

Space-Time Variational Formulations for Maxwell's Equations

Julia I.M. Hauser, Olaf Steinbach

Institute for Applied Mathematics

Content

1. Introduction and Definitions
2. Space-Time Variational Formulation
 - The ODE corresponding to Maxwell's Equations
 - Dependencies in the Right Hand Side
3. Generalization for the Variational Formulation
4. Numerical Example

Content

1. Introduction and Definitions
2. Space-Time Variational Formulation
 - The ODE corresponding to Maxwell's Equations
 - Dependencies in the Right Hand Side
3. Generalization for the Variational Formulation
4. Numerical Example

The Differential Equations

Let $\Omega \subset \mathbb{R}^d$, $d = 2, 3$, be a bounded Lipschitz domain, $T > 0$ and $Q := \Omega \times (0, T)$. Let $\epsilon, \mu \in [L^\infty(\Omega)]^3$ be symmetric and positive definite. Consider

$$\begin{aligned}
 \epsilon \partial_{tt} E + \nabla \times (\mu^{-1} \nabla \times E) &= -\partial_t J && \text{in } Q, \\
 n \times E &= 0 && \text{on } \Sigma, \\
 \epsilon \partial_t E(0, x) &= -J(0, x) + \nabla \times H_0(x) && \text{for } x \in \Omega, \\
 E(0, x) &= E_0(x) && \text{for } x \in \Omega.
 \end{aligned}$$

Sobolev Spaces

We define

$$H_{0;}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H^1(0, T; [L^2(\Omega)]^3),$$

$$H_{0;,0}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H_{;,0}^1(0, T; [L^2(\Omega)]^3).$$

Sobolev Spaces - Properties

One can show that the embedding

$$H^1(0, T; [L^2(\Omega)]^3) \subset C([0, T], [L^2(\Omega)]^3)$$

is continuous, see e.g. [Zeidler, 1990].

Sobolev Spaces - Properties

One can show that the embedding

$$H^1(0, T; [L^2(\Omega)]^3) \subset C([0, T], [L^2(\Omega)]^3)$$

is continuous, see e.g. [Zeidler, 1990].

The space

$$C^\infty(0, T) \hat{\otimes} [C^\infty(\bar{\Omega})]^3$$

is dense in

$$H^1(0, T) \hat{\otimes} [L^2(\Omega)]^3 \quad \text{and} \quad L^2(0, T) \hat{\otimes} H(\text{curl}; \Omega)$$

Sobolev Spaces - Properties

One can show that the embedding

$$H^1(0, T; [L^2(\Omega)]^3) \subset C([0, T], [L^2(\Omega)]^3)$$

is continuous, see e.g. [Zeidler, 1990].

The space

$$C^\infty(0, T) \hat{\otimes} [C^\infty(\bar{\Omega})]^3$$

is dense in

$$H^1(0, T) \hat{\otimes} [L^2(\Omega)]^3 \quad \text{and} \quad L^2(0, T) \hat{\otimes} H(\text{curl}; \Omega)$$

and

$$C^\infty([0, T]) \hat{\otimes} [C_0^\infty(\Omega)]^3$$

is dense in

$$L^2(0, T) \hat{\otimes} H_0(\text{curl}; \Omega) \simeq L^2(0, T; H(\text{curl}; \Omega)).$$

Sobolev Spaces - Properties

One can show that the embedding

$$H^1(0, T; [L^2(\Omega)]^3) \subset C([0, T], [L^2(\Omega)]^3)$$

is continuous, see e.g. [Zeidler, 1990].

The space

$$C^\infty(0, T) \hat{\otimes} [C^\infty(\bar{\Omega})]^3$$

is dense in

$$H^1(0, T) \hat{\otimes} [L^2(\Omega)]^3 \quad \text{and} \quad L^2(0, T) \hat{\otimes} H(\text{curl}; \Omega)$$

and

$$C^\infty([0, T]) \hat{\otimes} [C_0^\infty(\Omega)]^3$$

is dense in

$$L^2(0, T) \hat{\otimes} H_0(\text{curl}; \Omega) \simeq L^2(0, T; H(\text{curl}; \Omega)).$$

See [Weidmann, 2000], Ch 1.6, and [Aubin, 2000], Ch 12.7, 12.6.

Sobolev Spaces

We define

$$H_{0;}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H^1(0, T; [L^2(\Omega)]^3),$$

$$H_{0;0}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H_{\cdot,0}^1(0, T; [L^2(\Omega)]^3).$$

Sobolev Spaces

We define

$$H_{0;}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H^1(0, T; [L^2(\Omega)]^3),$$

$$H_{0;0}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H_{\cdot,0}^1(0, T; [L^2(\Omega)]^3).$$

Sobolev Spaces

We define

$$H_{0;}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H^1(0, T; [L^2(\Omega)]^3),$$

$$H_{0;0}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H_{\cdot,0}^1(0, T; [L^2(\Omega)]^3).$$

Content

1. Introduction and Definitions
2. Space-Time Variational Formulation
 - The ODE corresponding to Maxwell's Equations
 - Dependencies in the Right Hand Side
3. Generalization for the Variational Formulation
4. Numerical Example

