

Maxwell meets Korn: A new coercive inequality for tensor fields in $\mathbb{R}^{N \times N}$ with square-integrable exterior derivative

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For a bounded domain $\Omega \subset \mathbb{R}^N$ with connected Lipschitz boundary, we prove the existence of some $c > 0$, such that

$$c \|T\|_{L^2(\Omega, \mathbb{R}^{N \times N})} \leq \|\text{sym } T\|_{L^2(\Omega, \mathbb{R}^{N \times N})} + \|\text{Curl } T\|_{L^2(\Omega, \mathbb{R}^{N \times (N-1)N/2})}$$

holds for all square-integrable tensor fields $T : \Omega \rightarrow \mathbb{R}^{N \times N}$, having square-integrable generalized “rotation” tensor fields $\text{Curl } T : \Omega \rightarrow \mathbb{R}^{N \times (N-1)N/2}$ and vanishing tangential trace on $\partial\Omega$, where both operations are to be understood row-wise. Here, in each row, the operator curl is the vector analytical reincarnation of the exterior derivative d in \mathbb{R}^N . For compatible tensor fields T , that is, $T = \nabla v$, the latter estimate reduces to a non-standard variant of Korn’s first inequality in \mathbb{R}^N , namely

$$c \|\nabla v\|_{L^2(\Omega, \mathbb{R}^{N \times N})} \leq \|\text{sym } \nabla v\|_{L^2(\Omega, \mathbb{R}^{N \times N})}$$

for all vector fields $v \in H^1(\Omega, \mathbb{R}^N)$, for which $\nabla v_n, n = 1, \dots, N$, are normal at $\partial\Omega$. Copyright © 2012 John Wiley & Sons, Ltd.

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1. Introduction and preliminaries

We extend the results from [1, 2], which have been announced in [3], to the N -dimensional case following in close lines, the arguments presented there. Let $N \in \mathbb{N}$ and Ω be a bounded domain in \mathbb{R}^N with connected Lipschitz boundary $\Gamma := \partial\Omega$. We prove a Korn-type inequality in $\mathring{H}(\text{Curl}; \Omega)$ for eventually non-symmetric tensor fields T mapping Ω to $\mathbb{R}^{N \times N}$. More precisely, there exists a positive constant c , such that

$$c \|T\|_{L^2(\Omega)} \leq \|\text{sym } T\|_{L^2(\Omega)} + \|\text{Curl } T\|_{L^2(\Omega)}$$

holds for all tensor fields $T \in \mathring{H}(\text{Curl}; \Omega)$, where T belongs to $\mathring{H}(\text{Curl}; \Omega)$, if $T \in H(\text{Curl}; \Omega)$ has vanishing tangential trace on Γ . Thereby, the generalized Curl and tangential trace are defined as row-wise operations. For compatible tensor fields $T = \nabla v$ with vector fields $v \in H^1(\Omega)$, for which $\nabla v_n, n = 1, \dots, N$, are normal at $\partial\Omega$, the latter estimate reduces to a non-standard variant of the well known Korn’s first inequality in \mathbb{R}^N

$$c \|\nabla v\|_{L^2(\Omega)} \leq \|\text{sym } \nabla v\|_{L^2(\Omega)}.$$

Our proof relies on three essential tools, namely

1. Maxwell estimate (Poincaré-type estimate),
2. Helmholtz’ decomposition,
3. Korn’s first inequality.

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In [1], we already pointed out the importance of the Maxwell estimate and the related question of the Maxwell compactness property[‡]. Here, we mention the papers [4–10]. Results for the Helmholtz decomposition can be found in [6, 8, 10–16]. Nowadays, differential forms find prominent applications in numerical methods like Finite Element Exterior Calculus [17, 18] or Discrete Exterior Calculus [19].

