \tilde{E}|_{L^2(\Omega)}$$

$$\begin{aligned}
 \textcircled{2} \quad e_{\operatorname{rot}} &= \operatorname{rot} U, \quad U \in \mathbb{H}: \quad \forall \Phi \in \mathbb{H} \quad \forall X \in \mathring{R}(\Omega) \\
 \langle e_{\operatorname{rot}}, \operatorname{rot} \Phi \rangle_{L^2(\Omega)} &= \langle e, \operatorname{rot} \Phi \rangle_{L^2(\Omega)} = \langle E, \operatorname{rot} \Phi \rangle_{L^2(\Omega)} - \langle \tilde{E}, \operatorname{rot} \Phi \rangle_{L^2(\Omega)} \\
 &= \langle F - \operatorname{rot} X, \Phi \rangle_{L^2(\Omega)} + \langle X - \tilde{E}, \operatorname{rot} \Phi \rangle_{L^2(\Omega)} \\
 &\leq |F - \operatorname{rot} X|_{L^2(\Omega)} \underbrace{|\Phi|_{L^2(\Omega)}}_{\leq c_m |\operatorname{rot} \Phi|_{L^2(\Omega)}} + |X - \tilde{E}|_{L^2(\Omega)} |\operatorname{rot} \Phi|_{L^2(\Omega)}
 \end{aligned}$$

$$\Phi := U \quad \Rightarrow \quad |e_{\operatorname{rot}}|_{L^2(\Omega)} \leq c_m |F - \operatorname{rot} X|_{L^2(\Omega)} + |X - \tilde{E}|_{L^2(\Omega)}$$

$$\begin{aligned}
 \textcircled{3} \quad e_{\mathcal{H}} &: \text{ simple algebraic manipulation} \\
 &\Rightarrow |e_{\mathcal{H}}|_{L^2(\Omega)} \leq |\pi(\tilde{E} - D)|_{\mathbb{R}^d}
 \end{aligned}$$



# Maxwell Constants

## Part 2

### The Maxwell Constants in 3D

# Estimates for the Maxwell Constants

open problem: estimates for the Maxwell constants  $c_m$  in 3D or nD?

$$\forall E \in \mathring{R}(\Omega) \cap D(\Omega) \cap \mathcal{H}_D(\Omega)^\perp \quad |E|_{L^2(\Omega)} \leq c_{m,t} (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2)^{1/2}$$

$$\forall E \in R(\Omega) \cap \mathring{D}(\Omega) \cap \mathcal{H}_N(\Omega)^\perp \quad |E|_{L^2(\Omega)} \leq c_{m,n} (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2)^{1/2}$$

question:

$$? \leq c_{m,t}, c_{m,n} \leq ?$$

in 2D well known

$$c_{p,o} \leq c_{m,t}, c_{m,n} \leq c_p$$

with Poincaré constants

$$\forall u \in \mathring{H}^1(\Omega) \quad |u|_{L^2(\Omega)} \leq c_{p,o} |\nabla u|_{L^2(\Omega)}$$

$$\forall u \in H^1(\Omega) \cap \mathbb{R}^\perp \quad |u|_{L^2(\Omega)} \leq c_p |\nabla u|_{L^2(\Omega)}$$

note always

$$c_{p,o} = \frac{1}{\sqrt{\lambda_1}} < \frac{1}{\sqrt{\mu_2}} = c_p$$

# Step 1: Problem Reduction by Helmholtz Decomposition

$$\forall E \in \mathring{R}(\Omega) \cap D(\Omega) \cap \mathcal{H}_D(\Omega)^\perp \quad |E|_{L^2(\Omega)} \leq c_{m,t} (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2)^{1/2}$$

$$\forall E \in R(\Omega) \cap \mathring{D}(\Omega) \cap \mathcal{H}_N(\Omega)^\perp \quad |E|_{L^2(\Omega)} \leq c_{m,n} (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2)^{1/2}$$

