

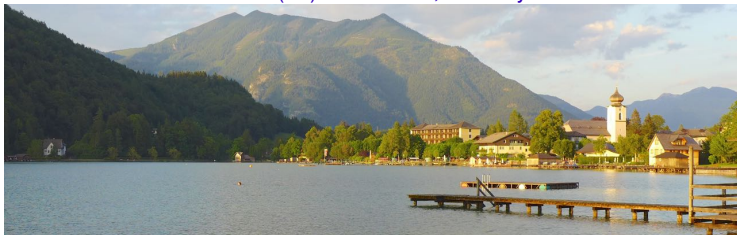
Approximation of the LBB constant on corner domains






Martin Costabel

Collaboration with Monique Dauge, Michel Crouzeix,
Christine Bernardi, Vivette Girault, Yvon Lafranche

IRMAR, Université de Rennes 1

AANMPDE(JS)-9-16 Strobl, 4–8 July 2016



-  M. DAUGE, C. BERNARDI, M. COSTABEL, V. GIRAULT
On Friedrichs constant and Horgan-Payne angle for LBB condition
Monogr. Mat. Garcia Galdeano, 39 (2014), 87–100.
-  M. COSTABEL, M. DAUGE
On the inequalities of Babuška–Aziz, Friedrichs and Horgan–Payne
Arch. Rational Mech. Anal. 217(3) (2015), 873–898.
-  M. COSTABEL, M. CROUZEIX, M. DAUGE, Y. LAFRANCHE
The inf-sup constant for the divergence on corner domains
Numer. Methods Partial Differential Equations 31(2) (2015), 439–458.
-  M. COSTABEL
Inequalities of Babuška–Aziz and Friedrichs–Velte for differential forms.
arXiv:1507.08464, to appear in Operator Theory, Advances and Applications
-  C. BERNARDI, M. COSTABEL, M. DAUGE, V. GIRAULT
Continuity properties of the inf-sup constant for the divergence
SIAM J. Math. Anal., 48 (2016), pp. 1250–1271.

- Ω **bounded** domain in \mathbb{R}^d ($d \geq 1$). **No regularity assumptions.**

The inf-sup constant of Ω

$$\beta(\Omega) = \inf_{q \in L^2_0(\Omega)} \sup_{\mathbf{v} \in H_0^1(\Omega)^d} \frac{\int_{\Omega} \operatorname{div} \mathbf{v} q}{\|\mathbf{v}\|_1 \|q\|_0}$$

- $L^2(\Omega)$ space of square integrable functions q on Ω . Norm $\|q\|_0$
- $H^1(\Omega)$ Sobolev space of $v \in L^2(\Omega)$ with gradient $\nabla v \in L^2(\Omega)^d$
- $L^2_0(\Omega)$ subspace of $q \in L^2(\Omega)$ with $\int_{\Omega} q = 0$.
- $H_0^1(\Omega)$ closure in $H^1(\Omega)$ of $C_0^\infty(\Omega)$ (zero trace on $\partial\Omega$)
- (Semi-)Norm $\|\mathbf{v}\|_1 = \|\nabla \mathbf{v}\|_0$ equivalent to norm $\|\mathbf{v}\|_{H^1(\Omega)}$
- $0 < \beta(\Omega) \leq 1$
- $\beta(\Omega)$ is invariant with respect to translations, rotations, dilations.
- We will often talk about $\alpha(\Omega) = \beta(\Omega)^2$ instead of $\beta(\Omega)$.

- Ω **bounded** domain in \mathbb{R}^d ($d \geq 1$). **No regularity assumptions.**

The inf-sup constant of Ω

$$\beta(\Omega) = \inf_{q \in L^2_0(\Omega)} \sup_{\mathbf{v} \in H^1_0(\Omega)^d} \frac{\int_{\Omega} \operatorname{div} \mathbf{v} q}{|\mathbf{v}|_1 \|q\|_0}$$

- $L^2(\Omega)$ space of square integrable functions q on Ω . Norm $\|q\|_0$
- $H^1(\Omega)$ Sobolev space of $v \in L^2(\Omega)$ with gradient $\nabla v \in L^2(\Omega)^d$
- $L^2_0(\Omega)$ subspace of $q \in L^2(\Omega)$ with $\int_{\Omega} q = 0$.
- $H^1_0(\Omega)$ closure in $H^1(\Omega)$ of $C_0^\infty(\Omega)$ (zero trace on $\partial\Omega$)
(Semi-)Norm $|\mathbf{u}|_1 = \|\nabla \mathbf{u}\|_0$ equivalent to norm $\|\mathbf{u}\|_{H^1(\Omega)}$

- $0 < \beta(\Omega) < \infty$
- $\beta(\Omega)$ is invariant with respect to translations, rotations, dilations.
- We will often talk about $\alpha(\Omega) = \beta(\Omega)^2$ instead of $\beta(\Omega)$.