1.1. Differential forms

We may look at Ω as a smooth Riemannian manifold of dimension N with compact closure and connected Lipschitz continuous boundary Γ . The alternating differential forms of rank $q \in \{0, \dots, N\}$ on Ω , briefly q -forms, with square-integrable coefficients will be denoted by $L^{2,q}(\Omega)$. The exterior derivative d and the co-derivative $\delta = \pm * d *$ ($*$: Hodge's star operator) are formally skew-adjoint to each other, that is,

$$\forall E \in \mathring{C}^{\infty,q}(\Omega) \quad H \in \mathring{C}^{\infty,q+1}(\Omega) \quad \langle dE, H \rangle_{L^{2,q+1}(\Omega)} = - \langle E, \delta H \rangle_{L^{2,q}(\Omega)},$$

where the $L^{2,q}(\Omega)$ -scalar product is given by

$$\forall E, H \in L^{2,q}(\Omega) \quad \langle E, H \rangle_{L^{2,q}(\Omega)} := \int_{\Omega} E \wedge *H.$$

Here, $\mathring{C}^{\infty,q}(\Omega)$ denotes the space of compactly supported and smooth q -forms on Ω . Using this duality, we can define weak versions of d and δ . The corresponding standard Sobolev spaces are denoted by

$$\begin{aligned} D^q(\Omega) &:= \{E \in L^{2,q}(\Omega) : dE \in L^{2,q+1}(\Omega)\}, \\ \Delta^q(\Omega) &:= \{H \in L^{2,q}(\Omega) : \delta H \in L^{2,q-1}(\Omega)\}. \end{aligned}$$

The homogeneous tangential boundary condition $\tau_{\Gamma} E = 0$, where τ_{Γ} denotes the tangential trace, is generalized in the space

$$\mathring{D}^q(\Omega) := \overline{\mathring{C}^{\infty,q}(\Omega)},$$

where the closure is taken in $D^q(\Omega)$. In classical terms, we have for smooth q -forms $\tau_{\Gamma} = \iota^*$ with the canonical embedding $\iota : \Gamma \hookrightarrow \overline{\Omega}$. An index 0 at the lower right position indicates vanishing derivatives, that is,

$$\mathring{D}_0^q(\Omega) = \{E \in \mathring{D}^q(\Omega) : dE = 0\}, \quad \Delta_0^q(\Omega) = \{H \in \Delta^q(\Omega) : \delta H = 0\}.$$

By definition and density, we have

$$\Delta_0^q(\Omega) = (d\mathring{D}^{q-1}(\Omega))^{\perp}, \quad \Delta_0^q(\Omega)^{\perp} = \overline{d\mathring{D}^{q-1}(\Omega)},$$

where \perp denotes the orthogonal complement with respect to the $L^{2,q}(\Omega)$ -scalar product and the closure is taken in $L^{2,q}(\Omega)$. Hence, we obtain the $L^{2,q}(\Omega)$ -orthogonal decomposition, usually called Hodge–Helmholtz decomposition,

$$L^{2,q}(\Omega) = \overline{d\mathring{D}^{q-1}(\Omega)} \oplus \Delta_0^q(\Omega), \tag{1.1}$$

where \oplus denotes the orthogonal sum with respect to the $L^{2,q}(\Omega)$ -scalar product. In [7, 10], the following crucial tool has been proved:

Lemma 1 (Maxwell compactness property)

For all q the embeddings

$$\mathring{D}^q(\Omega) \cap \Delta^q(\Omega) \hookrightarrow L^{2,q}(\Omega)$$

are compact.

As the first immediate consequence, the spaces of so called "harmonic Dirichlet forms"

$$\mathcal{H}^q(\Omega) := \mathring{D}_0^q(\Omega) \cap \Delta_0^q(\Omega)$$

are finite dimensional. In classical terms, a q -form E belongs to $\mathcal{H}^q(\Omega)$, if

$$dE = 0, \quad \delta E = 0, \quad \iota^* E = 0.$$

[‡]By "Maxwell estimate" and "Maxwell compactness property", we mean the estimates and compact embedding results used in the theory of Maxwell's equations.

The dimension of $\mathcal{H}^q(\Omega)$ equals the $(N - q)$ th Betti number of Ω . Because we assume the boundary Γ to be connected, the $(N - 1)$ th Betti number of Ω vanishes and therefore there are no Dirichlet forms of rank 1 besides zero, for example,

$$\mathcal{H}^1(\Omega) = \{0\}. \tag{1.2}$$

This condition on the domain Ω respectively its boundary Γ is satisfied, for example, for a ball or a torus.

