

Localized pointwise error estimates of finite element approximations to the Stokes problem on convex polyhedra (and polygons)

N. Behringer, D. Leykekhman, B. Vexler



12th Workshop on Analysis and Advanced Numerical Methods for Partial
Differential Equations
01.07.2019

Outline

1. Applications and problem statement
2. Idea of the proof

Outline

1. Applications and problem statement

2. Idea of the proof

The situation for the elliptic problem

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Schatz/Wahlbin 1977 (interior error estimates)

For $\Omega_1 \Subset \Omega_2 \Subset \Omega$, $\text{dist}(\Omega_1, \partial\Omega_2) \geq d$, $\text{dist}(\Omega_2, \partial\Omega) \geq d$, then

$$\|u - u_h\|_{L^\infty(\Omega_1)} \leq C_d \left(h^l |\ln h|^r \|u\|_{W^{l,\infty}(\Omega_2)} + \|u - u_h\|_{L^2(\Omega_2)} \right)$$

The situation for the elliptic problem

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Schatz/Wahlbin 1977 (interior error estimates)

For $\Omega_1 \Subset \Omega_2 \Subset \Omega$, $\text{dist}(\Omega_1, \partial\Omega_2) \geq d$, $\text{dist}(\Omega_2, \partial\Omega) \geq d$, then

$$\|u - u_h\|_{L^\infty(\Omega_1)} \leq C_d \left(h^l |\ln h|^r \|u\|_{W^{l,\infty}(\Omega_2)} + \|u - u_h\|_{L^2(\Omega_2)} \right)$$

- ▶ Optimal control
 - ▶ Sparse optimal control

The situation for the elliptic problem

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Schatz/Wahlbin 1977 (interior error estimates)

For $\Omega_1 \Subset \Omega_2 \Subset \Omega$, $\text{dist}(\Omega_1, \partial\Omega_2) \geq d$, $\text{dist}(\Omega_2, \partial\Omega) \geq d$, then

$$\|u - u_h\|_{L^\infty(\Omega_1)} \leq C_d \left(h^l |\ln h|^r \|u\|_{W^{l,\infty}(\Omega_2)} + \|u - u_h\|_{L^2(\Omega_2)} \right)$$

- ▶ Optimal control
 - ▶ Sparse optimal control
 - ▶ Control constrained pointwise tracking

The situation for the elliptic problem

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Schatz/Wahlbin 1977 (interior error estimates)

For $\Omega_1 \Subset \Omega_2 \Subset \Omega$, $\text{dist}(\Omega_1, \partial\Omega_2) \geq d$, $\text{dist}(\Omega_2, \partial\Omega) \geq d$, then

$$\|u - u_h\|_{L^\infty(\Omega_1)} \leq C_d \left(h^l |\ln h|^r \|u\|_{W^{l,\infty}(\Omega_2)} + \|u - u_h\|_{L^2(\Omega_2)} \right)$$

- ▶ Optimal control
 - ▶ Sparse optimal control
 - ▶ Control constrained pointwise tracking
 - ▶ Optimal control with state constraints

The situation for the elliptic problem

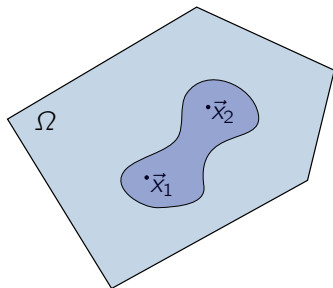
$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Schatz/Wahlbin 1977 (interior error estimates)

For $\Omega_1 \Subset \Omega_2 \Subset \Omega$, $\text{dist}(\Omega_1, \partial\Omega_2) \geq d$, $\text{dist}(\Omega_2, \partial\Omega) \geq d$, then

$$\|u - u_h\|_{L^\infty(\Omega_1)} \leq C_d \left(h^r |\ln h|^r \|u\|_{W^{l,\infty}(\Omega_2)} + \|u - u_h\|_{L^2(\Omega_2)} \right)$$