- Ω **bounded** domain in \mathbb{R}^d ($d \geq 1$). **No regularity assumptions.**

The inf-sup constant of Ω

$$\beta(\Omega) = \inf_{q \in L^2_0(\Omega)} \sup_{\mathbf{v} \in H_0^1(\Omega)^d} \frac{\int_{\Omega} \operatorname{div} \mathbf{v} q}{|\mathbf{v}|_1 \|q\|_0}$$

- $L^2(\Omega)$ space of square integrable functions q on Ω . Norm $\|q\|_0$
- $H^1(\Omega)$ Sobolev space of $v \in L^2(\Omega)$ with gradient $\nabla v \in L^2(\Omega)^d$
- $L^2_0(\Omega)$ subspace of $q \in L^2(\Omega)$ with $\int_{\Omega} q = 0$.
- $H_0^1(\Omega)$ closure in $H^1(\Omega)$ of $C_0^\infty(\Omega)$ (zero trace on $\partial\Omega$)
(Semi-)Norm $|\mathbf{u}|_1 = \|\nabla \mathbf{u}\|_0$ equivalent to norm $\|\mathbf{u}\|_{H^1(\Omega)}$
- $0 \leq \beta(\Omega) \leq 1$.

• $\beta(\Omega)$ is invariant with respect to translations, rotations, dilations.

• We will often talk about $\alpha(\Omega) = \beta(\Omega)^2$ instead of $\beta(\Omega)$.

- Ω **bounded** domain in \mathbb{R}^d ($d \geq 1$). **No regularity assumptions.**

The inf-sup constant of Ω

$$\beta(\Omega) = \inf_{q \in L^2_0(\Omega)} \sup_{\mathbf{v} \in H_0^1(\Omega)^d} \frac{\int_{\Omega} \operatorname{div} \mathbf{v} q}{|\mathbf{v}|_1 \|q\|_0}$$

- $L^2(\Omega)$ space of square integrable functions q on Ω . Norm $\|q\|_0$
- $H^1(\Omega)$ Sobolev space of $v \in L^2(\Omega)$ with gradient $\nabla v \in L^2(\Omega)^d$
- $L^2_0(\Omega)$ subspace of $q \in L^2(\Omega)$ with $\int_{\Omega} q = 0$.
- $H_0^1(\Omega)$ closure in $H^1(\Omega)$ of $C_0^\infty(\Omega)$ (zero trace on $\partial\Omega$)
(Semi-)Norm $|\mathbf{u}|_1 = \|\nabla \mathbf{u}\|_0$ equivalent to norm $\|\mathbf{u}\|_{H^1(\Omega)}$
- $0 \leq \beta(\Omega) \leq 1$.
- $\beta(\Omega)$ is invariant with respect to translations, rotations, dilations.

• We will often talk about $\alpha(\Omega) = \beta(\Omega)^2$ instead of $\beta(\Omega)$.

- Ω **bounded** domain in \mathbb{R}^d ($d \geq 1$). **No regularity assumptions.**

The inf-sup constant of Ω

$$\beta(\Omega) = \inf_{q \in L^2_0(\Omega)} \sup_{\mathbf{v} \in H_0^1(\Omega)^d} \frac{\int_{\Omega} \operatorname{div} \mathbf{v} q}{|\mathbf{v}|_1 \|q\|_0}$$

- $L^2(\Omega)$ space of square integrable functions q on Ω . Norm $\|q\|_0$
- $H^1(\Omega)$ Sobolev space of $v \in L^2(\Omega)$ with gradient $\nabla v \in L^2(\Omega)^d$
- $L^2_0(\Omega)$ subspace of $q \in L^2(\Omega)$ with $\int_{\Omega} q = 0$.
- $H_0^1(\Omega)$ closure in $H^1(\Omega)$ of $C_0^\infty(\Omega)$ (zero trace on $\partial\Omega$)
(Semi-)Norm $|\mathbf{u}|_1 = \|\nabla \mathbf{u}\|_0$ equivalent to norm $\|\mathbf{u}\|_{H^1(\Omega)}$
- $0 \leq \beta(\Omega) \leq 1$.
- $\beta(\Omega)$ is invariant with respect to translations, rotations, dilations.
- We will often talk about $\sigma(\Omega) = \beta(\Omega)^2$ instead of $\beta(\Omega)$.