By a usual indirect argument, we achieve another immediate consequence:

Lemma 2 (Poincaré estimate for differential forms)

For all q there exist positive constants $c_{p,q}$, such that for all $E \in \mathring{D}^q(\Omega) \cap \Delta^q(\Omega) \cap \mathcal{H}^q(\Omega)^\perp$

$$\|E\|_{L^{2,q}(\Omega)} \leq c_{p,q} \left(\|dE\|_{L^{2,q+1}(\Omega)}^2 + \|\delta E\|_{L^{2,q-1}(\Omega)}^2 \right)^{1/2}.$$

Because

$$d\mathring{D}^{q-1}(\Omega) \subset \mathring{D}_0^q(\Omega)$$

(note that $dd = 0$ and $\delta\delta = 0$ hold even in the weak sense) we get by (1.1)

$$d\mathring{D}^{q-1}(\Omega) = d\left(\mathring{D}^{q-1}(\Omega) \cap \Delta_0^{q-1}(\Omega)\right) = d\left(\mathring{D}^{q-1}(\Omega) \cap \Delta_0^{q-1}(\Omega) \cap \mathcal{H}^{q-1}(\Omega)^\perp\right).$$

Now, Lemma 2 shows that $d\mathring{D}^{q-1}(\Omega)$ is already closed. Hence, we obtain a refinement of (1.1)

Lemma 3 (Hodge–Helmholtz decomposition for differential forms)

The decomposition

$$L^{2,q}(\Omega) = d\mathring{D}^{q-1}(\Omega) \oplus \Delta_0^q(\Omega)$$

holds.

1.2. Functions and vector fields

Let us turn to the special case $q = 1$. In this case, we choose, for example, the identity as single global chart for Ω and use the canonical identification isomorphism for 1-forms (i.e., Riesz' representation theorem) with vector fields $dx_n \cong e^n$, namely,

$$\sum_{n=1}^N v_n(x) dx_n \cong v(x) = \begin{bmatrix} v_1(x) \\ \vdots \\ v_N(x) \end{bmatrix}, \quad x \in \Omega.$$

0-forms will be isomorphically identified with functions on Ω . Then, $d \cong \text{grad} = \nabla$ for 0-forms (functions) and $\delta \cong \text{div} = \nabla \cdot$ for 1-forms (vector fields). Hence, the well known first order differential operators from vector analysis occur. Moreover, on 1-forms, we define a new operator $\text{curl} : \cong d$, which turns into the usual curl if $N = 3$ or $N = 2$. $L^{2,q}(\Omega)$ equals the usual Lebesgue spaces of square integrable functions or vector fields on Ω with values in \mathbb{R}^n , $n := n_{N,q} := \binom{N}{q}$, which will be denoted by $L^2(\Omega) := L^2(\Omega, \mathbb{R}^n)$. $D^0(\Omega)$ and $\Delta^1(\Omega)$ are identified with the standard Sobolev spaces

$$H(\text{grad}; \Omega) := \left\{ u \in L^2(\Omega, \mathbb{R}) : \text{grad } u \in L^2(\Omega, \mathbb{R}^N) \right\} = H^1(\Omega),$$

$$H(\text{div}; \Omega) := \left\{ v \in L^2(\Omega, \mathbb{R}^N) : \text{div } v \in L^2(\Omega, \mathbb{R}) \right\},$$

respectively. Moreover, we may now identify $D^1(\Omega)$ with

$$H(\text{curl}; \Omega) := \left\{ v \in L^2(\Omega, \mathbb{R}^N) : \text{curl } v \in L^2(\Omega, \mathbb{R}^{(N-1)N/2}) \right\},$$

which is the well-known $H(\text{curl}; \Omega)$ for $N = 2, 3$. For example, for $N = 4$ we have

$$\text{curl } v = \begin{bmatrix} \partial_1 v_2 - \partial_2 v_1 \\ \partial_1 v_3 - \partial_3 v_1 \\ \partial_1 v_4 - \partial_4 v_1 \\ \partial_2 v_3 - \partial_3 v_2 \\ \partial_2 v_4 - \partial_4 v_2 \\ \partial_3 v_4 - \partial_4 v_3 \end{bmatrix} \in \mathbb{R}^6$$