- ▶ Optimal control
 - ▶ Sparse optimal control
 - ▶ Control constrained pointwise tracking
 - ▶ Optimal control with state constraints



The situation for the elliptic problem

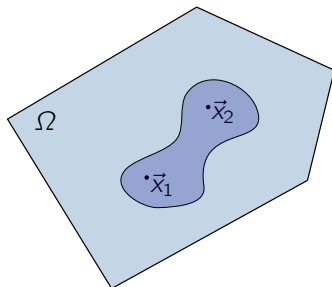
$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Schatz/Wahlbin 1977 (interior error estimates)

For $\Omega_1 \Subset \Omega_2 \Subset \Omega$, $\text{dist}(\Omega_1, \partial\Omega_2) \geq d$, $\text{dist}(\Omega_2, \partial\Omega) \geq d$, then

$$\|u - u_h\|_{L^\infty(\Omega_1)} \leq C_d \left(h^r |\ln h|^r |u|_{W^{l,\infty}(\Omega_2)} + \|u - u_h\|_{L^2(\Omega_2)} \right)$$

- ▶ Optimal control
 - ▶ Sparse optimal control
 - ▶ Control constrained pointwise tracking
 - ▶ Optimal control with state constraints
- ▶ L^∞ error estimates on graded meshes



The situation for the elliptic problem

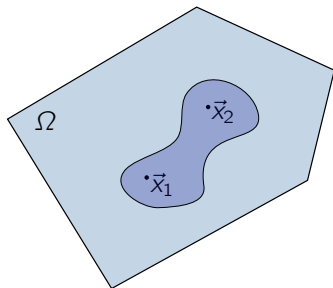
$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Schatz/Wahlbin 1977 (interior error estimates)

For $\Omega_1 \Subset \Omega_2 \Subset \Omega$, $\text{dist}(\Omega_1, \partial\Omega_2) \geq d$, $\text{dist}(\Omega_2, \partial\Omega) \geq d$, then

$$\|u - u_h\|_{L^\infty(\Omega_1)} \leq C_d \left(h^r |\ln h|^r \|u\|_{W^{l,\infty}(\Omega_2)} + \|u - u_h\|_{L^2(\Omega_2)} \right)$$

- ▶ Optimal control
 - ▶ Sparse optimal control
 - ▶ Control constrained pointwise tracking
 - ▶ Optimal control with state constraints
- ▶ L^∞ error estimates on graded meshes
- ▶ (Local) L^∞ error estimates for the parabolic problem (e.g. heat equation)



Problem statement

Let $\Omega \subset \mathbb{R}^3$ be a convex polyhedral domain and \vec{V}_h and M_h suitable finite element spaces for the Stokes problem (e.g. Taylor-Hood FEs).

Stokes equation and discretization

$(\vec{u}, p) \in H_0^1(\Omega)^3 \times L_0^2(\Omega)$ solve

$$-\Delta \vec{u} + \nabla p = \vec{f} \quad \text{in } \Omega$$

$$\nabla \cdot \vec{u} = 0 \quad \text{in } \Omega$$

$$\vec{u} = \vec{0} \quad \text{on } \partial\Omega$$

$(\vec{u}_h, p_h) \in \vec{V}_h \times M_h$ satisfy

$$\begin{aligned} (\nabla \vec{u}_h, \nabla \vec{v}_h) - (p_h, \nabla \cdot \vec{v}_h) + (\nabla \cdot \vec{u}_h, q_h) \\ = (\vec{f}, \vec{v}_h) \quad \forall (\vec{v}_h, q_h) \in \vec{V}_h \times M_h \end{aligned}$$

Discretization error estimate: global

$$\|\vec{u}_h - \vec{u}\|_{L^\infty(\Omega)} \leq \inf_{(\vec{v}_h, q_h) \in \vec{V}_h \times M_h} C |\ln h| \left(|\ln h| \|\vec{u} - \vec{v}_h\|_{L^\infty(\Omega)} + h \|p - q_h\|_{L^\infty(\Omega)} \right)$$

Problem statement

Let $\Omega \subset \mathbb{R}^3$ be a convex polyhedral domain and \vec{V}_h and M_h suitable finite element spaces for the Stokes problem (e.g. Taylor-Hood FEs).