The inf-sup condition or LBB condition

$$\beta(\Omega) > 0$$

Find $\mathbf{u} \in H_0^1(\Omega)^d, p \in L_0^2(\Omega)$:

$$\begin{aligned} -\Delta \mathbf{u} + \nabla p &= \mathbf{f} && \text{in } \Omega \\ \operatorname{div} \mathbf{u} &= g && \text{in } \Omega \end{aligned}$$

The mapping $(\mathbf{u}, p) \mapsto (\mathbf{f}, g) : H_0^1(\Omega)^d \times L_0^2(\Omega) \rightarrow H^{-1}(\Omega)^d \times L_0^2(\Omega)$ is an isomorphism if and only if $\beta(\Omega) > 0$.

Proved (more or less) by L. Gallabriga (1961) for smooth domains
Standard reference:

V. Girault, A. Raviart: Finite Element Methods for Navier-Stokes Equations,
Springer 1986

The inf-sup condition or LBB condition

$$\beta(\Omega) > 0$$

Classical:

This is **true** for **bounded Lipschitz** domains.

Not true for domains with **outward cusps**.

Find $u \in H_0^1(\Omega)^d, p \in L_0^2(\Omega)$:

$$-\Delta u + \nabla p = f \quad \text{in } \Omega$$

$$\operatorname{div} u = g \quad \text{in } \Omega$$

The mapping $(u, p) \mapsto (f, g) : H_0^1(\Omega)^d \times L_0^2(\Omega) \rightarrow H^{-1}(\Omega)^d \times L_0^2(\Omega)$ is an isomorphism if and only if $\beta(\Omega) > 0$.

The inf-sup condition or LBB condition

$$\beta(\Omega) > 0$$

Now known [Acosta et al, 2006–2016]: For bounded domains, this is basically **equivalent** to Ω being a **John domain**.
(More general than Lipschitz [▶ Digression: John domains](#)).

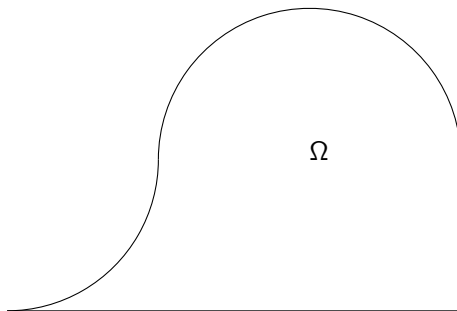


Figure: **Not a John domain**: Outward cusp, $\beta(\Omega) = 0$ [Friedrichs 1937]

The inf-sup condition or LBB condition

$$\beta(\Omega) > 0$$

The complete Stokes system

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$:

$$\begin{aligned} -\Delta \mathbf{u} + \nabla p &= \mathbf{f} & \text{in } \Omega \\ \operatorname{div} \mathbf{u} &= g & \text{in } \Omega \end{aligned}$$

Theorem

The mapping $(\mathbf{u}, p) \mapsto (\mathbf{f}, g) : H_0^1(\Omega)^d \times L_0^2(\Omega) \rightarrow H^{-1}(\Omega)^d \times L_0^2(\Omega)$ is an **isomorphism** if and only if $\beta(\Omega) > 0$.

Proved (more or less) by **L. Cattabriga (1961)** for smooth domains
Standard reference:

V. Girault, A. Raviart: Finite Element Methods for Navier-Stokes Equations, Springer 1986

LBB

From Wikipedia, the free encyclopedia

LBB may stand for:

- *Lactobacillus delbrueckii subsp. bulgaricus*, a bacterium used in the production of yogurt.
- **Lubbock Preston Smith International Airport**, the IATA code
- Little Brown Bird - birdwatchers acronym for indistinct or unknown small dark **bird**
- Liberty Bible dataBase (.lbb file extension)
- **Ladyzhenskaya-Babuska-Brezzi** conditions for stability in mixed finite element analysis

Since ~1980, the inf-sup condition for the divergence is often called LBB condition, after

- Ladyzhenskaya [Added by J. T. Oden in 1980, on suggestion by J.L. Lions]
- Babuška [Babuška 1971-73]
- Brezzi [Brezzi 1974]

Let $X_N \subset X = H_0^1(\Omega)^d$ and $M_N \subset M = L_0^2(\Omega)$ be sequences of closed subspaces.