Helmholtz decomposition  $\Rightarrow$  splits 2 problems into 4 'nicer' problems

$$\forall E \in D(\Omega) \cap \underbrace{\mathring{R}_0(\Omega) \cap \mathcal{H}_D(\Omega)^\perp}_{=\nabla \mathring{H}^1(\Omega)} \quad |E|_{L^2(\Omega)} \leq c_{m,t,\operatorname{div}} |\operatorname{div} E|_{L^2(\Omega)}$$

$$\forall E \in \mathring{R}(\Omega) \cap \underbrace{D_0(\Omega) \cap \mathcal{H}_D(\Omega)^\perp}_{=\operatorname{rot} R(\Omega)} \quad |E|_{L^2(\Omega)} \leq c_{m,t,\operatorname{rot}} |\operatorname{rot} E|_{L^2(\Omega)}$$

$$\forall E \in \mathring{D}(\Omega) \cap \underbrace{R_0(\Omega) \cap \mathcal{H}_N(\Omega)^\perp}_{=\nabla H^1(\Omega)} \quad |E|_{L^2(\Omega)} \leq c_{m,n,\operatorname{div}} |\operatorname{div} E|_{L^2(\Omega)}$$

$$\forall E \in R(\Omega) \cap \underbrace{\mathring{D}_0(\Omega) \cap \mathcal{H}_N(\Omega)^\perp}_{=\operatorname{rot} \mathring{R}(\Omega)} \quad |E|_{L^2(\Omega)} \leq c_{m,n,\operatorname{rot}} |\operatorname{rot} E|_{L^2(\Omega)}$$

## Step 2: First Results

reminder

$$\forall E \in \mathring{R}(\Omega) \cap D(\Omega) \cap \mathcal{H}_D(\Omega)^\perp \quad |E|_{L^2(\Omega)} \leq c_{m,t} (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2)^{1/2}$$

$$\forall E \in R(\Omega) \cap \mathring{D}(\Omega) \cap \mathcal{H}_N(\Omega)^\perp \quad |E|_{L^2(\Omega)} \leq c_{m,n} (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2)^{1/2}$$

$$\forall E \in D(\Omega) \cap \mathring{\nabla} H^1(\Omega) \quad |E|_{L^2(\Omega)} \leq c_{m,t,\operatorname{div}} |\operatorname{div} E|_{L^2(\Omega)}$$

$$\forall E \in \mathring{R}(\Omega) \cap \operatorname{rot} R(\Omega) \quad |E|_{L^2(\Omega)} \leq c_{m,t,\operatorname{rot}} |\operatorname{rot} E|_{L^2(\Omega)}$$

$$\forall E \in \mathring{D}(\Omega) \cap \mathring{\nabla} H^1(\Omega) \quad |E|_{L^2(\Omega)} \leq c_{m,n,\operatorname{div}} |\operatorname{div} E|_{L^2(\Omega)}$$

$$\forall E \in R(\Omega) \cap \operatorname{rot} \mathring{R}(\Omega) \quad |E|_{L^2(\Omega)} \leq c_{m,n,\operatorname{rot}} |\operatorname{rot} E|_{L^2(\Omega)}$$

trivially:  $c_{m,t,\operatorname{rot}}, c_{m,t,\operatorname{div}} \leq c_{m,t}$  and  $c_{m,n,\operatorname{rot}}, c_{m,n,\operatorname{div}} \leq c_{m,n}$ trivially:  $c_{m,t} \leq \max\{c_{m,t,\operatorname{rot}}, c_{m,t,\operatorname{div}}\}$  and  $c_{m,n} \leq \max\{c_{m,n,\operatorname{rot}}, c_{m,n,\operatorname{div}}\}$  (Helmholtz)trivially:  $c_{m,t} = \max\{c_{m,t,\operatorname{rot}}, c_{m,t,\operatorname{div}}\}$  and  $c_{m,n} = \max\{c_{m,n,\operatorname{rot}}, c_{m,n,\operatorname{div}}\}$ 