The Differential Equation

Consider the Maxwell's equations as the equation

$$\begin{aligned}
 \epsilon \partial_{tt} \mathbf{E} + \nabla \times (\mu^{-1} \nabla \times \mathbf{E}) &= -\partial_t \mathbf{J} && \text{in } Q, \\
 \epsilon \partial_t \mathbf{E}(0, \mathbf{x}) &= -\mathbf{J}(0, \mathbf{x}) + \nabla \times \mathbf{H}_0(\mathbf{x}) && \text{for } \mathbf{x} \in \Omega, \\
 \mathbf{E}(0, \mathbf{x}) &= \mathbf{E}_0(\mathbf{x}) && \text{for } \mathbf{x} \in \Omega, \\
 \mathbf{n} \times \mathbf{E} &= \mathbf{0} && \text{on } \Sigma.
 \end{aligned}$$

The Differential Equation

Consider

$$\begin{aligned}
 \epsilon \partial_{tt} \mathbf{u} + \nabla \times (\mu^{-1} \nabla \times \mathbf{u}) &= -\partial_t \mathbf{J} && \text{in } Q, \\
 \partial_t \mathbf{u}(0, \mathbf{x}) &= \boldsymbol{\psi}(\mathbf{x}) && \text{for } \mathbf{x} \in \Omega, \\
 \mathbf{u}(0, \mathbf{x}) &= \boldsymbol{\phi}(\mathbf{x}) && \text{for } \mathbf{x} \in \Omega, \\
 \mathbf{n} \times \mathbf{u} &= \mathbf{0} && \text{on } \Sigma = \partial\Omega \times (0, T)
 \end{aligned}$$

for $\boldsymbol{\phi} \in H_0(\text{curl}; \Omega)$, $\boldsymbol{\psi} \in [L^2(\Omega)]^3$.

Definition

We define

$$\|u\|_{L^2(\Omega, \epsilon)}^2 := (\epsilon u, u)_{L^2(\Omega)},$$

$$\|u\|_{H(\text{curl}; \Omega, \epsilon, \mu)}^2 := (\epsilon u, u)_{L^2(\Omega)} + (\mu^{-1} \nabla \times u, \nabla \times u)_{L^2(\Omega)},$$

$$\|u\|_{H^{\text{curl}; 1}(Q)}^2 := (\epsilon \partial_t u, \partial_t u)_{L^2(Q)} + (\mu^{-1} \nabla \times u, \nabla \times u)_{L^2(Q)}.$$

Existence and Uniqueness

Theorem

Let $\partial_t \mathbf{J} \in L^1(0, T; [L^2(\Omega)]^3)$, $\phi \in H_0(\text{curl}; \Omega)$ and $\psi \in [L^2(\Omega)]^3$.

Existence and Uniqueness

Theorem

Let $\partial_t \mathbf{J} \in L^1(0, T; [L^2(\Omega)]^3)$, $\phi \in H_0(\text{curl}; \Omega)$ and $\psi \in [L^2(\Omega)]^3$.

Then there exists a unique solution to the variational formulation:

Find $u \in H_{0;0}^{\text{curl};1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\mu^{-1} \nabla \times u, \nabla \times v)_Q = -(\partial_t \mathbf{J}, v)_Q - (\epsilon \psi, v(0, \cdot))_\Omega$$

for all $v \in H_{0;0}^{\text{curl};1}(Q)$.

Existence and Uniqueness

Theorem

Let $\partial_t \mathbf{J} \in L^1(0, T; [L^2(\Omega)]^3)$, $\phi \in H_0(\text{curl}; \Omega)$ and $\psi \in [L^2(\Omega)]^3$.

Then there exists a unique solution to the variational formulation:

Find $u \in H_{0;0}^{\text{curl};1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\mu^{-1} \nabla \times u, \nabla \times v)_Q = -(\partial_t \mathbf{J}, v)_Q - (\epsilon \psi, v(0, \cdot))_\Omega$$

for all $v \in H_{0;0}^{\text{curl};1}(Q)$. If additionally $\partial_t \mathbf{J} \in [L^2(Q)]^3$ then the following inequality holds true

$$\|u\|_{H_{\text{curl};1}^{\text{curl};1}(Q)}^2 \leq 3T \|\psi\|_{L^2(\Omega, \epsilon)}^2 + 3T \|\phi\|_{H(\text{curl}; \Omega, \epsilon, \mu)}^2 + 3T^2 \|\partial_t \mathbf{J}\|_{[L^2(Q)]^3}^2.$$

The ODE corresponding to Maxwell's Equations

Consider

$$\epsilon \partial_{tt} \mathbf{u} + \nabla \times (\mu^{-1} \nabla \times \mathbf{u}) = \mathbf{f} \quad \text{in } Q.$$

The ODE corresponding to Maxwell's Equations

Consider

$$\epsilon \partial_{tt} \mathbf{u} + \nabla \times (\mu^{-1} \nabla \times \mathbf{u}) = \mathbf{f} \quad \text{in } Q.$$

and the Ansatzfunction

$$\mathbf{u}(t, \mathbf{x}) = \sum_i U_i(t) \mathbf{e}_i(\mathbf{x}),$$

where $\{\mathbf{e}_i\}_{i \in \mathbb{N}}$ is a fundamental system in $H_0(\text{curl}; \Omega)$ which has the following property:

The ODE corresponding to Maxwell's Equations

Consider

$$\epsilon \partial_{tt} \mathbf{u} + \nabla \times (\mu^{-1} \nabla \times \mathbf{u}) = \mathbf{f} \quad \text{in } Q.$$

and the Ansatzfunction

$$\mathbf{u}(t, \mathbf{x}) = \sum_i U_i(t) \mathbf{e}_i(\mathbf{x}),$$

where $\{\mathbf{e}_i\}_{i \in \mathbb{N}}$ is a fundamental system in $H_0(\text{curl}; \Omega)$ which has the following property: For every i either a $\kappa_i > 0$, such that

$$(\mu^{-1} \nabla \times \mathbf{e}_i, \nabla \times \phi)_{L^2(\Omega)} = \kappa_i (\epsilon \mathbf{e}_i, \phi)_{L^2(\Omega)}$$

The ODE corresponding to Maxwell's Equations

Consider

$$\epsilon \partial_{tt} \mathbf{u} + \nabla \times (\mu^{-1} \nabla \times \mathbf{u}) = \mathbf{f} \quad \text{in } Q.$$

and the Ansatzfunction

$$\mathbf{u}(t, \mathbf{x}) = \sum_i U_i(t) \mathbf{e}_i(\mathbf{x}),$$

where $\{\mathbf{e}_i\}_{i \in \mathbb{N}}$ is a fundamental system in $H_0(\text{curl}; \Omega)$ which has the following property: For every i either a $\kappa_i > 0$, such that

$$(\mu^{-1} \nabla \times \mathbf{e}_i, \nabla \times \phi)_{L^2(\Omega)} = \kappa_i (\epsilon \mathbf{e}_i, \phi)_{L^2(\Omega)}$$

or it holds true that

$$(\mu^{-1} \nabla \times \mathbf{e}_i, \nabla \times \phi)_{L^2(\Omega)} = 0$$

for all $\phi \in H_0(\text{curl}; \Omega)$.

The ODE corresponding to Maxwell's Equations

Consider

$$\epsilon \partial_{tt} \mathbf{u} + \nabla \times (\mu^{-1} \nabla \times \mathbf{u}) = \mathbf{f} \quad \text{in } Q.$$

and the Ansatzfunction

$$\mathbf{u}(t, \mathbf{x}) = \sum_i U_i(t) \mathbf{e}_i(\mathbf{x}),$$

where $\{\mathbf{e}_i\}_{i \in \mathbb{N}}$ is a fundamental system in $H_0(\text{curl}; \Omega)$ which has the following property: For every i either a $\kappa_i > 0$, such that

$$(\mu^{-1} \nabla \times \mathbf{e}_i, \nabla \times \phi)_{L^2(\Omega)} = \kappa_i (\epsilon \mathbf{e}_i, \phi)_{L^2(\Omega)}$$

or it holds true that

$$(\mu^{-1} \nabla \times \mathbf{e}_i, \nabla \times \phi)_{L^2(\Omega)} = 0$$

for all $\phi \in H_0(\text{curl}; \Omega)$. [Monk, 2003]

The ODE corresponding to Maxwell's Equations

By rewriting the variational formulation

Find $u \in H_{0;0}^{curl;1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\mu^{-1} \nabla \times u, \nabla \times v)_Q = F(v)$$

for all $v \in H_{0;0}^{curl;1}(Q)$.

The ODE corresponding to Maxwell's Equations

By rewriting the variational formulation

Find $u \in H_{0;0}^{curl;1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\mu^{-1} \nabla \times u, \nabla \times v)_Q = F(v)$$

for all $v \in H_{0;0}^{curl;1}(Q)$.

we get

Find $U_j \in H^1(0, T)$, with $U_j(0) = \phi$, such that either

$$-(\partial_t U_j, \partial_t V)_{(0,T)} + \kappa_j (U_j, V)_{(0,T)} = F(V e_j)$$

The ODE corresponding to Maxwell's Equations

By rewriting the variational formulation

Find $u \in H_{0;0}^{curl;1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\mu^{-1} \nabla \times u, \nabla \times v)_Q = F(v)$$

for all $v \in H_{0;0}^{curl;1}(Q)$.

we get

Find $U_j \in H^1(0, T)$, with $U_j(0) = \phi$, such that either

$$-(\partial_t U_j, \partial_t V)_{(0,T)} + \kappa_j (U_j, V)_{(0,T)} = F(Ve_j)$$

or

$$-(\partial_t U_j, \partial_t V)_{(0,T)} = F(Ve_j)$$

for all $V \in H_{0;0}^1(0, T)$.

