

## Inverse point source location for the Helmholtz equation

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## The time-periodic wave equation

We consider the propagation of acoustic waves in a homogeneous medium

$$(1) \quad \begin{aligned} \partial_{tt} p(t) - \Delta p(t) &= f(t) && \text{in } \Omega, \\ \partial_t p(t) + \partial_\nu p(t) &= 0 && \text{on } \Gamma_{\text{art}}, \\ \partial_\nu p(t) &= 0 && \text{on } \Gamma_{\text{D}}. \end{aligned}$$

$\partial\Omega = \Gamma_{\text{art}} \cup \Gamma_{\text{D}}$  and a source term  $f$  given by

$$f(t) = \hat{u}(t) \delta_{\hat{x}} \quad \hat{x} \in \Omega_c \subsetneq \Omega$$

and a time periodic signal

$$\hat{u} = \sum_{n=1}^N a_n \sin(-\omega_n t + \varphi_n) = \sum_{n=1}^N \operatorname{Re}(\hat{u}_n \exp(-i\omega_n t)),$$

with frequencies  $\omega_n$ , phaseshifts  $\varphi_n$ , amplitudes  $a_n$  and  $\hat{u}_n = a_n \exp(i\varphi_n) \in \mathbb{C}$ .

## The Helmholtz equation

By a Fourier transform in  $t$  the solution  $p$  to (1) is given by

$$p(t) = \sum_{n=1}^N \operatorname{Re}(p_n \exp(-i\omega_n t)).$$

where the functions  $p_n$  are the solutions to the Helmholtz equation

$$(2) \quad \begin{aligned} -\Delta p_n - \omega_n^2 p_n &= \hat{u}_n \delta_{\hat{x}} && \text{in } \Omega, \\ \partial_\nu p_n - i\omega_n p_n &= 0 && \text{on } \Gamma_{\text{art}}, \\ \partial_\nu p_n &= 0 && \text{on } \Gamma_D, \end{aligned}$$

## The inverse problem

### Problem statement

Given some measurements of the acoustic pressure at the points  $\{x_k\}_{k=1,\dots,K}$ , find the location  $\hat{x} \in \Omega_c$  and coefficients  $u_n \in \mathbb{C}^N$ .

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- ▶ nonconvex optimization problem formulation, see Bermudez et. al 2004

$$(3) \quad \min_{x \in \Omega_c, \hat{u} \in \mathbb{C}^N} \frac{1}{2} \sum_{k=1}^K |\bar{p}(x_k) - p_d^k|_{\mathbb{C}^N}^2 + \alpha |\hat{u}|_{\mathbb{C}^N},$$

subject to  $-\Delta \bar{p} - \bar{\omega}^2 \bar{p} = \hat{u} \delta_x, \quad (+BC)$

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- ▶ convex(ified) optimization problem formulation, see Bredies/Pikkarainen 2013

$$(4) \quad \min_{u \in \mathcal{M}(\Omega_c, \mathbb{C}^N)} \frac{1}{2} \sum_{k=1}^K |\bar{p}(x_k) - p_d^k|_{\mathbb{C}^N}^2 + \alpha \|u\|_{\mathcal{M}(\Omega_c, \mathbb{C}^N)},$$

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## Inverse problem

Consider

$$(5) \quad \min_{u \in \mathcal{M}(\Omega_c, \mathbb{C}^N)} J(p, u) := \frac{1}{2} \sum_{k=1}^K |p(x_k) - p_d^k|_{\mathbb{C}^N}^2 + \alpha \|u\|_{\mathcal{M}(\Omega_c, \mathbb{C}^N)},$$

$$(6) \quad \text{subject to} \quad \begin{cases} -\Delta p_n - \omega_n^2 p_n = u_n|_{\Omega}, & x \in \Omega, \\ \partial_\nu p_n - i\omega_n p_n = 0, & x \in \Gamma_{art}, \quad n = 1, 2, \dots, N. \\ \partial_\nu p_n = u_n|_{\Gamma_D}, & x \in \Gamma_D, \end{cases}$$

- ▶  $\Omega \subset \mathbb{R}^d$ ,  $d \leq 3$ , convex polygonal/polyhedral,  $\Omega_c \subset \bar{\Omega}$  compact.
- ▶  $\Omega_c \cap \Gamma_{art} = \emptyset$ .
- ▶  $\Gamma_D = \cup_i \bar{\Gamma}_i$ ,  $\bar{\Gamma}_i$  plane face of  $\Gamma$ ,  $\Gamma_{art} = \partial\Omega \setminus \Gamma_D$ .
- ▶  $\{x_k\}_{k=1}^K \subset \Omega \setminus \Omega_c$ .