Since ~ 1980 , the **inf-sup condition** for the divergence is often called **LBB condition**, after

- **Ladyzhenskaya** Added by J. T. Oden ca 1980, on suggestion by J.-L. Lions
- **Babuška** [Babuška 1971-73]
- **Brezzi** [Brezzi 1974]

Let $X_N \subset X = H_0^1(\Omega)^d$ and $M_N \subset M = L_0^2(\Omega)$ be sequences of closed subspaces. Define

$$\beta_N = \inf_{q \in M_N} \sup_{v \in X_N} \frac{\int_{\Omega} \operatorname{div} v \, q}{\|v\|_X \|q\|_M}$$

The uniform discrete inf-sup condition

$$\beta_N(\Omega) \geq \beta_* > 0 \quad \forall N$$

is also simply called **Babuška-Brezzi condition** or **LBB condition**.

Stability and convergence of finite element methods for the Stokes system.

Since ~ 1980 , the **inf-sup condition** for the divergence is often called **LBB condition**, after

- **Ladyzhenskaya** Added by J. T. Oden ca 1980, on suggestion by J.-L. Lions
- **Babuška** [Babuška 1971-73]
- **Brezzi** [Brezzi 1974]

Discrete LBB condition

Let $X_N \subset X = H_0^1(\Omega)^d$ and $M_N \subset M = L_0^2(\Omega)$ be sequences of closed subspaces. Define

$$\beta_N = \inf_{q \in M_N} \sup_{\mathbf{v} \in X_N} \frac{\int_{\Omega} \operatorname{div} \mathbf{v} q}{|\mathbf{v}|_1 \|q\|_0}$$

The **uniform discrete inf-sup condition**

$$\beta_N(\Omega) \geq \beta_* > 0 \quad \forall N$$

is also simply called **Babuška-Brezzi condition** or **LBB condition**.

Application

Stability and convergence of finite element methods for the Stokes system.

Why is it important to know the $\beta(\Omega)$?

The Stokes system of incompressible fluid dynamics for $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = \mathbf{f} & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = 0 & \text{in } \Omega \end{array}$$

has the variational form

$$\begin{aligned} \langle \nabla \mathbf{u}, \nabla \mathbf{v} \rangle - \langle \operatorname{div} \mathbf{v}, p \rangle &= \langle \mathbf{v}, \mathbf{f} \rangle \quad \forall \mathbf{v} \in H_0^1(\Omega)^d \\ \langle \operatorname{div} \mathbf{u}, q \rangle &= 0 \quad \forall q \in L_0^2(\Omega) \end{aligned}$$

Pressure Stability for the Stokes problem

$$\begin{aligned} \|\mathbf{u}\|_1 &\leq \|\mathbf{f}\|_{-1} \\ \|p\|_0 &\leq \frac{1}{\beta(\Omega)} \|\mathbf{f}\|_{-1} \end{aligned}$$

Also: Error reduction factor for iterative algorithms such as Uzawa.

- 1 History of this circle of ideas
- 2 Review of basic properties
- 3 Approximation problems
- 4 Corner domains

- 1898-1901 E.&F. Cosserat: 9 papers in CR Acad Sci Paris
- 1924 L. Lichtenstein: a boundary integral equation method
- 1967 V. Maz'ya – S. Mikhlin: “On the Cosserat spectrum. . .”
- 1973 S. Mikhlin: “The spectrum of an operator pencil. . .”

- 1993-1999 A. Kozhevnikov: Cosserat EV distribution, 100 years of history

- 1898-1901 E.&F. Cosserat: 9 papers in CR Acad Sci Paris
- 1924 L. Lichtenstein: a boundary integral equation method
- 1967 V. Maz'ya – S. Mikhlin: “On the Cosserat spectrum. . .”
- 1971 I. Babuška – A.K. Aziz: Foundations of FEM
- 1973 S. Mikhlin: “The spectrum of an operator pencil. . .”
- 1974 F. Brezzi: “...saddle point problems...”