Dependencies in the Right Hand Side

Consider

$$J = \sigma E + J_a.$$

Dependencies in the Right Hand Side

Consider

$$J = \sigma E + J_a.$$

Then we get the following variational formulation:

Find $u \in H_{0;}^{curl;1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\sigma \partial_t u, v)_Q + (\mu^{-1} \nabla \times u, \nabla \times v)_Q = F(v),$$

Dependencies in the Right Hand Side

Consider

$$J = \sigma E + J_a.$$

Then we get the following variational formulation:

Find $u \in H_{0;0}^{curl;1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\sigma \partial_t u, v)_Q + (\mu^{-1} \nabla \times u, \nabla \times v)_Q = F(v),$$

where

$$F(v) := -(\partial_t J_a, v)_Q - (\epsilon \psi, v(0, \cdot))_\Omega$$

for all $v \in H_{0;0}^{curl;1}(Q)$.

Existence and Uniqueness

Theorem

Let $\partial_t \mathbf{J}_a \in L^1(0, T; [L^2(\Omega)]^3)$, $\phi \in H_0(\text{curl}; \Omega)$, $\psi \in [L^2(\Omega)]^3$ and $\sigma \in L^\infty(\Omega)$ strictly positive a.e.

Existence and Uniqueness

Theorem

Let $\partial_t \mathbf{J}_a \in L^1(0, T; [L^2(\Omega)]^3)$, $\phi \in H_0(\text{curl}; \Omega)$, $\psi \in [L^2(\Omega)]^3$ and $\sigma \in L^\infty(\Omega)$ strictly positive a.e. or $\sigma \in [L^\infty(\Omega)]^{3 \times 3}$ positive definite.

Existence and Uniqueness

Theorem

Let $\partial_t J_a \in L^1(0, T; [L^2(\Omega)]^3)$, $\phi \in H_0(\text{curl}; \Omega)$, $\psi \in [L^2(\Omega)]^3$ and $\sigma \in L^\infty(\Omega)$ strictly positive a.e. or $\sigma \in [L^\infty(\Omega)]^{3 \times 3}$ positive definite.

Then there exists a unique solution to the variational formulation:

Find $u \in H_{0;1}^{\text{curl};1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\sigma \partial_t u, v)_Q + \left(\mu^{-1} \nabla \times u, \nabla \times v \right)_Q = F(v)$$

for all $v \in H_{0;0}^{\text{curl};1}(Q)$,

Existence and Uniqueness

Theorem

Let $\partial_t \mathbf{J}_a \in L^1(0, T; [L^2(\Omega)]^3)$, $\phi \in H_0(\text{curl}; \Omega)$, $\psi \in [L^2(\Omega)]^3$ and $\sigma \in L^\infty(\Omega)$ strictly positive a.e. or $\sigma \in [L^\infty(\Omega)]^{3 \times 3}$ positive definite.

Then there exists a unique solution to the variational formulation:

Find $u \in H_{0;1}^{\text{curl};1}(Q)$, with $u(x, 0) = \phi$, such that

$$-(\epsilon \partial_t u, \partial_t v)_Q + (\sigma \partial_t u, v)_Q + \left(\mu^{-1} \nabla \times u, \nabla \times v \right)_Q = F(v)$$

for all $v \in H_{0;0}^{\text{curl};1}(Q)$, where

$$F(v) := -(\partial_t \mathbf{J}_a, v)_Q - (\epsilon \psi, v(0, \cdot))_\Omega.$$

Content

1. Introduction and Definitions
2. Space-Time Variational Formulation
 - The ODE corresponding to Maxwell's Equations
 - Dependencies in the Right Hand Side
3. Generalization for the Variational Formulation
4. Numerical Example

The Differential Equation

Consider

$$\begin{aligned} \epsilon \partial_{tt} \mathbf{u} + \nabla \times (\mu^{-1} \nabla \times \mathbf{u}) &= -\partial_t \mathbf{J} && \text{in } Q, \\ \partial_t \mathbf{u}(0, \mathbf{x}) &= \mathbf{0} && \text{for } \mathbf{x} \in \Omega, \\ \mathbf{u}(0, \mathbf{x}) &= \mathbf{0} && \text{for } \mathbf{x} \in \Omega, \\ \mathbf{n} \times \mathbf{u} &= \mathbf{0} && \text{on } \Sigma = \partial\Omega \times (0, T). \end{aligned}$$

Sobolev Spaces

We defined

$$H_{0;0}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H_{0,\cdot}^1(0, T; [L^2(\Omega)]^3),$$

$$H_{0;0}^{curl;1}(Q) := L^2(0, T; H_0(curl; \Omega)) \cap H_{\cdot,0}^1(0, T; [L^2(\Omega)]^3).$$

Definitions

Define

$$D_{tt,cc}^{Q_-} u := \epsilon \partial_{tt} u + \nabla \times (\mu^{-1} \nabla \times u)$$

as an operator in the distributional sense for distributions, i.e.