## Theorem ('13 DP)

$$c_{m,t,\operatorname{div}} = c_{p,0} \quad c_{m,n,\operatorname{div}} = c_p \quad c_{m,t,\operatorname{rot}} = c_{m,n,\operatorname{rot}}$$

remains to estimate

$$c_{m,\operatorname{rot}} := c_{m,t,\operatorname{rot}} = c_{m,n,\operatorname{rot}}$$



## Step 3: Main Results

$$\forall E \in \mathring{R}(\Omega) \cap D(\Omega) \cap \mathcal{H}_D(\Omega)^\perp \quad |E|_{L^2(\Omega)} \leq c_{m,t} (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2)^{1/2}$$

$$\forall E \in R(\Omega) \cap \mathring{D}(\Omega) \cap \mathcal{H}_N(\Omega)^\perp \quad |E|_{L^2(\Omega)} \leq c_{m,n} (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2)^{1/2}$$

$$\forall E \in D(\Omega) \cap \mathring{\nabla}H^1(\Omega) \quad |E|_{L^2(\Omega)} \leq c_{p,o} |\operatorname{div} E|_{L^2(\Omega)}$$

$$\forall E \in \mathring{R}(\Omega) \cap \operatorname{rot} R(\Omega) \quad |E|_{L^2(\Omega)} \leq c_{m,\operatorname{rot}} |\operatorname{rot} E|_{L^2(\Omega)}$$

$$\forall E \in \mathring{D}(\Omega) \cap \nabla H^1(\Omega) \quad |E|_{L^2(\Omega)} \leq c_p |\operatorname{div} E|_{L^2(\Omega)}$$

$$\forall E \in R(\Omega) \cap \operatorname{rot} \mathring{R}(\Omega) \quad |E|_{L^2(\Omega)} \leq c_{m,\operatorname{rot}} |\operatorname{rot} E|_{L^2(\Omega)}$$

trivially:  $c_{m,t} = \max\{c_{m,\operatorname{rot}}, c_{p,o}\}$  and  $c_{m,n} = \max\{c_{m,\operatorname{rot}}, c_p\}$   
 remains to estimate  $c_{m,\operatorname{rot}}$

## Theorem ('13 DP)

Let  $\Omega$  be bounded and convex. Then  $c_{m,\operatorname{rot}} \leq c_p$ . Moreover,  $c_{p,o} \leq c_{m,t} \leq c_{m,n} = c_p$ .

equivalent formulation for eigenvalues

# Proof of First Theorem

Proof ... by some functional analysis ...

$A : D(A) \subset H_1 \rightarrow H_2$  lin., dens. def., closed with adjoint  $A^* : D(A^*) \subset H_2 \rightarrow H_1$

assume  $D(A) \cap \overline{R(A^*)} \hookrightarrow H_1$  compact!

define  $M := \begin{bmatrix} 0 & A^* \\ A & 0 \end{bmatrix}$  and note  $M^2 := \begin{bmatrix} A^*A & 0 \\ 0 & AA^* \end{bmatrix}$

$\Rightarrow M, M^2, A^*A, AA^*$  self-adjoint with pure point spectra and

$$\sigma_p(M) = \pm \sqrt{\sigma_p(A^*A)} = \pm \sqrt{\sigma_p(AA^*)} = \pm \{\kappa_1, \kappa_2, \dots\}, \quad 0 \leq \kappa_n \nearrow \infty$$

looking at first resp. second eigenvalues  $\Rightarrow$

$$\inf_{0 \neq u \in D(A) \cap R(A^*)} \frac{|Au|_{H_2}^2}{|u|_{H_1}^2} = \inf_{0 \neq v \in D(A^*) \cap R(A)} \frac{|A^*v|_{H_1}^2}{|v|_{H_2}^2}$$

# Proof of First Theorem...

$A : D(A) \subset H_1 \rightarrow H_2$  lin., dens. def., cl., adjoint  $A^* : D(A^*) \subset H_2 \rightarrow H_1$   
 $D(A) \cap R(A^*) \hookrightarrow H_1$  cpt (note  $R(A^*) = N(A)^\perp$  and  $R(A^*)$  cl.)

