

AANMPDE(JS)

Strobl, July 7, 2016

**An extended midpoint scheme  
for the Landau-Lifschitz-Gilbert equation  
in computational micromagnetics**

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joint work with

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TU Wien  
Institute for Analysis and Scientific Computing

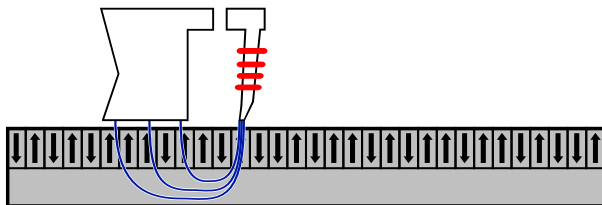


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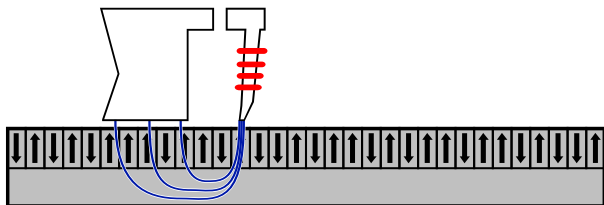
# Model problem

## What is it all about?



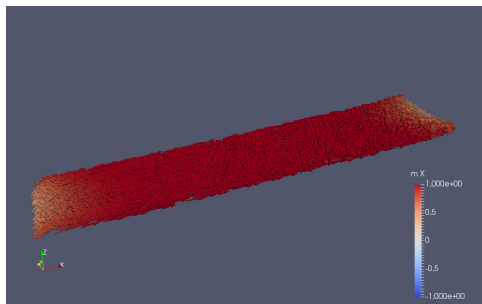
- Writing information on hard drives

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- Writing information on hard drives
- Describes evolution of magnetization  $\mathbf{m} : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  over time
- Ferromagnetic body  $\Omega \subset \mathbb{R}^3$
- Constant modulus of magnetization

## Numerical experiments

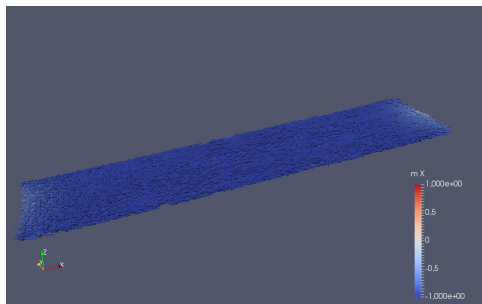


Schöberl: NGSolve Finite Element Library



Śmigaj, Betcke et al.: *ACM Trans. Math. Software*, 41, 2015

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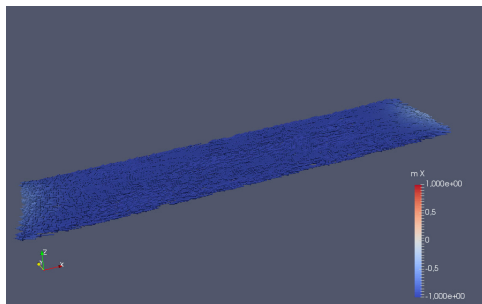


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## Numerical experiments



- FEM-part  $\rightsquigarrow$  Netgen/NGSolve
- BEM-part  $\rightsquigarrow$  BEM++

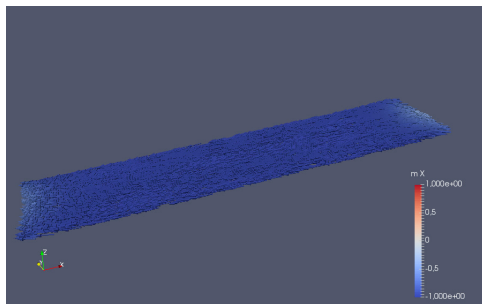


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## Model problem

### LLG equation

- $\partial_t \mathbf{m} = -\mathbf{m} \times \mathbf{h}_{\text{eff}} + \alpha \mathbf{m} \times \partial_t \mathbf{m}$  in  $\Omega_T := (0, T) \times \Omega$
- $\partial_{\mathbf{n}} \mathbf{m} = 0$  on  $(0, T) \times \partial\Omega$
- $\mathbf{m}(0) = \mathbf{m}^0$  on  $\Omega$ ,  $|\mathbf{m}^0| = 1$  on  $\Omega$

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  - $\partial_t \mathbf{m} \cdot \mathbf{m} = 0 \iff \frac{1}{2} \frac{d}{dt} |\mathbf{m}|^2 = 0$  in  $\Omega_T \implies |\mathbf{m}| = 1$  in  $\Omega_T$

## Challenges

- Non-linear PDE
- Non-convex constraint  $|m| = 1$
- Stray field leads to coupled problem on  $\mathbb{R}^3 \rightsquigarrow$  embedded problem