$D_{tt,cc}^{Q_-} : \mathcal{D}'(Q_-) \rightarrow \mathcal{D}'(Q_-)$ and

$$D_{tt,cc}^{Q_-} T(\phi) = T(D_{tt,cc}^{Q_-} \phi).$$

Definitions

Define

$$D_{tt,cc}^{Q_-} u := \epsilon \partial_{tt} u + \nabla \times (\mu^{-1} \nabla \times u)$$

as an operator in the distributional sense for distributions, i.e.

$$D_{tt,cc}^{Q_-} : \mathcal{D}'(Q_-) \rightarrow \mathcal{D}'(Q_-) \text{ and}$$

$$D_{tt,cc}^{Q_-} T(\phi) = T(D_{tt,cc}^{Q_-} \phi).$$

Consider

$$\mathcal{H}^{curl,1}(Q) := \{u|_Q \mid u \in L^2(Q_-), u|_{(-\infty,0) \times \Omega} = 0, D_{tt,cc}^{Q_-} T u \in [H_{0;0}^{curl;1}(Q)]'\}$$

with

$$Q_- := (-\infty, T) \times \Omega,$$

$$T_u(\phi) := \int_Q u \phi \, dx \, dt \quad \forall \phi \in \mathcal{D}(Q),$$

$$\|u\|_{\mathcal{H}^{curl,1}(Q)}^2 := \|u\|_{L^2(Q)}^2 + \|D_{tt,cc}^{Q_-} T u\|_{[H_{0;0}^{curl;1}(Q)]'}^2.$$

Definitions

Consider

$$\mathcal{H}^{curl,1}(Q) := \{u|_Q \mid u \in L^2(Q_-), u|_{(-\infty,0) \times \Omega} = 0, D_{tt,cc}^{Q_-} T_u \in [H_{0;0}^{curl;1}(Q)]'\}.$$

We define

$$\mathcal{H}_{0,}^{curl,1}(Q) = \overline{H_{0;0,}^{curl;1}(Q)}^{\|\cdot\|_{\mathcal{H}^{curl,1}(Q)}}.$$

Definitions

Consider

$$\mathcal{H}^{curl,1}(Q) := \{u|_Q \mid u \in L^2(Q_-), u|_{(-\infty,0) \times \Omega} = 0, D_{tt,cc}^{Q-} T_u \in [H_{0;0}^{curl;1}(Q)]'\}.$$

We define

$$\mathcal{H}_{0,}^{curl,1}(Q) = \overline{H_{0;0}^{curl;1}(Q)}^{\|\cdot\|_{\mathcal{H}^{curl,1}(Q)}}.$$

If $u \in H_{0,}^{curl;1}(Q)$, with $\partial u(0, \cdot) = 0$, and $v \in H_{0,0}^{curl;1}(Q)$, then

$$\left\langle D_{tt,cc}^{Q-} T_u, v \right\rangle_Q = -(\epsilon \partial_t u, \partial_t v)_{L^2(Q)} + \left(\mu^{-1} \nabla \times u, \nabla \times v \right)_{L^2(Q)}.$$

Further Generalization

Theorem

Let $f \in [H_{0,0}^{curl;1}(Q)]'$ then there exists a unique $u \in \mathcal{H}_{0,0}^{curl;1}(Q)$ such that

$$\left\langle D_{tt,cc}^Q T_u, v \right\rangle_Q = \langle f, v \rangle_Q \quad \forall v \in H_{0,0}^{curl;1}(Q)$$

and

$$\mathcal{L} : \mathcal{H}_{0,0}^{curl;1}(Q) \rightarrow [H_{0,0}^{curl;1}(Q)]'$$

with $\mathcal{L}u := f$ is an isomorphism.

Content

1. Introduction and Definitions
2. Space-Time Variational Formulation
 - The ODE corresponding to Maxwell's Equations
 - Dependencies in the Right Hand Side
3. Generalization for the Variational Formulation
4. Numerical Example

Example

We take a look at the following example over $Q = (0, 1)^2 \times (0, 1)$ with $\epsilon, \mu \equiv 1$

$$u(x, t) = t^2(x - x^2)(y - y^2) \begin{pmatrix} y \\ -x \end{pmatrix}.$$

Example

We take a look at the following example over $Q = (0, 1)^2 \times (0, 1)$ with $\epsilon, \mu \equiv 1$

$$u(x, t) = t^2(x - x^2)(y - y^2) \begin{pmatrix} y \\ -x \end{pmatrix}.$$

Consider $u_h(t, x) = \sum_{i=1}^N \sum_{j=1}^M u_{i,j} \phi_i(t) \psi_j(x)$, where $\{\phi_i\}_i \in \mathbf{S}_{h_t}^1(\mathcal{T}_N^t)$ and $\{\vec{\psi}_j\}_j \in \mathbf{N}'_\alpha(\mathcal{T}_M^x)$.