Stokes equation and discretization

$$\begin{aligned}
 (\vec{u}, p) \in H_0^1(\Omega)^3 \times L_0^2(\Omega) \text{ solve} \\
 -\Delta \vec{u} + \nabla p = \vec{f} \quad \text{in } \Omega \\
 \nabla \cdot \vec{u} = 0 \quad \text{in } \Omega \\
 \vec{u} = \vec{0} \quad \text{on } \partial\Omega
 \end{aligned}$$

$$\begin{aligned}
 (\vec{u}_h, p_h) \in \vec{V}_h \times M_h \text{ satisfy} \\
 (\nabla \vec{u}_h, \nabla \vec{v}_h) - (p_h, \nabla \cdot \vec{v}_h) + (\nabla \cdot \vec{u}_h, q_h) \\
 = (\vec{f}, \vec{v}_h) \quad \forall (\vec{v}_h, q_h) \in \vec{V}_h \times M_h
 \end{aligned}$$

Discretization error estimate: local

$\Omega_1 \subset \Omega_2 \subset \Omega$ with $\text{dist}(\bar{\Omega}_1, \partial\Omega_2) \geq d$

$$\begin{aligned}
 \|\vec{u}_h - \vec{u}\|_{L^\infty(\Omega_1)} \leq \inf_{(\vec{v}_h, q_h) \in \vec{V}_h \times M_h} \left[C |\ln h| \left(|\ln h| \|\vec{u} - \vec{v}_h\|_{L^\infty(\Omega_2)} + h \|p - q_h\|_{L^\infty(\Omega_2)} \right) + \right. \\
 \left. C_d |\ln h| \left(h \|\vec{u} - \vec{v}_h\|_{H^1(\Omega)} + \|\vec{u} - \vec{v}_h\|_{L^2(\Omega)} + h \|p - q_h\|_{L^2(\Omega)} \right) \right]
 \end{aligned}$$

A short history

R. G. Durán, R. H. Nochetto, and J. P. Wang. [Sharp maximum norm error estimates for finite element approximations of the Stokes problem in 2-D.](#)

Math. Comp., 51(184):491–506, 1988

V. Girault, R. H. Nochetto, and L. R. Scott. [Maximum-norm stability of the finite element Stokes projection.](#)

J. Math. Pures Appl. (9), 84(3):279–330, 2005

J. Guzmán and D. Leykekhman. [Pointwise error estimates of finite element approximations to the Stokes problem on convex polyhedra.](#)

Math. Comp., 81(280):1879–1902, 2012

V. Girault, R. H. Nochetto, and L. R. Scott. [Max-norm estimates for Stokes and Navier-Stokes approximations in convex polyhedra.](#)

Numer. Math., 131(4):771–822, 2015

A short history

R. G. Durán, R. H. Nochetto, and J. P. Wang. Sharp maximum norm error estimates for finite element approximations of the Stokes problem in 2-D.

Math. Comp., 51(184):491–506, 1988

Two dimensions, global, $L^\infty(\Omega)$, $W^{1,\infty}(\Omega)$.

V. Girault, R. H. Nochetto, and L. R. Scott. Maximum-norm stability of the finite element Stokes projection.

J. Math. Pures Appl. (9), 84(3):279–330, 2005

J. Guzmán and D. Leykekhman. Pointwise error estimates of finite element approximations to the Stokes problem on convex polyhedra.

Math. Comp., 81(280):1879–1902, 2012

V. Girault, R. H. Nochetto, and L. R. Scott. Max-norm estimates for Stokes and Navier-Stokes approximations in convex polyhedra.

Numer. Math., 131(4):771–822, 2015

A short history

R. G. Durán, R. H. Nochetto, and J. P. Wang. Sharp maximum norm error estimates for finite element approximations of the Stokes problem in 2-D.