Carbou, Fabrie: *Differential Integral Equations* 5, 2001



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- Non-linear PDE
- Non-convex constraint  $|m| = 1$
- Stray field leads to coupled problem on  $\mathbb{R}^3 \rightsquigarrow$  embedded problem
- Weak-strong uniqueness property of LLG:
  - Ex. unique strong solution up to some  $T^* > 0$
  - Ex. global weak solution, uniqueness may fail
  - Weak solution is unique up to  $T^*$



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# Numerical integrator

## Time and space discretization

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- Space discretization:
  - Piecewise affine functions in every dimension  $\rightsquigarrow \mathbf{V}_h$
  - $|\varphi_h(z)| = 1$  for all nodes  $\rightsquigarrow \mathcal{M}_h$

## Midpoint scheme

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### Algorithm (Bartels, Prohl, '06)

- Input:  $\mathbf{m}_h^0 \in \mathcal{M}_h$ .
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## Midpoint with full effective field

### System at each time step

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Bartels, Prohl: *SIAM J. Numer. Anal.*, 44, 2006

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- Solve non-linear system for every time-step  $\rightsquigarrow$  fixed-point iteration



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- Solve non-linear system for every time-step  $\rightsquigarrow$  fixed-point iteration
- Evaluate  $\boldsymbol{\pi}_h(\cdot)$  in every iteration  $\rightsquigarrow$  FEM-BEM problem



Bartels, Prohl: *SIAM J. Numer. Anal.*, 44, 2006

## Midpoint with full effective field

### System at each time step

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- Solve non-linear system for every time-step  $\rightsquigarrow$  fixed-point iteration
- Evaluate  $\boldsymbol{\pi}_h(\cdot)$  in every iteration  $\rightsquigarrow$  FEM-BEM problem



Bartels, Prohl: *SIAM J. Numer. Anal.*, 44, 2006

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- Well-defined  $\rightsquigarrow$  Brouwer fixed-point theorem

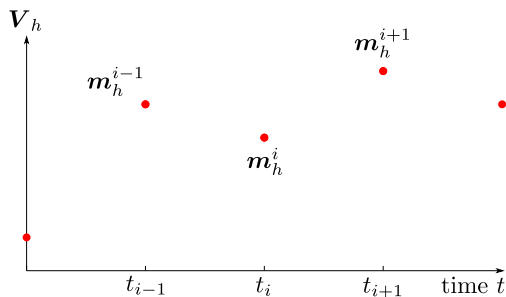


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# Main result

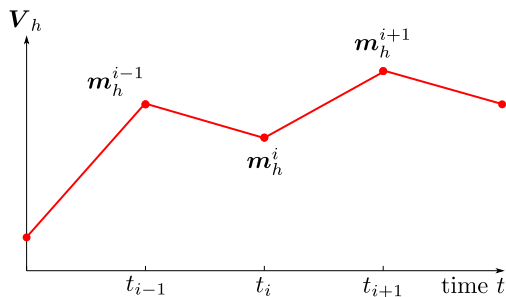
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- Output:  $\mathbf{m}_{hk} \in \mathbf{H}^1(\Omega_T)$

## Main result

- Assumptions:
  - $\mathbf{m}_h^0 \rightarrow \mathbf{m}^0$  in  $\mathbf{H}^1(\Omega)$  as  $h \rightarrow 0$
  - $\pi_h(\mathbf{m}_h^{i+1}, \mathbf{m}_h^i, \mathbf{m}_h^{i-1}) \rightarrow \pi(\mathbf{m}(t_i))$  in  $\mathbf{L}^2(\Omega)$  as  $h \rightarrow 0$

### Theorem (Praetorius, Ruggeri, S.' 16)

Ex.  $\mathbf{m} \in \mathbf{H}^1(\Omega_T)$  s.t.

- ex. subsequence with  $\mathbf{m}_{hk} \rightharpoonup \mathbf{m}$  in  $\mathbf{H}^1(\Omega_T)$  **unconditionally**
- $\mathbf{m}$  is a weak solution of LLG

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- Other couplings: Maxwell-LLG (?), Spin-Diffusion-LLG (?)

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- **New approach:**  $\pi_h : \mathbf{V}_h^3 \rightarrow \mathbf{V}_h$ 
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- **Unconditionally** convergent numerical integrator
- Same technique on ELLG  $\rightsquigarrow$  Decoupled system

# Thanks for listening!

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## Weak solution of LLG

### LLG equation

- $\partial_t \mathbf{m} = -\mathbf{m} \times (C_{\text{ex}} \Delta \mathbf{m} + \mathbf{f} + \boldsymbol{\pi}(\mathbf{m})) + \alpha \mathbf{m} \times \partial_t \mathbf{m}$

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