$$\inf_{0 \neq u \in D(A) \cap R(A^*)} \frac{|Au|_{H_2}^2}{|u|_{H_1}^2} = \inf_{0 \neq v \in D(A^*) \cap R(A)} \frac{|A^*v|_{H_1}^2}{|v|_{H_2}^2}$$

especially

$A := \mathring{\nabla} : \mathring{H}^1(\Omega) \subset L^2(\Omega) \rightarrow L^2(\Omega)$ ,  $A^* := -\operatorname{div} : D(\Omega) \subset L^2(\Omega) \rightarrow L^2(\Omega)$

$R(A^*) = N(A)^\perp = \{0\}^\perp = L^2(\Omega)$

$\mathring{H}^1(\Omega) \cap L^2(\Omega) = \mathring{H}^1(\Omega) \hookrightarrow L^2(\Omega)$  cpt by Rellich's selection theorem

$$\frac{1}{C_{P,0}^2} = \lambda_1 = \inf_{0 \neq u \in \mathring{H}^1(\Omega)} \frac{|\nabla u|_{L^2(\Omega)}^2}{|u|_{L^2(\Omega)}^2} = \inf_{0 \neq E \in D(\Omega) \cap \mathring{\nabla} \mathring{H}^1(\Omega)} \frac{|\operatorname{div} E|_{L^2(\Omega)}^2}{|E|_{L^2(\Omega)}^2} = \frac{1}{C_{m,t,\operatorname{div}}^2}$$

# Proof of First Theorem.....

$A : D(A) \subset H_1 \rightarrow H_2$  lin., dens. def., cl., adjoint  $A^* : D(A^*) \subset H_2 \rightarrow H_1$   
 $D(A) \cap R(A^*) \hookrightarrow H_1$  cpt (note  $R(A^*) = N(A)^\perp$  and  $R(A^*)$  cl.)

$$\inf_{0 \neq u \in D(A) \cap R(A^*)} \frac{|Au|_{H_2}^2}{|u|_{H_1}^2} = \inf_{0 \neq v \in D(A^*) \cap R(A)} \frac{|A^*v|_{H_1}^2}{|v|_{H_2}^2}$$

especially

$A := \nabla : H^1(\Omega) \subset L^2(\Omega) \rightarrow L^2(\Omega)$ ,  $A^* := -\operatorname{div} : \mathring{D}(\Omega) \subset L^2(\Omega) \rightarrow L^2(\Omega)$

$R(A^*) = N(A)^\perp = \mathbb{R}^\perp$

$H^1(\Omega) \cap \mathbb{R}^\perp \subset H^1(\Omega) \hookrightarrow L^2(\Omega)$  cpt by Rellich's selection theorem

$$\frac{1}{c_p^2} = \mu_2 = \inf_{0 \neq u \in H^1(\Omega) \cap \mathbb{R}^\perp} \frac{|\nabla u|_{L^2(\Omega)}^2}{|u|_{L^2(\Omega)}^2} = \inf_{0 \neq E \in \mathring{D}(\Omega) \cap \nabla H^1(\Omega)} \frac{|\operatorname{div} E|_{L^2(\Omega)}^2}{|E|_{L^2(\Omega)}^2} = \frac{1}{c_{m,n,\operatorname{div}}^2}$$

## Proof of First Theorem.....

$A : D(A) \subset H_1 \rightarrow H_2$  lin., dens. def., cl., adjoint  $A^* : D(A^*) \subset H_2 \rightarrow H_1$   
 $D(A) \cap R(A^*) \hookrightarrow H_1$  cpt (note  $R(A^*) = N(A)^\perp$  and  $R(A^*)$  cl.)

$$\inf_{0 \neq u \in D(A) \cap R(A^*)} \frac{|Au|_{H_2}^2}{|u|_{H_1}^2} = \inf_{0 \neq v \in D(A^*) \cap R(A)} \frac{|A^*v|_{H_1}^2}{|v|_{H_2}^2}$$

especially

$A := \text{rot} : \mathring{R}(\Omega) \subset L^2(\Omega) \rightarrow L^2(\Omega)$ ,  $A^* := \text{rot} : R(\Omega) \subset L^2(\Omega) \rightarrow L^2(\Omega)$