Math. Comp., 51(184):491–506, 1988

Two dimensions, global, $L^\infty(\Omega)$, $W^{1,\infty}(\Omega)$.

V. Girault, R. H. Nochetto, and L. R. Scott. Maximum-norm stability of the finite element Stokes projection.

J. Math. Pures Appl. (9), 84(3):279–330, 2005

Three dimensions, global, $W^{1,\infty}$, more than convexity.

J. Guzmán and D. Leykekhman. Pointwise error estimates of finite element approximations to the Stokes problem on convex polyhedra.

Math. Comp., 81(280):1879–1902, 2012

V. Girault, R. H. Nochetto, and L. R. Scott. Max-norm estimates for Stokes and Navier-Stokes approximations in convex polyhedra.

Numer. Math., 131(4):771–822, 2015

A short history

R. G. Durán, R. H. Nochetto, and J. P. Wang. Sharp maximum norm error estimates for finite element approximations of the Stokes problem in 2-D.

Math. Comp., 51(184):491–506, 1988

Two dimensions, global, $L^\infty(\Omega)$, $W^{1,\infty}(\Omega)$.

V. Girault, R. H. Nochetto, and L. R. Scott. Maximum-norm stability of the finite element Stokes projection.

J. Math. Pures Appl. (9), 84(3):279–330, 2005

Three dimensions, global, $W^{1,\infty}$, more than convexity.

J. Guzmán and D. Leykekhman. Pointwise error estimates of finite element approximations to the Stokes problem on convex polyhedra.

Math. Comp., 81(280):1879–1902, 2012

Three dimensions, global, $W^{1,\infty}(\Omega)$, technique I.

V. Girault, R. H. Nochetto, and L. R. Scott. Max-norm estimates for Stokes and Navier-Stokes approximations in convex polyhedra.

Numer. Math., 131(4):771–822, 2015

A short history

R. G. Durán, R. H. Nochetto, and J. P. Wang. Sharp maximum norm error estimates for finite element approximations of the Stokes problem in 2-D.

Math. Comp., 51(184):491–506, 1988

Two dimensions, global, $L^\infty(\Omega)$, $W^{1,\infty}(\Omega)$.

V. Girault, R. H. Nochetto, and L. R. Scott. Maximum-norm stability of the finite element Stokes projection.

J. Math. Pures Appl. (9), 84(3):279–330, 2005

Three dimensions, global, $W^{1,\infty}$, more than convexity.

J. Guzmán and D. Leykekhman. Pointwise error estimates of finite element approximations to the Stokes problem on convex polyhedra.

Math. Comp., 81(280):1879–1902, 2012

Three dimensions, global, $W^{1,\infty}(\Omega)$, technique I.

V. Girault, R. H. Nochetto, and L. R. Scott. Max-norm estimates for Stokes and Navier-Stokes approximations in convex polyhedra.

Numer. Math., 131(4):771–822, 2015

Three dimensions, global, $W^{1,\infty}(\Omega)$, technique II.

A short history

R. G. Durán, R. H. Nochetto, and J. P. Wang. Sharp maximum norm error estimates for finite element approximations of the Stokes problem in 2-D.

Math. Comp., 51(184):491–506, 1988

Two dimensions, global, $L^\infty(\Omega)$, $W^{1,\infty}(\Omega)$.

V. Girault, R. H. Nochetto, and L. R. Scott. Maximum-norm stability of the finite element Stokes projection.

J. Math. Pures Appl. (9), 84(3):279–330, 2005

Three dimensions, global, $W^{1,\infty}$, more than convexity.

J. Guzmán and D. Leykekhman. Pointwise error estimates of finite element approximations to the Stokes problem on convex polyhedra.

Math. Comp., 81(280):1879–1902, 2012

Three dimensions, global, $W^{1,\infty}(\Omega)$, technique I.

V. Girault, R. H. Nochetto, and L. R. Scott. Max-norm estimates for Stokes and Navier-Stokes approximations in convex polyhedra.

Numer. Math., 131(4):771–822, 2015

Three dimensions, global, $W^{1,\infty}(\Omega)$, technique II.