and for $N = 5$, we get $\text{curl } v \in \mathbb{R}^{10}$. In general, the entries of the $(N - 1)N/2$ -vector $\text{curl } v$ consist of all possible combinations of

$$\partial_h v_m - \partial_m v_h, \quad 1 \leq h < m \leq N.$$

Similarly, we obtain the closed subspaces

$$\mathring{H}(\text{grad}; \Omega) = \mathring{H}^1(\Omega), \quad \mathring{H}(\text{curl}; \Omega)$$

as reincarnations of $\mathring{D}^0(\Omega)$ and $\mathring{D}^1(\Omega)$, respectively. We note

$$\mathring{H}(\text{grad}; \Omega) = \overline{\mathring{C}^\infty(\Omega)}, \quad \mathring{H}(\text{curl}; \Omega) = \overline{\mathring{C}^\infty(\Omega)},$$

where the closures are taken in the respective graph norms, and that in these Sobolev spaces the classical homogeneous scalar and tangential (compare with $N = 3$) boundary conditions

$$u|_\Gamma = 0, \quad v \times \nu|_\Gamma = 0$$

are generalized. Here, ν denotes the outward unit normal for Γ . Furthermore, we have the spaces of irrotational or solenoidal vector fields

$$H(\text{curl}_0; \Omega) = \{v \in H(\text{curl}; \Omega) : \text{curl } v = 0\},$$

$$\mathring{H}(\text{curl}_0; \Omega) = \{v \in \mathring{H}(\text{curl}; \Omega) : \text{curl } v = 0\},$$

$$H(\text{div}_0; \Omega) = \{v \in H(\text{div}; \Omega) : \text{div } v = 0\}.$$

Again, all these spaces are Hilbert spaces. Now, we have two compact embeddings

$$\mathring{H}(\text{grad}; \Omega) \hookrightarrow L^2(\Omega), \quad \mathring{H}(\text{curl}; \Omega) \cap H(\text{div}; \Omega) \hookrightarrow L^2(\Omega),$$

that is, Rellich's selection theorem and the Maxwell compactness property. Moreover, the following Poincaré and Maxwell estimates hold:

Corollary 4 (Poincaré estimate for functions)

Let $c_p := c_{p,0}$. Then, for all functions $u \in \mathring{H}(\text{grad}; \Omega)$

$$\|u\|_{L^2(\Omega)} \leq c_p \|\text{grad } u\|_{L^2(\Omega)}.$$

Corollary 5 (Maxwell estimate for vector fields)

Let $c_m := c_{p,1}$. Then, for all vector fields $v \in \mathring{H}(\text{curl}; \Omega) \cap H(\text{div}; \Omega)$

$$\|v\|_{L^2(\Omega)} \leq c_m \left(\|\text{curl } v\|_{L^2(\Omega)}^2 + \|\text{div } v\|_{L^2(\Omega)}^2 \right)^{1/2}.$$

We note that generally $\mathcal{H}^0(\Omega) = \{0\}$ and by (1.2) also $\mathcal{H}^1(\Omega) = \{0\}$. The appropriate Helmholtz decomposition for our needs is

Corollary 6 (Helmholtz decomposition for vector fields)

$$L^2(\Omega) = \text{grad } \mathring{H}(\text{grad}; \Omega) \oplus H(\text{div}_0; \Omega)$$

1.3. Tensor fields

We extend our calculus to $(N \times N)$ -tensor (matrix) fields. For vector fields v with components in $H(\text{grad}; \Omega)$ and tensor fields T with rows in $H(\text{curl}; \Omega)$ resp. $H(\text{div}; \Omega)$, that is,

$$v = \begin{bmatrix} v_1 \\ \vdots \\ v_N \end{bmatrix}, \quad v_n \in H(\text{grad}; \Omega), \quad T = \begin{bmatrix} T_1^t \\ \vdots \\ T_N^t \end{bmatrix}, \quad T_n \in H(\text{curl}; \Omega) \text{ resp. } H(\text{div}; \Omega)$$

