Error analysis of a finite difference method on graded meshes for a time-fractional diffusion equation

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Joint work with

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#### The PDE and the behaviour of its solution

Finite difference method on a uniform mesh

Finite difference method on a graded mesh



## Outline

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Fractional-derivative PDE (initial-boundary value problem)

$$Lu := D_t^{\alpha} u - p \frac{\partial^2 u}{\partial x^2} + r(x)u = f(x, t)$$

for  $(x,t)\in Q:=(0,l) imes (0,T]$ , with

u(0, t) = u(I, t) = 0 for  $t \in (0, T]$ ,  $u(x, 0) = \phi(x)$  for  $x \in [0, I]$ ,

where  $D_t^{\alpha} u$  is a Caputo fractional derivative of order  $\alpha \in (0, 1)$ , p is a positive constant, the functions r, f are continuous on  $\overline{Q} := [0, I] \times [0, T]$ with  $r(x) \ge 0$  for all x, and  $\phi \in C[0, I]$ .



# The fractional derivative

for

 $D_t^{lpha}$  denotes the Caputo fractional derivative defined by

$$D_t^{\alpha}g(x,t) := \frac{1}{\Gamma(1-\alpha)} \int_{s=0}^t (t-s)^{-\alpha} \left(\frac{\partial g}{\partial t}\right)(x,s) \, ds$$
$$(x,t) \in Q.$$

The derivative definition is *not* local (unlike classical derivatives).

Fact: if 
$$g \in C^1(\bar{Q})$$
, then 
$$\lim_{\alpha \to 1^-} [D_t^{\alpha} g(x,t)] = g_t(x,t) \quad \text{for each } (x,t) \in Q.$$



# Example (part 1)

Example. Consider the fractional heat equation

$$D^lpha_t v - rac{\partial^2 v}{\partial x^2} = 0 \quad ext{on } (0,\pi) imes (0,T]$$

with initial condition  $v(x,0) = \sin x$ and boundary conditions  $v(0,t) = v(\pi,t) = 0$ . Its solution is

where the Mittag-Leffler function

$$E_{\alpha}(z) := \sum_{k=0}^{\infty} \frac{z^k}{\Gamma(\alpha k+1)}.$$

M-L function is fractional analogue of the exponential function:

 $D_t^{\alpha} E_{\alpha}(\lambda t^{\alpha}) = \lambda E_{\alpha}(t^{\alpha}).$ 



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#### Graph of solution to Example

Plot of surface v(x, t) and its cross-section at  $x = \pi/2$  when  $\alpha = 0.3$ . An initial layer in v at t = 0 is evident.





# Example (part 2)

In this Example, one has [recall that  $0 < \alpha < 1$ ]

$$egin{aligned} & v_t(x,t) pprox \mathit{Ct}^{lpha-1}\sin x ext{ as } t 
ightarrow 0^+, \ & v_{tt}(x,t) pprox \mathit{Ct}^{lpha-2}\sin x ext{ as } t 
ightarrow 0^+, \end{aligned}$$

while

$$\left|rac{\partial^i v(x,t)}{\partial x^i}
ight| \leq C ext{ for } i=0,1,2,3,4 ext{ and all } (x,t) \in ar{Q}.$$



Regularity of the solution u (part 1)

Return to our problem

$$Lu := D_t^{\alpha} u - p \frac{\partial^2 u}{\partial x^2} + r(x)u = f(x, t).$$

Existence/uniqueness/regularity of the solution is examined in K.Sakamoto and M.Yamamoto, J. Math. Anal. Appl., 382 (2011), 426–447.

- Y.Luchko, Fract. Calc. Appl. Anal., 15 (2012) 141–160.
- uses separation of variables to prove existence and uniqueness of a classical solution to this problem
- i.e., a function u whose derivatives exist and satisfy the PDE and the initial-boundary conditions pointwise
- under some extra hypotheses on the data



## Regularity of the solution u (part 2)

Can extend results of those papers to show that

$$\left|rac{\partial^i u(x,t)}{\partial x^i}
ight| \leq C ext{ for } i=0,1,2,3,4 ext{ and all } (x,t) \in ar{Q}.$$

and

$$\left|rac{\partial^j u(x,t)}{\partial t^j}
ight| \leq C t^{lpha-j} ext{ for } j=1,2 ext{ and all } (x,t) \in Q$$

Here and subsequently, C denotes a generic constant that depends only on the data  $\alpha$ , p, r, f,  $\phi$ , l, T.

These bounds are sharp: they agree with the behaviour of our earlier example

 $v(x,t) = E_{\alpha}(-t^{\alpha})\sin x$  for  $(x,t) \in [0,\pi] \times [0,1]$ .