Our results: Global results in three dimensions ($L^\infty(\Omega)$), local results in two and three dimensions ($L^\infty(\Omega)$, $W^{1,\infty}(\Omega)$)

Outline

1. Applications and problem statement

2. Idea of the proof

Selected ingredients for the proof

For the **Ritz projection** $R_h \vec{z}$ of $\vec{z} \in H_0^1(\Omega)^3$ into the finite element space given by

$$(\nabla R_h \vec{z}, \nabla \vec{v}_h) = (\nabla \vec{z}, \nabla \vec{v}_h) \quad \forall \vec{v}_h \in \vec{V}_h$$

that for $\vec{z} \in H_0^1(\Omega)^3 \cap L^\infty(\Omega)^3$ the solution of the Laplace equation, it holds that

$$\|R_h \vec{z}\|_{L^\infty(\Omega)} \leq C |\ln h| \|\vec{z}\|_{L^\infty(\Omega)}.$$

Selected ingredients for the proof

For the Ritz projection $R_h \vec{z}$ of $\vec{z} \in H_0^1(\Omega)^3$ into the finite element space given by

$$(\nabla R_h \vec{z}, \nabla \vec{v}_h) = (\nabla \vec{z}, \nabla \vec{v}_h) \quad \forall \vec{v}_h \in \vec{V}_h$$

that for $\vec{z} \in H_0^1(\Omega)^3 \cap L^\infty(\Omega)^3$ the solution of the Laplace equation, it holds that

$$\|R_h \vec{z}\|_{L^\infty(\Omega)} \leq C |\ln h| \|\vec{z}\|_{L^\infty(\Omega)}.$$

A space fulfilling this assumption holds would be e.g. the space of Taylor-Hood finite elements of order greater or equal three.

Selected ingredients for the proof

For the Ritz projection $R_h \vec{z}$ of $\vec{z} \in H_0^1(\Omega)^3$ into the finite element space given by

$$(\nabla R_h \vec{z}, \nabla \vec{v}_h) = (\nabla \vec{z}, \nabla \vec{v}_h) \quad \forall \vec{v}_h \in \vec{V}_h$$

that for $\vec{z} \in H_0^1(\Omega)^3 \cap L^\infty(\Omega)^3$ the solution of the Laplace equation, it holds that

$$\|R_h \vec{z}\|_{L^\infty(\Omega)} \leq C |\ln h| \|\vec{z}\|_{L^\infty(\Omega)}.$$

A space fulfilling this assumption holds would be e.g. the space of Taylor-Hood finite elements of order greater or equal three.

To start off the proof, we define a regularized Green's function

$$\begin{aligned} -\Delta \vec{g} + \nabla \lambda &= \delta_h \vec{e}_i \quad \text{in } \Omega, \\ \nabla \cdot \vec{g} &= 0 \quad \text{in } \Omega, \\ \vec{g} &= \vec{0} \quad \text{on } \partial\Omega. \end{aligned}$$

Here $\delta_h \in C_0^1(T_{\vec{x}_0})$, $T_{\vec{x}_0}$ the cell where the maximum of $|\vec{u}_h|$ is attained, which satisfies for every $\vec{v}_h \in \vec{V}_h$:

$$\vec{v}_{h,i}(\vec{x}_0) = (\vec{v}_h, \delta_h \vec{e}_i)_{T_{\vec{x}_0}}.$$

L^∞ estimate

$$\begin{aligned} |\vec{u}_{h,i}(\vec{x}_0)| &= |(\vec{u}_h, \delta_h \vec{e}_i)_{T_{\vec{x}_0}}| = |(\nabla \vec{u}_h, \nabla \vec{g}_h) - (p_h, \nabla \cdot \vec{g}_h) + (\nabla \cdot \vec{u}_h, \lambda_h)| \\ &= |(\nabla \vec{u}, \nabla \vec{g}_h) - (p, \nabla \cdot \vec{g}_h)| \end{aligned}$$