Example

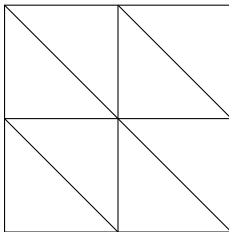
We take a look at the following example over $Q = (0, 1)^2 \times (0, 1)$ with $\epsilon, \mu \equiv 1$

$$u(x, t) = t^2(x - x^2)(y - y^2) \begin{pmatrix} y \\ -x \end{pmatrix}.$$

Consider $u_h(t, x) = \sum_{i=1}^N \sum_{j=1}^M u_{i,j} \phi_i(t) \psi_j(x)$, where $\{\phi_i\}_i \subset S_{h_t}^1(\mathcal{T}_N^t)$ and $\{\vec{\psi}_j\}_j \subset N_\alpha^l(\mathcal{T}_M^x)$. Then we get the following L^2 -error

hx \ ht	1/8	1/16	1/32	1/64	1/128	1/256
1/4	188.10	4897.40	18.3346	3.4329	0.01086	0.011
1/8	1148.722	31.69	10.2872	4.2366	0.01082	0.011
1/16	2.271	0.0099	0.0105	0.01088	0.011	0.011

CFL-Condition



For a form regular triangulation with isosceles rectangular triangles and \mathcal{N}_0^I elements in space the CFL-condition is given by

$$h_t < \sqrt{\frac{12\pi}{18c_F^2}} h_x \approx 0,299725 h_x.$$

Summary

- A variational formulation for the 2nd order PDE and $\partial_t \mathbf{J} \in L^1(0, T; [L^2(\Omega)]^3)$

Summary

- A variational formulation for the 2nd order PDE and $\partial_t \mathbf{J} \in L^1(0, T; [L^2(\Omega)]^3)$
- A variational formulation for linear dependencies in the right hand side

Summary

- A variational formulation for the 2nd order PDE and $\partial_t \mathbf{J} \in L^1(0, T; [L^2(\Omega)]^3)$
- A variational formulation for linear dependencies in the right hand side
- A variational formulation for the 2nd order PDE and $\partial_t \mathbf{J} \in [H_{0,0}^{1;curl}(Q)]'$

Summary

- A variational formulation for the 2nd order PDE and $\partial_t \mathbf{J} \in L^1(0, T; [L^2(\Omega)]^3)$
- A variational formulation for linear dependencies in the right hand side
- A variational formulation for the 2nd order PDE and $\partial_t \mathbf{J} \in [H_{,0;0}^{1;curl}(Q)]'$
- One numerical example

References

- **E. Zeidler**, *Nonlinear Functional Analysis and its Application II/A: Linear Monotone Operators*, Springer, New York, 1990
- **O.A. Ladyzhenskaya**, *The Boundary Value Problems of Mathematical Physics*, Springer, New York, 1985
- **P. Monk**, *Finite Element Methods for Maxwell's Equations*, Oxford, 2003
- **O. Steinbach and M. Zank**, *A Stabilized Space-Time Finite Element Method for the Wave Equation*, Selected papers from the 30th Chemnitz FEM Symposium 2017, Springer, Cham, 2019
- **M. Zank**, *Inf-Sup Stable Space-Time Methods for Time-Dependent Partial Differential Equations*, 2019
- **J.I.M. Hauser and O. Steinbach**, *Space-time variational methods for Maxwell's equations*, Proceedings in Applied Mathematics and Mechanics - 90th GAMM Annual Meeting, 2019

Number of Dofs

hx \ ht	0.125000	0.062500	0.031250
0.250000	909	1717	3333
0.125000	3393	6409	12441
0.062500	12897	24361	47289

hx \ ht	0.015625	0.007812	0.003906
0.250000	6565	13029	25957
0.125000	24505	48633	96889
0.062500	93145	184857	368281

The Variational Formulation for the System

Consider the operator $L : H_{0;0}^{curl;1} \times H_{0;0}^{curl;1} \rightarrow [L^2(Q)]^3 \times [L^2(Q)]^3$ with

$$L \begin{pmatrix} E \\ H \end{pmatrix} = \begin{pmatrix} \epsilon & 0 \\ 0 & \mu \end{pmatrix} \frac{\partial}{\partial t} \begin{pmatrix} E \\ H \end{pmatrix} + \begin{pmatrix} 0 & -\nabla \times \\ \nabla \times & 0 \end{pmatrix} \begin{pmatrix} E \\ H \end{pmatrix}.$$

The Variational Formulation for the System

Consider the operator $L : H_{0;0}^{curl;1} \times H_{0;0}^{curl;1} \rightarrow [L^2(Q)]^3 \times [L^2(Q)]^3$ with

$$L \begin{pmatrix} E \\ H \end{pmatrix} = \begin{pmatrix} \epsilon & 0 \\ 0 & \mu \end{pmatrix} \frac{\partial}{\partial t} \begin{pmatrix} E \\ H \end{pmatrix} + \begin{pmatrix} 0 & -\nabla \times \\ \nabla \times & 0 \end{pmatrix} \begin{pmatrix} E \\ H \end{pmatrix}.$$

Define

$$V := \overline{H_{0;0}^{curl;1} \times H_{0;0}^{curl;1}}^{\|\cdot\|_V}$$

with

$$\|v\|_V^2 := \|v\|_{[L^2(Q)]^3 \times [L^2(Q)]^3}^2 + \|Lv\|_{[L^2(Q)]^3 \times [L^2(Q)]^3}^2.$$

The Variational Formulation for the System

Theorem

Let $(f, g) \in [L^2(Q)]^3 \times [L^2(Q)]^3$, then there exists a unique pair $(E, H) \in V$, s.t.

$$(L(E, H), (\phi, \nu))_W = ((f, g), (\phi, \nu))_W,$$

for all $(\phi, \nu) \in [L^2(Q)]^3 \times [L^2(Q)]^3$.