## Wellposedness of State equation

Consider the following very weak formulation of (6)

$$(7) \quad -(p, \Delta \varphi + \omega^2 \varphi)_{\Omega} = \langle u, \chi_{\Omega_c} \varphi \rangle \quad \forall \varphi \in H^2(\Omega) \quad \text{with} \quad \partial_{\nu} \varphi + \chi_{\Gamma_{art}} i \omega \varphi = 0 \quad \text{on}$$

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### Existence of very weak solutions

For any  $u \in \mathcal{M}(\Omega_c)$ , there exists a unique very weak solution  $p \in L^2(\Omega)$  to (6) and there holds

$$\|p\|_{L^2(\Omega)} \leq C \|u\|_{\mathcal{M}(\Omega_c)}$$

for some  $C > 0$ .

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### Additional regularity

There holds  $p \in W^{1,s}(\Omega) \cap \mathcal{C}(\Omega \setminus \mathcal{N}_\varepsilon(\Omega_c))$  for any  $s < d/(d-1)$ ,  $\varepsilon > 0$  where

$$\mathcal{N}_\varepsilon(\Omega_c) = \{x \in \Omega \mid \text{dist}(x, \Omega_c) \leq \varepsilon\}.$$

## Existence of optimal solutions

### Control-to-observation operator

The operator  $S$  given by

$$S : \mathcal{M}(\Omega_c, \mathbb{C}^N) \rightarrow (\mathbb{C}^N)^K \quad S(u) = (p(x_1), p(x_2), \dots, p(x_K)).$$

is weak\*-to-strong continuous. Moreover it is the dual of  $S^* : (\mathbb{C}^N)^K \rightarrow \mathcal{C}(\Omega_c, \mathbb{C}^N)$  with  $S^*q = \xi|_{\Omega_c}$ ,  $\xi = (\xi_1, \dots, \xi_N)$  and

$$(8) \quad \begin{cases} -\Delta \xi_n - \omega_n \xi_n = \sum_{k=1}^K q_{n,k} \delta_{x_k}, & x \in \Omega, \\ \partial_\nu \xi_n + i\omega_n \xi_n = 0, & x \in \Gamma_{art}, \quad n \in \{1, 2, \dots, N\}, \\ \partial_\nu \xi_n = 0, & x \in \Gamma_D, \end{cases}$$

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### Existence of optimal solutions

The optimal control problem (5) has an optimal solution  $\hat{u}$ .

## Existence of finitely supported solutions

### Bound on the number of support points

There exists an optimal solution  $\hat{u}$  to (5) which consists of  $N_d \leq 2NK$  point sources,

$$\hat{u} = \sum_{j=1}^{N_d} \hat{u}_j \delta_{\hat{x}_j} \quad \text{where } \hat{u}_j \in \mathbb{C}^N, \hat{x}_j \in \Omega_c.$$

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► Show

$$U_{p_d, \alpha} = \overline{\text{conv} \{ u \in U_{p_d, \alpha} \mid u \text{ extremal} \}}^{\text{weak-}*}.$$



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- Show

$$\{ u \in U_{p_d, \alpha} \mid u \text{ extremal} \} \subset \left\{ \sum_{j=1}^{2NK} u_j \delta_{x_j} \mid u_j \in \mathbb{C}^N, x_j \in \Omega_c \right\}.$$

## Optimality condition

### Support condition

A measure  $\widehat{u} \in \mathcal{M}(\Omega_c, \mathbb{C}^N)$  is a solution to (5) if and only if the adjoint state  $\widehat{\xi} = S^*(S\widehat{u} - p_d)$  satisfies  $\|\widehat{\xi}\|_{C(\Omega_c, \mathbb{C}^N)} \leq \alpha$  and the polar decomposition  $d\widehat{u} = \widehat{u}' d|\widehat{u}|$ , with  $\widehat{u}' \in L^1(\Omega_c, |\widehat{u}|, \mathbb{C}^N)$ , satisfies

$$\alpha \widehat{u}' = -\widehat{\xi} \quad |\widehat{u}|\text{-almost everywhere.}$$

Thereby,  $\text{supp } |\widehat{u}| \subset \{x \in \Omega_c : |\widehat{\xi}(x)|_{\mathbb{C}^N} = \alpha\}$  for each solution  $\widehat{u}$ .