L^∞ estimate

$$\begin{aligned} |\vec{u}_{h,i}(\vec{x}_0)| &= |(\vec{u}_h, \delta_h \vec{e}_i)_{T_{\vec{x}_0}}| = |(\nabla \vec{u}_h, \nabla \vec{g}_h) - (p_h, \nabla \cdot \vec{g}_h) + (\nabla \cdot \vec{u}_h, \lambda_h)| \\ &= |(\nabla \vec{u}, \nabla \vec{g}_h) - (p, \nabla \cdot \vec{g}_h)| \\ &= |(\nabla R_h \vec{u}, \nabla \vec{g}_h) - (p, \nabla \cdot (\vec{g}_h - \vec{g}))| \end{aligned}$$

L^∞ estimate

$$\begin{aligned} |\vec{u}_{h,i}(\vec{x}_0)| &= |(\vec{u}_h, \delta_h \vec{e}_i)_{T_{\vec{x}_0}}| = |(\nabla \vec{u}_h, \nabla \vec{g}_h) - (p_h, \nabla \cdot \vec{g}_h) + (\nabla \cdot \vec{u}_h, \lambda_h)| \\ &= |(\nabla \vec{u}, \nabla \vec{g}_h) - (p, \nabla \cdot \vec{g}_h)| \\ &= |(\nabla R_h \vec{u}, \nabla \vec{g}_h) - (p, \nabla \cdot (\vec{g}_h - \vec{g}))| \end{aligned}$$

For the first term we get

$$\begin{aligned} |(\nabla R_h \vec{u}, \nabla \vec{g}_h)| &= |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g})) - (R_h \vec{u}, \Delta \vec{g})| \\ &= |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g})) - (R_h \vec{u}, -\delta_h \vec{e}_i + \nabla \lambda)| \\ &\leq h^{-1} \|R_h \vec{u}\|_{L^\infty(\Omega)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} + \|R_h \vec{u}\|_{L^\infty(\Omega)} (C + \|\nabla \lambda\|_{L^1(\Omega)}) \\ &\leq Ch^{-1} |\ln h| \|\vec{u}\|_{L^\infty(\Omega)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} \\ &\quad + C |\ln h| \|\vec{u}\|_{L^\infty(\Omega)} (1 + \|\nabla \lambda\|_{L^1(\Omega)}) \end{aligned}$$

L^∞ estimate

$$\begin{aligned} |\vec{u}_{h,i}(\vec{x}_0)| &= |(\vec{u}_h, \delta_h \vec{e}_i)_{T_{\vec{x}_0}}| = |(\nabla \vec{u}_h, \nabla \vec{g}_h) - (p_h, \nabla \cdot \vec{g}_h) + (\nabla \cdot \vec{u}_h, \lambda_h)| \\ &= |(\nabla \vec{u}, \nabla \vec{g}_h) - (p, \nabla \cdot \vec{g}_h)| \\ &= |(\nabla R_h \vec{u}, \nabla \vec{g}_h) - (p, \nabla \cdot (\vec{g}_h - \vec{g}))| \end{aligned}$$

For the first term we get

$$\begin{aligned} |(\nabla R_h \vec{u}, \nabla \vec{g}_h)| &= |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g})) - (R_h \vec{u}, \Delta \vec{g})| \\ &= |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g})) - (R_h \vec{u}, -\delta_h \vec{e}_i + \nabla \lambda)| \\ &\leq h^{-1} \|R_h \vec{u}\|_{L^\infty(\Omega)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} + \|R_h \vec{u}\|_{L^\infty(\Omega)} (C + \|\nabla \lambda\|_{L^1(\Omega)}) \\ &\leq Ch^{-1} |\ln h| \|\vec{u}\|_{L^\infty(\Omega)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} \\ &\quad + C |\ln h| \|\vec{u}\|_{L^\infty(\Omega)} (1 + \|\nabla \lambda\|_{L^1(\Omega)}) \end{aligned}$$

and for the second term

$$|(p, \nabla \cdot (\vec{g}_h - \vec{g}))| \leq C \|p\|_{L^\infty(\Omega)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)}$$