The Variational Formulation for the System

Theorem

Let $(f, g) \in [L^2(Q)]^3 \times [L^2(Q)]^3$, then there exists a unique pair $(E, H) \in V$, s.t.

$$(L(E, H), (\phi, \nu))_W = ((f, g), (\phi, \nu))_W,$$

for all $(\phi, \nu) \in [L^2(Q)]^3 \times [L^2(Q)]^3$. Furthermore

$$\|(E, H)\|_V \leq (1 + T^2 c(\epsilon, \mu)^2)^{1/2} \|(f, g)\|_W.$$

Generalization-Definitions

Define

$$D_{tt,t,cc}^{Q-} u := \epsilon \partial_{tt} u - \sigma \partial_t u + \nabla \times (\mu^{-1} \nabla \times u)$$

as an operator in the distributional sense for distributions, i.e.

$D_{tt,t,cc}^{Q-} : \mathcal{D}'(Q_-) \rightarrow \mathcal{D}'(Q_-)$ and

$$D_{tt,t,cc}^{Q-} T(\phi) = T(D_{tt,t,cc}^{Q-} \phi).$$

Generalization-Definitions

Define

$$D_{tt,t,cc}^{Q-} u := \epsilon \partial_{tt} u - \sigma \partial_t u + \nabla \times (\mu^{-1} \nabla \times u)$$

as an operator in the distributional sense for distributions, i.e.

$$D_{tt,t,cc}^{Q-} : \mathcal{D}'(Q_-) \rightarrow \mathcal{D}'(Q_-) \text{ and}$$

$$D_{tt,t,cc}^{Q-} T(\phi) = T(D_{tt,t,cc}^{Q-} \phi).$$

Consider

$$\hat{\mathcal{H}}^{curl,1}(Q) := \{u|_Q \mid u \in L^2(Q_-), u|_{(-\infty,0) \times \Omega} = 0, D_{tt,t,cc}^{Q-} T u \in [H_{0;0}^{curl;1}(Q)]'\}$$

with

$$Q_- := (-\infty, T) \times \Omega,$$

$$\|u\|_{\hat{\mathcal{H}}^{curl,1}(Q)}^2 := \|u\|_{L^2(Q)}^2 + \|D_{tt,t,cc}^{Q-} T u\|_{[H_{0;0}^{curl;1}(Q)]'}^2$$

Generalization-Definitions

Define

$$D_{tt,t,cc}^{Q-} u := \epsilon \partial_{tt} u - \sigma \partial_t u + \nabla \times (\mu^{-1} \nabla \times u)$$

as an operator in the distributional sense for distributions, i.e.

$$D_{tt,t,cc}^{Q-} : \mathcal{D}'(Q_-) \rightarrow \mathcal{D}'(Q_-) \text{ and}$$

$$D_{tt,t,cc}^{Q-} T(\phi) = T(D_{tt,t,cc}^{Q-} \phi).$$

Consider

$$\hat{\mathcal{H}}^{curl,1}(Q) := \{u|_Q \mid u \in L^2(Q_-), u|_{(-\infty,0) \times \Omega} = 0, D_{tt,t,cc}^{Q-} T u \in [H_{0,0}^{curl;1}(Q)]'\}$$

with

$$Q_- := (-\infty, T) \times \Omega,$$

$$\|u\|_{\hat{\mathcal{H}}^{curl,1}(Q)}^2 := \|u\|_{L^2(Q)}^2 + \|D_{tt,t,cc}^{Q-} T u\|_{[H_{0,0}^{curl;1}(Q)]'}^2$$

and

$$\hat{\mathcal{H}}_{0,0}^{curl,1}(Q) = \overline{H_{0,0}^{curl;1}(Q)}^{\|\cdot\|_{\hat{\mathcal{H}}^{curl,1}(Q)}}.$$

Properties

It holds true that

- The space $(\hat{\mathcal{H}}^{curl,1}(Q), (\cdot, \cdot)_{\hat{\mathcal{H}}^{curl,1}(Q)})$ is a Hilbert space.

Properties

It holds true that

- The space $(\hat{\mathcal{H}}^{curl,1}(Q), (\cdot, \cdot)_{\hat{\mathcal{H}}^{curl,1}(Q)})$ is a Hilbert space.
- $H_{0;0}^{curl;1}(Q) \subset \hat{\mathcal{H}}^{curl,1}(Q)$ and $\hat{\mathcal{H}}_{0,}^{curl,1}(Q) \subset \hat{\mathcal{H}}^{curl,1}(Q)$.

Properties

It holds true that

- The space $(\hat{\mathcal{H}}^{curl,1}(Q), (\cdot, \cdot)_{\hat{\mathcal{H}}^{curl,1}(Q)})$ is a Hilbert space.
- $H_{0;0}^{curl,1}(Q) \subset \hat{\mathcal{H}}^{curl,1}(Q)$ and $\hat{\mathcal{H}}_{0}^{curl,1}(Q) \subset \hat{\mathcal{H}}^{curl,1}(Q)$.
- $(\hat{\mathcal{H}}_{0}^{curl,1}(Q), (\cdot, \cdot)_{\hat{\mathcal{H}}^{curl,1}(Q)})$ is a Hilbert space.