- 1993-1999 A. Kozhevnikov: Cosserat EV distribution, 100 years of history

- 1898-1901 E.&F. Cosserat: 9 papers in CR Acad Sci Paris
- 1909 A. Korn: Korn's inequality
- 1924 L. Lichtenstein: a boundary integral equation method
- 1937 K. Friedrichs: "On certain inequalities. . ."
- 1967 V. Maz'ya – S. Mikhlin: "On the Cosserat spectrum. . ."
- 1971 I. Babuška – A.K. Aziz: Foundations of FEM
- 1973 S. Mikhlin: "The spectrum of an operator pencil. . ."
- 1974 F. Brezzi: "...saddle point problems..."
- 1983 C.O. Horgan – L.E. Payne: "On Inequalities of Korn, Friedrichs and
- 1993-1999 A. Kozhevnikov: Cosserat EV distribution, 100 years of history

- 1898-1901 E.&F. Cosserat: 9 papers in CR Acad Sci Paris
- 1909 A. Korn: Korn's inequality
- 1924 L. Lichtenstein: a boundary integral equation method
- 1937 K. Friedrichs: "On certain inequalities. . ."
- 1967 V. Maz'ya – S. Mikhlin: "On the Cosserat spectrum. . ."
- 1971 I. Babuška – A.K. Aziz: Foundations of FEM
- 1973 S. Mikhlin: "The spectrum of an operator pencil. . ."
- 1974 F. Brezzi: "...saddle point problems..."
- 1979 M.E. Bogovskiĭ: an integral operator for solving $\operatorname{div} \mathbf{u} = \mathbf{q}$
- 1983 C.O. Horgan – L.E. Payne: "On Inequalities of Korn, Friedrichs and
- 1993-1999 A. Kozhevnikov: Cosserat EV distribution, 100 years of history
- 1997 M. Crouzeix: "On the convergence of Uzawa's algorithm"
- 1990-1998 W. Velte: "On optimal constants in some inequalities"

- 1898-1901 E.&F. Cosserat: 9 papers in CR Acad Sci Paris
- 1909 A. Korn: Korn's inequality
- 1924 L. Lichtenstein: a boundary integral equation method
- 1937 K. Friedrichs: "On certain inequalities. . ."
- 1967 V. Maz'ya – S. Mikhlin: "On the Cosserat spectrum. . ."
- 1971 I. Babuška – A.K. Aziz: Foundations of FEM
- 1973 S. Mikhlin: "The spectrum of an operator pencil. . ."
- 1974 F. Brezzi: "...saddle point problems..."
- 1979 M.E. Bogovskiĭ: an integral operator for solving $\operatorname{div} \mathbf{u} = q$
- 1983 C.O. Horgan – L.E. Payne: "On Inequalities of Korn, Friedrichs and"
- 1993-1999 A. Kozhevnikov: Cosserat EV distribution, 100 years of history
- 1997 M. Crouzeix: "On the convergence of Uzawa's algorithm"
- 1990-1998 W. Velte: "On optimal constants in some inequalities"
- 1994-2000 E. Chizhonkov – M. Olshanskiĭ: "On the optimal constant in the inf-
- 1999-2009 G. Stoyan: discrete inequalities
- 2000-2004 S. Zsuppán: conformal mappings
- 2006- C. Simader – W. v. Wahl – S. Weyers: L^q , unbounded domains
- 2006- G. Acosta – R.G. Durán – M.A. Muschietti: John domains
- 2000-2016 C. Bernardi, M. Co., M. Dauge, V. Girault . . .

Ball in \mathbb{R}^d : $\sigma(\Omega) = \frac{1}{d}$ [Ellipsoids in 3D: E.&F. Cosserat 1898]

In 2D:

Ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} < 1, a < b$: $\sigma(\Omega) = \frac{a^2}{a^2 + b^2}$

Some other simple 2D domains, for example:

Annulus $a < r < 1$: $\sigma(\Omega) = \frac{1}{2} - \frac{1}{2} \sqrt{\frac{1-a^2}{1+a^2} \log 1/a}$
[Chazarain-Chazaraki 2004]

Ball in \mathbb{R}^d : $\sigma(\Omega) = \frac{1}{d}$ [Ellipsoids in 3D: E.&F. Cosserat 1898]

In 2D:

Ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} < 1, a < b$: $\sigma(\Omega) = \frac{a^2}{a^2 + b^2}$

Some other simple 2D domains, for example:

Annulus $a < r < 1$: $\sigma(\Omega) = \frac{1}{2} - \frac{1}{2} \sqrt{\frac{1-a^2}{1+a^2} \frac{1}{\log 1/a}}$
[Chizhonkov-Olshanskii 2000]