L^∞ estimate

$$\begin{aligned}
 |\bar{u}_{h,i}(\vec{x}_0)| &= |(\bar{u}_h, \delta_h \bar{e}_i)_{T_{\vec{x}_0}}| = |(\nabla \bar{u}_h, \nabla \bar{g}_h) - (p_h, \nabla \cdot \bar{g}_h) + (\nabla \cdot \bar{u}_h, \lambda_h)| \\
 &= |(\nabla \bar{u}, \nabla \bar{g}_h) - (p, \nabla \cdot \bar{g}_h)| \\
 &= |(\nabla R_h \bar{u}, \nabla \bar{g}_h) - (p, \nabla \cdot (\bar{g}_h - \bar{g}))|
 \end{aligned}$$

For the first term we get

$$\begin{aligned}
 |(\nabla R_h \bar{u}, \nabla \bar{g}_h)| &= |(\nabla R_h \bar{u}, \nabla(\bar{g}_h - \bar{g})) - (R_h \bar{u}, \Delta \bar{g})| \\
 &= |(\nabla R_h \bar{u}, \nabla(\bar{g}_h - \bar{g})) - (R_h \bar{u}, -\delta_h \bar{e}_i + \nabla \lambda)| \\
 &\leq h^{-1} \|R_h \bar{u}\|_{L^\infty(\Omega)} \|\nabla(\bar{g}_h - \bar{g})\|_{L^1(\Omega)} + \|R_h \bar{u}\|_{L^\infty(\Omega)} (C + \|\nabla \lambda\|_{L^1(\Omega)}) \\
 &\leq Ch^{-1} |\ln h| \|\bar{u}\|_{L^\infty(\Omega)} \|\nabla(\bar{g}_h - \bar{g})\|_{L^1(\Omega)} \\
 &\quad + C |\ln h| \|\bar{u}\|_{L^\infty(\Omega)} (1 + \|\nabla \lambda\|_{L^1(\Omega)})
 \end{aligned}$$

and for the second term

$$|(p, \nabla \cdot (\bar{g}_h - \bar{g}))| \leq C \|p\|_{L^\infty(\Omega)} \|\nabla(\bar{g}_h - \bar{g})\|_{L^1(\Omega)}$$

Then, estimates

$$\|\nabla(\bar{g}_h - \bar{g})\|_{L^1(\Omega)} \leq Ch |\ln h| \quad \text{and} \quad \|\nabla \lambda\|_{L^1(\Omega)} \leq C |\ln h| \quad \text{give the result.}$$

Localization

Let x_0 be where $\|\vec{u}_h\|_{L^\infty(\Omega_1)}$ is maximal and consider the weight

$$\sigma = \sqrt{|\vec{x} - \vec{x}_0|^2 + \kappa^2 h^2}.$$

Note that $\sigma^{-1} \sim d^{-1}$ for $|\vec{x} - \vec{x}_0| \geq d$ and h small.

Localization

Let x_0 be where $\|\vec{u}_h\|_{L^\infty(\Omega_1)}$ is maximal and consider the weight

$$\sigma = \sqrt{|\vec{x} - \vec{x}_0|^2 + \kappa^2 h^2}.$$

Note that $\sigma^{-1} \sim d^{-1}$ for $|\vec{x} - \vec{x}_0| \geq d$ and h small. Then, as before

$$|\vec{u}_{h,i}(\vec{x}_0)| = |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g})) - (R_h \vec{u}, -\delta_h \vec{e}_i + \nabla \lambda) - (\rho, \nabla \cdot (\vec{g}_h - \vec{g}))|.$$

Localization

Let x_0 be where $\|\vec{u}_h\|_{L^\infty(\Omega_1)}$ is maximal and consider the weight

$$\sigma = \sqrt{|\vec{x} - \vec{x}_0|^2 + \kappa^2 h^2}.$$

Note that $\sigma^{-1} \sim d^{-1}$ for $|\vec{x} - \vec{x}_0| \geq d$ and h small. Then, as before

$$|\vec{u}_{h,i}(\vec{x}_0)| = |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g})) - (R_h \vec{u}, -\delta_h \vec{e}_i + \nabla \lambda) - (\rho, \nabla \cdot (\vec{g}_h - \vec{g}))|.$$