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Consider the time-fractional heat equation

$$D_t^{lpha} v - rac{\partial^2 v}{\partial x^2} = 0 \quad ext{on } (0,\pi) imes (0,T]$$

with initial condition  $v(x,0) = \phi(x) \in C^2[0,1]$ satisfying  $\phi(0) = \phi(\pi) = 0$  and  $v(0,t) = v(\pi,t) = 0$ .

one must have  $v \equiv 0$ .

M.Stynes, *Too much regularity may force too much uniqueness*, Fract. Calc. Appl. Anal. 19 (2016), no. 6, 1554–1562.

Y.Lin and C.Xu, *Finite difference/spectral approximations for the time-fractional diffusion equation*, J. Comput. Phys., 225 (2007), 1533–1552. MathSciNet references: 207



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## Uniform mesh, spatial discretisation

Let M and N be positive integers. Set

$$x_n := nh \text{ for } n = 0, 1, \dots, N \text{ with } h := I/N,$$
  
$$t_m := m\tau \text{ for } m = 0, 1, \dots, M \text{ with } \tau := T/M.$$

Computed approximation to the solution at each mesh point  $(x_n, t_m)$  is denoted by  $u_n^m$ .

 $u_{xx}$  is discretised using a standard approximation:

$$\frac{\partial^2 u}{\partial x^2}(x_n, t_m) \approx \delta_x^2 u_n^m := \frac{u_{n+1}^m - 2u_n^m + u_{n-1}^m}{h^2}$$



#### Discretisation in time

The Caputo fractional derivative

$$D_t^{\alpha}u(x_n,t_m) = \frac{1}{\Gamma(1-\alpha)}\sum_{k=0}^{m-1}\int_{s=t_k}^{t_{k+1}}(t_m-s)^{-\alpha}\frac{\partial u(x_n,s)}{\partial t}\,ds$$

is approximated by the so-called L1 approximation

$$D_M^{lpha} u_n^m := rac{1}{\Gamma(1-lpha)} \sum_{k=0}^{m-1} rac{u_n^{k+1} - u_n^k}{ au} \int_{s=t_k}^{t_{k+1}} (t_m - s)^{-lpha} \, ds \ = rac{ au^{-lpha}}{\Gamma(2-lpha)} \left[ d_1 u_n^m - d_m u_n^0 + \sum_{k=1}^{m-1} (d_{k+1} - d_k) u_n^{m-k} 
ight] \, ,$$

with 
$$d_k := k^{1-\alpha} - (k-1)^{1-\alpha}$$
 for  $k \ge 1$ .  
Here  $d_1 = 1$ ,  $d_k > d_{k+1} > 0$ , and  
 $(1-\alpha)k^{-\alpha} \le d_k \le (1-\alpha)(k-1)^{-\alpha}$ .



#### The scheme

Thus we approximate the IBVP by the discrete problem

$$\begin{split} L_{N,M} u_n^m &:= D_M^{\alpha} u_n^m - p \, \delta_x^2 u_n^m + r(x_n) u_n^m = f(x_n, t_m) \\ & \text{for } 1 \le n \le N - 1, \ 1 \le m \le M; \\ u_0^m &= 0, \quad u_N^m = 0 \ \text{ for } 0 < m \le M, \\ u_n^0 &= \phi(x_n) \ \text{ for } 0 \le n \le N. \end{split}$$

This discretisation is standard; it is considered for example in F.Liu, P.Zhuang & K.Burrage, *Numerical methods and analysis for a class of fractional advection-dispersion models*, Comput. Math. Appl., 64 (2012), 2990–3007.



# Properties of discrete system

At each time level,

- Must solve a tridiagonal linear system; matrix is an M-matrix so scheme satisfies a discrete maximum principle.
- Have to use computed solutions at all previous time levels



Previous numerical analysis: a criticism

—In our discussion of convergence, we consider only the discrete  $L^{\infty}$  norm—

There exist papers (e.g., Liu, Zhang & Burrage 2012) that consider problems and discretisations like ours, and prove  $O(h^2 + \tau^{2-\alpha})$  convergence of the numerical method, under the hypothesis that the solution u of the original problem is in  $C^{4,2}(\bar{Q})$  —which is satisfied only for very special data!

We are interested in proving a convergence result under the realistic hypothesis that  $u \in C^{4,0}(\overline{Q})$  with

$$\left|rac{\partial^\ell u}{\partial t^\ell}(x,t)
ight|\leq C(1+t^{lpha-\ell}) \ \ \, ext{for}\ \, \ell=0,1,2.$$



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Numerical experiments with our simple but typical first Example

$$v(x,t) = E_{lpha}(-t^{lpha})\sin x$$
 for  $(x,t) \in [0,\pi] imes [0,1],$ 

show that for our numerical method one obtains  $O(h^2 + \tau^{\alpha})$  convergence, not the  $O(h^2 + \tau^{2-\alpha})$  that occurs only for unrealistically smooth solutions.