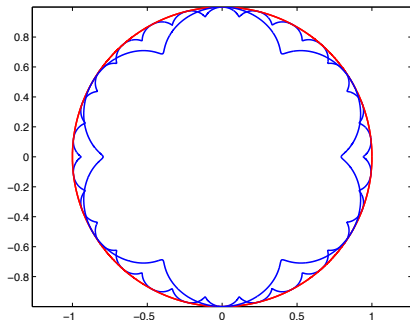
An example from [Zsuppán 2004] “Epitrochoid”

Conformal mapping $g_{m,c} : \Omega = \{z \in \mathbb{C} \mid |z| < 1\} \rightarrow \Omega_{m,c}$

$$g_{m,c}(z) = \frac{z - \frac{c}{m}z^m}{1 + \frac{c}{m}}$$

[Zsuppán 2004]

For $0 < c < 1$ and $m \in \mathbb{N}$ odd: $\beta(\Omega_{m,c})^2 = \frac{1}{2} \left(1 - \frac{m+1}{2m} c\right)$



Showing:

$\Omega_{m,c}$ for $c = 0.8$
 $m = 7$ and $m = 27$

Observation: Non-convergence

As $m \rightarrow \infty$: $g_{m,c}(z) \rightarrow z$

$\Omega_{m,c} \rightarrow \Omega$, but

$$\beta(\Omega_{m,c})^2 \rightarrow \frac{1}{2} - \frac{c}{4} \neq \frac{1}{2} = \beta(\Omega)^2$$

Ball

Known: $\beta(\Omega) \leq \frac{1}{\sqrt{d}}$ for any bounded domain.

Hence: For $d = 2$, the ball is optimal: β is maximal.

Unknown: For $d \geq 3$, is the ball optimal? $\beta(\Omega) \leq \frac{1}{\sqrt{d}}$?

$\beta(\square)$ is still unknown!

$$\alpha(\square) = \frac{1}{2} - \frac{1}{\pi} \approx 0.18169 \dots \quad (\rightarrow \beta(\square) = \sqrt{\frac{1}{2} - \frac{1}{\pi}} \approx 0.42625)$$

Optimality

Known: $\beta(\Omega) \leq \frac{1}{\sqrt{2}}$ for any bounded domain.

Hence: For $d = 2$, the ball is optimal: β is maximal.

Unknown: For $d \geq 3$, is the ball optimal? $\beta(\Omega) \leq \frac{1}{\sqrt{d}}$?

$\beta(\Omega)$ is still unknown !

$$\beta(\Omega) = \frac{1}{2} - \frac{1}{4} \approx 0.1875 \quad (\leftrightarrow \beta(\Omega) = \sqrt{\frac{1}{2}} - \frac{1}{4} \approx 0.42825)$$

Optimality

Known: $\beta(\Omega) \leq \frac{1}{\sqrt{2}}$ for any bounded domain.

Hence: For $d = 2$, the ball is optimal: β is maximal.

Unknown: For $d \geq 3$, is the ball optimal? $\beta(\Omega) \leq \frac{1}{\sqrt{d}}$?

The square $\Omega = (0, 1) \times (0, 1) =: \square \subset \mathbb{R}^2$

$\beta(\square)$ is still unknown !

Current Conjecture

$$\sigma(\square) = \frac{1}{2} - \frac{1}{\pi} \approx 0.18169... \quad (\rightarrow \beta(\square) = \sqrt{\frac{1}{2} - \frac{1}{\pi}} \approx 0.42625)$$

Def: $J(q) = \sup_{\mathbf{v} \in H_0^1(\Omega)^d} \frac{\langle \operatorname{div} \mathbf{v}, q \rangle}{|\mathbf{v}|_1} \quad (= |\nabla q|_{-1}, \text{ dual norm})$

Lemma: $\sup = \max$

$$J(q) = \frac{\langle \operatorname{div} \mathbf{w}(q), q \rangle}{|\mathbf{w}(q)|_1} = |\mathbf{w}(q)|_1$$

where $\mathbf{w}(q) \in H_0^1(\Omega)^d$ is the solution \mathbf{w} of the vector Dirichlet problem $\Delta \mathbf{w} = \nabla q$, or in variational form

$$\langle \nabla \mathbf{w}, \nabla \mathbf{v} \rangle = \langle \operatorname{div} \mathbf{v}, q \rangle \quad \forall \mathbf{v} \in H_0^1(\Omega)^d$$

We write

$$\mathbf{w}(q) = \Delta^{-1} \nabla q$$

Recall the Stokes system of incompressible fluid dynamics for $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$

$$\begin{aligned} -\Delta \mathbf{u} + \nabla p &= \mathbf{f} && \text{in } \Omega \\ \operatorname{div} \mathbf{u} &= 0 && \text{in } \Omega \end{aligned}$$

Definition

The **Schur complement operator** \mathcal{S} for the Stokes system is

$$\mathcal{S} = \operatorname{div} \Delta^{-1} \nabla : L_0^2 \xrightarrow{\nabla} \mathbf{H}^{-1} \xrightarrow{\Delta^{-1}} \mathbf{H}_0^1 \xrightarrow{\operatorname{div}} L_0^2$$

\mathcal{S} is a bounded positive selfadjoint operator in $L_0^2(\Omega)$.