for $n = 1, \dots, N$, we define

$$\text{Grad } v := \begin{bmatrix} \text{grad}^t v_1 \\ \vdots \\ \text{grad}^t v_N \end{bmatrix} = J_v = \nabla v, \quad \text{Curl } T := \begin{bmatrix} \text{curl}^t T_1 \\ \vdots \\ \text{curl}^t T_N \end{bmatrix}, \quad \text{Div } T := \begin{bmatrix} \text{div } T_1 \\ \vdots \\ \text{div } T_N \end{bmatrix},$$

where J_v denotes the Jacobian of v and t the transpose. We note that v and $\text{Div } T$ are N -vector fields, T and $\text{Grad } v$ are $(N \times N)$ -tensor fields, whereas $\text{Curl } T$ is a $(N \times (N - 1)N/2)$ -tensor field that may also be viewed as a totally anti-symmetric third order tensor field with entries

$$(\text{Curl } T)_{ijk} = \partial_j T_{ik} - \partial_k T_{ij}.$$

The corresponding Sobolev spaces will be denoted by

$$\begin{array}{cccc} H(\text{Grad}; \Omega), & \mathring{H}(\text{Grad}; \Omega), & H(\text{Div}; \Omega), & H(\text{Div}_0; \Omega), \\ H(\text{Curl}; \Omega), & \mathring{H}(\text{Curl}; \Omega), & H(\text{Curl}_0; \Omega), & \mathring{H}(\text{Curl}_0; \Omega). \end{array}$$

There are three crucial tools to prove our estimate. First, we have obvious consequences from Corollaries 4, 5, and 6:

Corollary 7 (Poincaré estimate for vector fields)

For all $v \in \mathring{H}(\text{Grad}; \Omega)$

$$\|v\|_{L^2(\Omega)} \leq c_p \|\text{Grad } v\|_{L^2(\Omega)}.$$

Corollary 8 (Maxwell estimate for tensor fields)

The estimate

$$\|T\|_{L^2(\Omega)} \leq c_m \left(\|\text{Curl } T\|_{L^2(\Omega)}^2 + \|\text{Div } T\|_{L^2(\Omega)}^2 \right)^{1/2}$$

holds for all tensor fields $T \in \mathring{H}(\text{Curl}; \Omega) \cap H(\text{Div}; \Omega)$.

Corollary 9 (Helmholtz decomposition for tensor fields)

$$L^2(\Omega) = \text{Grad } \mathring{H}(\text{Grad}; \Omega) \oplus H(\text{Div}_0; \Omega)$$

The last important tool is Korn's first inequality.

Lemma 10 (Korn's first inequality)

For all vector fields $v \in \mathring{H}(\text{Grad}; \Omega)$

$$\|\text{Grad } v\|_{L^2(\Omega)} \leq \sqrt{2} \|\text{sym Grad } v\|_{L^2(\Omega)}.$$

Here, we introduce the symmetric and skew-symmetric parts

$$\text{sym } T := \frac{1}{2}(T + T^t), \quad \text{skew } T := \frac{1}{2}(T - T^t)$$

of a $(N \times N)$ -tensor $T = \text{sym } T + \text{skew } T$.

Remark 11

We note that the proof including the value of the constant is simple. By density, we may assume $v \in \mathring{C}^\infty(\Omega)$. Twofold partial integration yields

$$\langle \partial_n v_m, \partial_m v_n \rangle_{L^2(\Omega)} = \langle \partial_m v_m, \partial_n v_n \rangle_{L^2(\Omega)}$$

and hence

$$\begin{aligned} 2 \|\text{sym Grad } v\|_{L^2(\Omega)}^2 &= \frac{1}{2} \sum_{n,m=1}^N \|\partial_n v_m + \partial_m v_n\|_{L^2(\Omega)}^2 = \sum_{n,m=1}^N \left(\|\partial_n v_m\|_{L^2(\Omega)}^2 + \langle \partial_n v_m, \partial_m v_n \rangle_{L^2(\Omega)} \right) \\ &= \|\text{Grad } v\|_{L^2(\Omega)}^2 + \|\text{div } v\|_{L^2(\Omega)}^2 \geq \|\text{Grad } v\|_{L^2(\Omega)}^2. \end{aligned}$$

More on Korn's first inequality can be found, for example, in [20].