We consider only the first term (the others follow similarly)

$$\begin{aligned} |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g}))| &\leq \|\nabla R_h \vec{u}\|_{L^\infty(\Omega_2)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} \\ &\quad + \|\sigma^{-3/2} \nabla R_h \vec{u}\|_{L^2(\Omega \setminus \Omega_2)} \|\sigma^{3/2} \nabla(\vec{g}_h - \vec{g})\|_{L^2(\Omega)} \\ &\leq Ch^{-1} |\ln h| \|\vec{u}\|_{L^\infty(\Omega_2)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} \\ &\quad + C_d h^{-1} |\ln h| \|\vec{u}\|_{L^2(\Omega \setminus \Omega_2)} \|\sigma^{3/2} \nabla(\vec{g}_h - \vec{g})\|_{L^2(\Omega)}. \end{aligned}$$

Localization

Let x_0 be where $\|\vec{u}_h\|_{L^\infty(\Omega_1)}$ is maximal and consider the weight

$$\sigma = \sqrt{|\vec{x} - \vec{x}_0|^2 + \kappa^2 h^2}.$$

Note that $\sigma^{-1} \sim d^{-1}$ for $|\vec{x} - \vec{x}_0| \geq d$ and h small. Then, as before

$$|\vec{u}_{h,i}(\vec{x}_0)| = |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g})) - (R_h \vec{u}, -\delta_h \vec{e}_i + \nabla \lambda) - (p, \nabla \cdot (\vec{g}_h - \vec{g}))|.$$

We consider only the first term (the others follow similarly)

$$\begin{aligned} |(\nabla R_h \vec{u}, \nabla(\vec{g}_h - \vec{g}))| &\leq \|\nabla R_h \vec{u}\|_{L^\infty(\Omega_2)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} \\ &\quad + \|\sigma^{-3/2} \nabla R_h \vec{u}\|_{L^2(\Omega \setminus \Omega_2)} \|\sigma^{3/2} \nabla(\vec{g}_h - \vec{g})\|_{L^2(\Omega)} \\ &\leq Ch^{-1} |\ln h| \|\vec{u}\|_{L^\infty(\Omega_2)} \|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} \\ &\quad + C_d h^{-1} |\ln h| \|\vec{u}\|_{L^2(\Omega \setminus \Omega_2)} \|\sigma^{3/2} \nabla(\vec{g}_h - \vec{g})\|_{L^2(\Omega)}. \end{aligned}$$

The result follows by the respective estimates for

$$\|\nabla(\vec{g}_h - \vec{g})\|_{L^1(\Omega)} \quad \text{and} \quad \|\sigma^{3/2} \nabla(\vec{g}_h - \vec{g})\|_{L^2(\Omega)}.$$

A word on the L^1 estimate of $\vec{g}_h - \vec{g}$

To prove the convergence result we use the well-known dyadic decomposition technique, where we split the domain in the following way. Put $d_j = 2^{-j}$ and consider the decomposition

$$\Omega = \Omega_* \cup \bigcup_{j=0}^J \Omega_j,$$

where

$$\Omega_* = \{\vec{x} \in \Omega : |\vec{x} - \vec{x}_0| \leq Kh\},$$

$$\Omega_j = \{\vec{x} \in \Omega : d_{j+1} \leq |\vec{x} - \vec{x}_0| \leq d_j\},$$

K is a sufficiently large constant to be chosen later and J is an integer such that

$$2^{-(J+1)} \leq Kh \leq 2^{-J}.$$

The convergence of $\|\sigma^{3/2} \nabla(\vec{g}_h - \vec{g})\|_{L^2(\Omega)}$ follows then directly from the L^1 estimate.

Thank you very much for your attention and (potential) questions!

Preprint available on <http://www.igdk.eu/IGDK1754/Preprints>

`niklas.behringer@ma.tum.de`