Observation

Define

$$\sigma(\Omega) = \min \operatorname{Sp}(\mathcal{S})$$

Then

$$\sigma(\Omega) = \beta(\Omega)^2$$

Proof: $-\Delta : H_0^1(\Omega) \rightarrow H^{-1}(\Omega)$ is the Riesz isometry. For $q \in L_0^2(\Omega)$:

$$\begin{aligned} \langle \mathcal{S}q, q \rangle &= \langle \operatorname{div} \Delta^{-1} \nabla q, q \rangle \\ &= \langle -\Delta^{-1} \nabla q, \nabla q \rangle \\ &= |\nabla q|_{-1}^2 \\ &= J(q)^2 \end{aligned}$$

$$\sigma(\Omega) = \inf_{q \in L_0^2(\Omega)} \frac{\langle \mathcal{S}q, q \rangle}{\langle q, q \rangle} = \beta(\Omega)^2$$

A well known lemma

Let $A: X \rightarrow Y$ and $B: Y \rightarrow X$ be linear operators. Then

$$Sp(AB) \setminus \{0\} \equiv Sp(BA) \setminus \{0\}.$$

Recall $\mathcal{S} = \operatorname{div} \Delta^{-1} \nabla$.

The eigenvalue problem for the Schur complement of the Stokes system

$$\mathcal{S}p = \sigma p \quad \text{in } L^2_0(\Omega)$$

is, for $\sigma \neq 0$, equivalent to the eigenvalue problem

$$\Delta^{-1} \nabla \operatorname{div} u = \sigma u \quad \text{in } H_0^1(\Omega)^d$$

which is the same as

$$\sigma \Delta u = \nabla \operatorname{div} u \quad \text{in } H_0^1(\Omega)^d.$$

This is the Cosserat eigenvalue problem [E. & F. Cosserat, 1898]

A well known lemma

Let $A : X \rightarrow Y$ and $B : Y \rightarrow X$ be linear operators. Then

$$\text{Sp}(AB) \setminus \{0\} \equiv \text{Sp}(BA) \setminus \{0\}.$$

Recall $\mathcal{S} = \text{div } \Delta^{-1} \nabla$.

Corollary

The eigenvalue problem for the Schur complement of the Stokes system

$$\mathcal{S}p = \sigma p \quad \text{in } L^2_0(\Omega)$$

is, for $\sigma \neq 0$, equivalent to the eigenvalue problem

$$\Delta^{-1} \nabla \text{div } \mathbf{u} = \sigma \mathbf{u} \quad \text{in } H^1_0(\Omega)^d$$

which is the same as

$$\sigma \Delta \mathbf{u} = \nabla \text{div } \mathbf{u} \quad \text{in } H^1_0(\Omega)^d.$$

This is the **Cosserat** eigenvalue problem [E.&F. Cosserat, 1898]

Theorem [BCDG 2016]

Let $X_N \subset X = H_0^1(\Omega)^d$ and $M_N \subset M = L_0^2(\Omega)$ be sequences of closed subspaces.

If $(M_N)_N$ is asymptotically dense in M , then

$$\limsup_{N \rightarrow \infty} \beta_N \leq \beta(\Omega)$$

Proof: Recall the definition of $J(q)$ and define similarly

$$J_N(q) = \sup_{\mathbf{v} \in X_N} \frac{\langle \operatorname{div} \mathbf{v}, q \rangle}{|\mathbf{v}|_1}, \text{ so that } \beta(\Omega) = \inf_{q \in M} \frac{J(q)}{\|q\|_0} \text{ and } \beta_N = \inf_{q_N \in M_N} \frac{J_N(q_N)}{\|q_N\|_0}$$

Now for $q \in M$ given, choose $q_N \in M_N$ so that $q_N \rightarrow q$ in $L_0^2(\Omega)$. Then one has

$$\beta_N \leq \frac{J_N(q_N)}{\|q_N\|_0} \leq \frac{J(q_N)}{\|q_N\|_0} \rightarrow \frac{J(q)}{\|q\|_0}$$

Now assume that $\beta_N \rightarrow \beta_\infty$. Then $\beta_\infty \leq \frac{J(q)}{\|q\|_0}$ for any $q \in M$ and, taking the inf, finally $\beta_\infty \leq \beta(\Omega)$.