## Numerical solution, see Bredies/Pikkarainen 2013

$$1. \text{ Set } u^1 = 0, i=1, M = \frac{\sum_{k=1}^K |p_d^k|^2}{2\alpha}, \varphi(t) = \begin{cases} \beta t, & t \leq M \\ \frac{\beta}{2M}(t^2 + M^2), & \text{else} \end{cases}$$

**while**  $s_i \neq 0$  **do**

$$2. \text{ Calculate } \xi^i = S^*(Su_k - p_d). \text{ Determine } x^i \in \Omega_c \text{ with } \langle -\xi^i, \delta_{x^i} \rangle = \|\xi^i\|_{C(\Omega_c, \mathbb{C}^N)}$$

$$3. \text{ Set } \theta^i = \begin{cases} 0, & \|\xi^i\|_{C(\Omega_c, \mathbb{C}^N)} \leq \alpha \\ -\frac{M}{\beta} \xi^i(x_k), & \text{else} \end{cases}$$

$$4. \text{ Set } s_i = \min \left\{ 1, \frac{\alpha \|u_k\|_{M(\Omega_c, \mathbb{C}^N)} - \varphi(\theta^i) + \langle u^i - \theta^i \delta_{x^i}, \xi^i \rangle}{\|S(u^i - \theta^i \delta_{x^i})\|_{\mathbb{C}^{NK}}^2} \right\} \text{ and}$$

$$u_{i+\frac{1}{2}} = (1 - s_i)u^i + s_i \theta^i \delta_{x^i} = \sum_{k=1}^{N_d^{i+\frac{1}{2}}} \tilde{u}_k^{i+\frac{1}{2}} \delta_{x_k^{i+\frac{1}{2}}}.$$

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$$5. \text{ Postprocess } u_{k+\frac{1}{2}} \text{ to get } u_{k+\frac{3}{4}} = \sum_{k=1}^{N_d^{i+\frac{3}{4}}} \tilde{u}_k^{i+\frac{3}{4}} \delta_{x_k^{i+\frac{3}{4}}}, N_d^{i+\frac{3}{4}} \leq 2NK$$

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6. Get  $u_{k+1}$  by solving

$$\min_{\tilde{u}} J(S(u_{k+\frac{3}{4}}(\tilde{u})), u_{k+\frac{3}{4}}(\tilde{u})) \text{ s.t. } u_{k+\frac{3}{4}}(\tilde{u}) = \sum_{k=1}^{N_d^{i+\frac{3}{4}}} \tilde{u}_k \delta_{x_k^{i+\frac{3}{4}}}$$

## Postprocessing

1. Let  $u = \sum_{k=1}^{N_d} \mathbf{u}_k \delta_{x_k}$ ,  $N_d = 2NK + 1$

2. Set

$$u_k = u|_{\{x_k\}} = \mathbf{u}_k \delta_{x_k}, \text{ and } w_k = S(\mathbf{v}_k \delta_{x_k}), \text{ where } \mathbf{v}_k = \frac{\mathbf{u}_k}{\|\mathbf{u}_k\|}.$$

3. Find nontrivial solution  $\lambda \in \mathbb{R}^{N_d}$  of  $\sum_{k=1, \dots, N_d} \lambda_k w_k = 0$  with  $\sum_{k=1, \dots, N_d} \lambda_k \geq 0$ .

4. Set  $u_{new} = \sum_{k=1}^{N_d} \left(1 - \frac{\lambda_k}{\tau \|\mathbf{u}_k\|}\right) \mathbf{u}_k \delta_{x_k}$  with  $\tau = \max_{k=1, \dots, N_d} \frac{\lambda_k}{\|\mathbf{u}_k\|} \geq 0$ .