Properties

It holds true that

- The space $(\hat{\mathcal{H}}^{curl,1}(Q), (\cdot, \cdot)_{\hat{\mathcal{H}}^{curl,1}(Q)})$ is a Hilbert space.
- $H_{0;0}^{curl,1}(Q) \subset \hat{\mathcal{H}}^{curl,1}(Q)$ and $\hat{\mathcal{H}}_0^{curl,1}(Q) \subset \hat{\mathcal{H}}^{curl,1}(Q)$.
- $(\hat{\mathcal{H}}_0^{curl,1}(Q), (\cdot, \cdot)_{\hat{\mathcal{H}}^{curl,1}(Q)})$ is a Hilbert space.
- $|\cdot|_{\hat{\mathcal{H}}^{curl,1}(Q)} := \|D_{tt,t,cc}^{Q-} \cdot\|_{[H_{0;0}^{curl,1}(Q)]'}$ is equivalent to $\|\cdot\|_{\hat{\mathcal{H}}^{curl,1}(Q)}$ in $\hat{\mathcal{H}}_0^{curl,1}(Q)$.

Properties

It holds true that

- The space $(\hat{\mathcal{H}}^{curl,1}(Q), (\cdot, \cdot)_{\hat{\mathcal{H}}^{curl,1}(Q)})$ is a Hilbert space.
- $H_{0;0}^{curl;1}(Q) \subset \hat{\mathcal{H}}^{curl,1}(Q)$ and $\hat{\mathcal{H}}_{0,}^{curl,1}(Q) \subset \hat{\mathcal{H}}^{curl,1}(Q)$.
- $(\hat{\mathcal{H}}_{0,}^{curl,1}(Q), (\cdot, \cdot)_{\hat{\mathcal{H}}^{curl,1}(Q)})$ is a Hilbert space.
- $|\cdot|_{\hat{\mathcal{H}}^{curl,1}(Q)} := \|D_{tt,t,cc}^{Q-} \cdot\|_{[H_{0;0}^{curl;1}(Q)]'}$ is equivalent to $\|\cdot\|_{\hat{\mathcal{H}}^{curl,1}(Q)}$ in $\hat{\mathcal{H}}_{0,}^{curl,1}(Q)$.
- If $u, v \in H^{curl;1}(Q)$, then

$$\left(D_{tt,t,cc}^{Q-} u, v \right)_Q = -(\epsilon \partial_t u, \partial_t v)_{L^2(Q)} + (\sigma \partial_t u, v)_{L^2(Q)} + (\mu^{-1} \nabla \times u, \nabla \times v)_{L^2(Q)}.$$

Further Generalization

Theorem

Let $f \in [H_{0;0}^{curl;1}(Q)]'$ then there exists a unique $u \in \hat{\mathcal{H}}_{0,}^{curl;1}(Q)$ such that

$$\left(D_{tt,t,cc}^{Q-} u, v \right)_Q = (f, v)_Q \quad \forall v \in H_{0;0}^{curl;1}(Q)$$

and

$$\mathcal{L} : \hat{\mathcal{H}}_{0,}(Q) \rightarrow [H_{0;0}^{curl;1}(Q)]'$$

with $\mathcal{L}u := f$ is an isomorphism.

Remark 2D curl

There are two different *curl* in 2D:

Remark 2D curl

There are two different *curl* in 2D:

- $\nabla \times \vec{E} = \partial_x E_2 - \partial_y E_1$

Remark 2D curl

There are two different *curl* in 2D:

- $\nabla \times \vec{E} = \partial_x E_2 - \partial_y E_1$
- $\vec{\nabla} \times E = \begin{pmatrix} \partial_y E \\ -\partial_x E \end{pmatrix}$

Remark 2D curl

There are two different *curl* in 2D:

- $\nabla \times \vec{E} = \partial_x E_2 - \partial_y E_1$
- $\vec{\nabla} \times E = \begin{pmatrix} \partial_y E \\ -\partial_x E \end{pmatrix}$

Hence we look at the differential equation:

$$\epsilon \partial_{tt} \vec{E} + \vec{\nabla} \times \mu^{-1} (\nabla \times \vec{E}) = \vec{f}$$

Remark 2D curl

There are two different *curl* in 2D:

- $\nabla \times \vec{E} = \partial_x E_2 - \partial_y E_1$
- $\vec{\nabla} \times E = \begin{pmatrix} \partial_y E \\ -\partial_x E \end{pmatrix}$

Hence we look at the differential equation:

$$\epsilon \partial_{tt} \vec{E} + \vec{\nabla} \times \mu^{-1} (\nabla \times \vec{E}) = \vec{f}$$

and the variational formulation

$$-(\epsilon \partial_t \vec{u}, \partial_t \vec{v})_Q + (\mu^{-1} \nabla \times \vec{u}, \nabla \times \vec{v})_Q = (\vec{f}, \vec{v})_Q.$$