$R(A^*) = \text{rot} R(\Omega)$

$\mathring{R}(\Omega) \cap \text{rot} R(\Omega) \subset \mathring{R}(\Omega) \cap D(\Omega) \hookrightarrow L^2(\Omega)$  cpt by MCP

$$\frac{1}{\mathcal{C}_{m,t,\text{rot}}^2} = \kappa_2 = \inf_{0 \neq E \in \mathring{R}(\Omega) \cap \text{rot} R(\Omega)} \frac{|\text{rot} E|_{L^2(\Omega)}^2}{|E|_{L^2(\Omega)}^2} = \inf_{0 \neq E \in R(\Omega) \cap \text{rot} \mathring{R}(\Omega)} \frac{|\text{rot} E|_{L^2(\Omega)}^2}{|E|_{L^2(\Omega)}^2} = \frac{1}{\mathcal{C}_{m,n,\text{rot}}^2}$$

□

# Proof of Second (Main) Theorem

## Proof

crucial estimate for convex domains

Lemma ('98 C. Amrouche, C. Bernardi, M. Dauge, V. Girault)

$\Omega \subset \mathbb{R}^3$  *bd and convex*. Then  $E \in \mathring{R}(\Omega) \cap D(\Omega), R(\Omega) \cap \mathring{D}(\Omega) \subset H^1(\Omega)$  *continuous and*

$$|\nabla E|_{L^2(\Omega)}^2 \leq 1 \cdot (|\operatorname{rot} E|_{L^2(\Omega)}^2 + |\operatorname{div} E|_{L^2(\Omega)}^2).$$

related, earlier, partial results by M. Costabel ('91), J. Saranen ('82), P. Grisvard ('72, '85), R. Leis ('68), J. Kadlec ('64)

$\Rightarrow$  pick  $E \in R(\Omega) \cap \operatorname{rot} \mathring{R}(\Omega) = R(\Omega) \cap \mathring{D}_0(\Omega) \cap \mathcal{H}_N(\Omega)^\perp = R(\Omega) \cap \mathring{D}_0(\Omega)$  ( $\Omega$  convex)

$\Rightarrow \langle E, a \rangle_{L^2(\Omega)} = \langle \operatorname{rot} H, a \rangle_{L^2(\Omega)} = 0$  for all  $a \in \mathbb{R}^3$  since  $H \in \mathring{R}(\Omega)$

$\Rightarrow E \in H^1(\Omega) \cap (\mathbb{R}^3)^\perp$

$\Rightarrow |E|_{L^2(\Omega)} \stackrel{\text{Poincare}}{\leq} c_p |\nabla E|_{L^2(\Omega)} \stackrel{\text{Lemma}}{\leq} 1 \cdot c_p |\operatorname{rot} E|_{L^2(\Omega)}$

$\Rightarrow c_{m,\operatorname{rot}} \leq c_p$

very simple!  $\square$

# Last Slide!

## Blagodarya / Thank You

more results:

### Functional A Posteriori Error Estimates:

- lower bounds
- usual features of Sergey's estimates:  
sharpness, only natural constants, simple implementation, ...
- $\Omega$  exterior domain, polynomially weighted estimates
- differential forms,  $\Omega \subset \mathbb{R}^N$ ,  $\Omega$  Riemannian manifold
- hyperbolic problems, full time-dependent Maxwell system, eddy current, ...
- with  $\varepsilon$ ,  $\mu$  and inhomogeneous bc
- diffusion problem, elasticity, ...
- magnetic problem!!!!
- mixed boundary conditions

### Maxwell Constants:

- also with  $\varepsilon$ ,  $\mu$
- also  $\Omega \subset \mathbb{R}^N$  with differential forms
- also on non-convex polygons (not too pointy)