5.  $\# \text{supp } u_{new} \leq N_d - 1$ ,  $J(S(u_{new}), u_{new}) \leq J(S(u), u)$ .

# Convergence

## Sublinear Convergence (Bredies13)

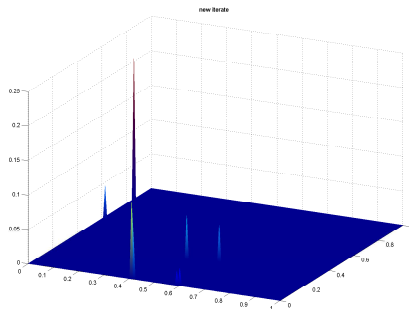
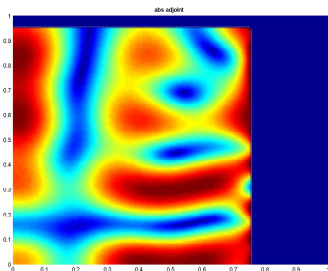
Let the sequence  $\{u_i\}_{i \in \mathbb{N}}$  be generated by the generalized conditional gradient method. Then  $\{u_i\}_{i \in \mathbb{N}}$  is a minimizing sequence for  $J$ , every  $u_i$  has at most  $2NK$  support points and every subsequence of  $\{u_i\}_{i \in \mathbb{N}}$  has a weak\* convergent subsequence that converges to a minimizer  $\hat{u}$ ,  $\# \text{supp } \hat{u} \leq 2NK$  of  $J$ . Furthermore

$$J(S(u_i), u_i) - J(S(\hat{u}), \hat{u}) \leq \frac{c}{i}$$

for a positive,  $i$ -independent constant  $c$

## Numerical Example

- ▶ Consider the unit square  $\Omega$ ,  $\Omega_c = \{x \in \Omega \mid x_1 \leq 0.75, x_2 \leq 0.95\}$ ,  $x_k = (0.875, \frac{k}{16})$ ,  $k = 1, \dots, 15$ ,  $\omega_1 = 13$ .
- ▶ Try to recover a single Dirac located in  $\hat{x} = (0.125, 0.75)$ ,  $u_1 = 0.538 + 0.867i$
- ▶ Solve (5) for  $\alpha_k = (0.6)^k$ ,  $k = 3, \dots, 33$





## But...

Set  $w_\Omega^n = \frac{1}{K} \sum_{k=1}^K |G_n^{x_k}|$ , and consider as admissible set

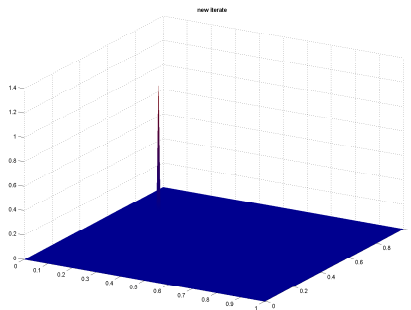
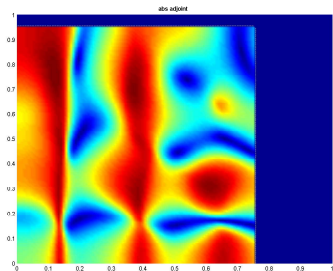
$$\mathcal{M}_w(\Omega_c, \mathbb{C}^N) = \left\{ u \in \mathcal{M}(\Omega_c, \mathbb{C}^N) \mid \int_{\Omega_c} |w_\Omega u'| \, d|u| < \infty \right\}.$$

and the corresponding total variation norm

$$\|u\|_{\mathcal{M}_w(\Omega_c, \mathbb{C}^N)} = \int_{\Omega_c} |w u'| \, d|u| = \int_{\Omega_c} \sqrt{\sum_{n=1}^N (w^n(x) |u'_n(x)|)^2} \, d|u|(x)$$

## And it works!

- ▶ Still a lot to do here, when should you use which weight, does it work in general?
- ▶ Maybe get rid of assumption that  $\Omega_c \subsetneq \Omega$ .



**Last but not least...**

**Thank you for your attention!**