2. Results

For tensor fields $T \in H(\text{Curl}; \Omega)$, we define the semi-norm

$$\|T\| := \left(\|\text{sym } T\|_{L^2(\Omega)}^2 + \|\text{Curl } T\|_{L^2(\Omega)}^2 \right)^{1/2}.$$

The main step is to prove the following.

Lemma 12

Let $\hat{c} := \max \{2, \sqrt{5}c_m\}$. Then, for all $T \in \mathring{H}(\text{Curl}; \Omega)$

$$\|T\|_{L^2(\Omega)} \leq \hat{c} \|T\|.$$

Proof

Let $T \in \mathring{H}(\text{Curl}; \Omega)$. According to Corollary 9, we orthogonally decompose

$$T = \text{Grad } v + S \in \text{Grad } \mathring{H}(\text{Grad}; \Omega) \oplus \text{H}(\text{Div}_0; \Omega).$$

Then, $\text{Curl } T = \text{Curl } S$ and we observe $S \in \mathring{H}(\text{Curl}; \Omega) \cap \text{H}(\text{Div}_0; \Omega)$ because

$$\text{Grad } \mathring{H}(\text{Grad}; \Omega) \subset \mathring{H}(\text{Curl}_0; \Omega). \quad (2.1)$$

By Corollary 8, we have

$$\|S\|_{L^2(\Omega)} \leq c_m \|\text{Curl } T\|_{L^2(\Omega)}. \quad (2.2)$$

Then, by Lemma 10 and (2.2), we obtain

$$\|T\|_{L^2(\Omega)}^2 = \|\text{Grad } v\|_{L^2(\Omega)}^2 + \|S\|_{L^2(\Omega)}^2 \leq 2 \|\text{sym Grad } v\|_{L^2(\Omega)}^2 + \|S\|_{L^2(\Omega)}^2 \leq 4 \|\text{sym } T\|_{L^2(\Omega)}^2 + 5 \|S\|_{L^2(\Omega)}^2,$$

which completes the proof. \square

The immediate consequence is our main result.

Theorem 13

On $\mathring{H}(\text{Curl}; \Omega)$ the norms $\|\cdot\|_{\text{H}(\text{Curl}; \Omega)}$ and $\|\cdot\|$ are equivalent. In particular, $\|\cdot\|$ is a norm on $\mathring{H}(\text{Curl}; \Omega)$ and there exists a positive constant c , such that

$$c \|T\|_{\text{H}(\text{Curl}; \Omega)}^2 \leq \|T\|^2 = \|\text{sym } T\|_{L^2(\Omega)}^2 + \|\text{Curl } T\|_{L^2(\Omega)}^2$$

holds for all $T \in \mathring{H}(\text{Curl}; \Omega)$.

Remark 14

For a skew-symmetric tensor field $T : \Omega \rightarrow \mathfrak{so}(N)$, our estimate reduces to a Poincaré inequality in disguise, because $\text{Curl } T$ controls all partial derivatives of T (compare with [21]) and the homogeneous tangential boundary condition for T is implied by $T|_{\Gamma} = 0$.

Setting $T := \text{Grad } v$, we obtain the following.

Remark 15 (Korn's first inequality: tangential-variant)

For all $v \in \mathring{H}(\text{Grad}; \Omega)$

$$\|\text{Grad } v\|_{L^2(\Omega)} \leq \hat{c} \|\text{sym Grad } v\|_{L^2(\Omega)} \quad (2.3)$$

holds by Lemma 12 and (2.1). This is just Korn's first inequality from Lemma 10 with a larger constant \hat{c} . Because Γ is connected, that is, $\mathcal{H}^1(\Omega) = \{0\}$, we even have

$$\text{Grad } \mathring{H}(\text{Grad}; \Omega) = \mathring{H}(\text{Curl}_0; \Omega).$$

Thus, (2.3) holds for all $v \in \text{H}(\text{Grad}; \Omega)$ with $\text{Grad } v \in \mathring{H}(\text{Curl}_0; \Omega)$, that is, with $\text{grad } v_n$, $n = 1, \dots, N$, normal at Γ , which then extends Lemma 10 through the (apparently) weaker boundary condition.

The elementary arguments above apply certainly to much more general situations, for example, to not necessarily connected boundaries Γ and to tangential boundary conditions that are imposed only on parts of Γ . These discussions are left to forthcoming papers.

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