# Truncation error; convergence of scheme

Temporal truncation error: one can show (a bit long and messy) that

$$|D^{\alpha}_{M}u(x_{n},t_{m})-D^{\alpha}_{t}u(x_{n},t_{m})|\leq Cm^{-\alpha}.$$

Also need to sharpen stability estimate of Liu, Zhang & Burrage 2012.

#### Theorem

For m = 1, 2, ..., M the solution  $u_n^m$  of the scheme satisfies

$$\max_{(x_n,t_m)\in\bar{Q}}|u(x_n,t_m)-u_n^m|\leq C(h^2+\tau^{\alpha}).$$

Numerical experiments show that this bound is sharp.



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#### Mesh graded in time

Let M and N be positive integers. Set

$$x_n := nh$$
 for  $n = 0, 1, ..., N$  with  $h := I/N$ ,  
 $t_m := T(m/M)^r$  for  $m = 0, 1, ..., M$ 

with mesh grading  $r \ge 1$  chosen by the user.

Set 
$$\tau_m = t_m - t_{m-1}$$
 for  $m = 1, 2, ..., M$ .

Computed approximation to the solution at each mesh point  $(x_n, t_m)$  is denoted by  $u_n^m$ .

 $u_{xx}$  is discretised as before



#### Discretisation in time

The Caputo fractional derivative

$$D_t^{\alpha}u(x_n,t_m) = \frac{1}{\Gamma(1-\alpha)}\sum_{k=0}^{m-1}\int_{s=t_k}^{t_{k+1}}(t_m-s)^{-\alpha}\frac{\partial u(x_n,s)}{\partial t}\,ds$$

is again approximated by the L1 approximation (but now the mesh is nonuniform in time)

$$D_{M}^{\alpha}u_{n}^{m} := \frac{1}{\Gamma(1-\alpha)} \sum_{k=0}^{m-1} \frac{u_{n}^{k+1} - u_{n}^{k}}{\tau_{k+1}} \int_{s=t_{k}}^{t_{k+1}} (t_{m}-s)^{-\alpha} ds$$
$$= \frac{1}{\Gamma(1-\alpha)} \sum_{k=0}^{m-1} \frac{u_{n}^{k+1} - u_{n}^{k}}{\tau_{k+1}} [(t_{m}-t_{k})^{1-\alpha} - (t_{m}-t_{k+1})^{1-\alpha}]$$



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Truncation error and stability on graded meshes

#### Lemma (temporal truncation error)

There exists a constant C such that for all  $(x_m, t_n) \in Q$  one has

$$|D_N^{\alpha}u(x_m,t_n)-D_t^{\alpha}u(x_m,t_n)|\leq Cn^{-\min\{2-\alpha,r\alpha\}}$$

Also need to prove new discrete stability result (delicate). Lemma (stability of L1 scheme) For n = 1, 2, ..., N one has

$$\|u^n\|_{\infty} \leq \|u^0\|_{\infty} + \tau_n^{\delta} \Gamma(2-\delta) \sum_{j=1}^n \theta_{n,j} \|f^j\|_{\infty}$$

where 
$$\theta_{n,n} = 1$$
 and  $\theta_{n,j} = \sum_{k=1}^{n-j} \tau_{n-k}^{\delta} (d_{n,k} - d_{n,k+1}) \theta_{n-k,j}$ 

for 
$$n = 1, 2, ..., N$$
 and  $j = 1, 2, ..., n - 1$ .



# Convergence on graded meshes

# Theorem The solution $u_m^n$ of the scheme satisfies

$$\max_{(x_m,t_n)\in\bar{Q}}|u(x_m,t_n)-u_m^n|\leq CT^{\alpha}\left(h^2+N^{-\min\{2-\alpha,r\alpha\}}\right).$$

Hence: for  $r \ge (2 - \alpha)/\alpha$ , the rate of convergence is  $O(h^2 + N^{-(2-\alpha)})$ .

Numerical experiments show our theorem is sharp.



#### Reference

Martin Stynes, Eugene O'Riordan and José Luis Gracia, Error analysis of a finite difference method on graded meshes for a time-fractional diffusion equation, SIAM J. Numer. Anal. 55 (2017), 1057–1079.



## Future work

- Alternative discretizations of the fractional derivative?
- Some alternative way of dealing with the weak singularity at t = 0?
- Two spatial dimensions?
- etc. etc.



# Thank you for your attention $\nabla$

7th Conference on Finite Difference Methods: Theory and Applications, 11–16 June 2018 in Lozenetz, Bulgaria Mini-symposium on

> Numerical methods for fractional-derivative problems and applications

organised by Anatoly Alikhanov, Raytcho Lazarov & Martin Stynes