A simple case where convergence holds

In general, one can have $\beta_N \leq \beta(\Omega)$ or $\beta_N \geq \beta(\Omega)$.
No general criterion known.

$$\text{if } X_N = \Delta^{-1} \nabla M_N, \quad \text{then } \beta_N \geq \beta(\Omega).$$

Thus, if one knows a basis $(q_n)_{n \in N}$ of $L^2_0(\Omega)$ for which the Dirichlet problem for $w_n \in H^1_0(\Omega)^d$

$$\Delta w_n = \nabla q_n$$

can be solved exactly, setting

$$M_N = \text{span}\{q_1, \dots, q_N\}, \quad X_N = \text{span}\{w_1, \dots, w_N\}$$

leads to

$$\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega).$$

Proof: One has now $J_N(q) = J(q)$ for $q \in M_N$.

In other words, this is a Galerkin eigenvalue approximation of the exact Schur complement operator \mathcal{S} . In general cases, Δ^{-1} will have to be approximated, too.

A simple case where convergence holds

In general, one can have $\beta_N \leq \beta(\Omega)$ or $\beta_N \geq \beta(\Omega)$.
No general criterion known.

Exception

If $X_N = \Delta^{-1} \nabla M_N$, then $\beta_N \geq \beta(\Omega)$.

Thus, if one knows a basis $(q_n)_{n \in \mathbb{N}}$ of $L^2_0(\Omega)$ for which the Dirichlet problem for $\mathbf{w}_n \in H^1_0(\Omega)^d$

$$\Delta \mathbf{w}_n = \nabla q_n$$

can be solved exactly, setting

$$M_N = \text{span}\{q_1, \dots, q_N\}, \quad X_N = \text{span}\{\mathbf{w}_1, \dots, \mathbf{w}_N\}$$

leads to

$$\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega).$$

Proof: One has now $J_N(q) = J(q)$ for $q \in M_N$.
In other words, this is a Galerkin eigenvalue approximation of the exact Schur complement operator \mathcal{S} . In general cases, $\Delta^{-1} \nabla$ will have to be approximated, too.

In general, one can have $\beta_N \leq \beta(\Omega)$ or $\beta_N \geq \beta(\Omega)$.
No general criterion known.

Exception

If $X_N = \Delta^{-1} \nabla M_N$, then $\beta_N \geq \beta(\Omega)$.

Thus, if one knows a basis $(q_n)_{n \in \mathbb{N}}$ of $L^2_0(\Omega)$ for which the Dirichlet problem for $\mathbf{w}_n \in H^1_0(\Omega)^d$

$$\Delta \mathbf{w}_n = \nabla q_n$$

can be solved exactly, setting

$$M_N = \text{span}\{q_1, \dots, q_N\}, \quad X_N = \text{span}\{\mathbf{w}_1, \dots, \mathbf{w}_N\}$$

leads to

$$\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega).$$

Proof: One has now $J_N(q) = J(q)$ for $q \in M_N$.

In other words, this is a Galerkin eigenvalue approximation of the exact Schur complement operator. In general cases, β_N will have to be approximated, too.

A simple case where convergence holds

In general, one can have $\beta_N \leq \beta(\Omega)$ or $\beta_N \geq \beta(\Omega)$.

No general criterion known.

Exception

If $X_N = \Delta^{-1} \nabla M_N$, then $\beta_N \geq \beta(\Omega)$.

Thus, if one knows a basis $(q_n)_{n \in \mathbb{N}}$ of $L^2_0(\Omega)$ for which the Dirichlet problem for $\mathbf{w}_n \in H^1_0(\Omega)^d$

$$\Delta \mathbf{w}_n = \nabla q_n$$

can be solved exactly, setting

$$M_N = \text{span}\{q_1, \dots, q_N\}, \quad X_N = \text{span}\{\mathbf{w}_1, \dots, \mathbf{w}_N\}$$

leads to

$$\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega).$$

Proof: One has now $J_N(q) = J(q)$ for $q \in M_N$.

In other words, this is a Galerkin eigenvalue approximation of the exact Schur complement operator \mathcal{S} . In general cases, Δ^{-1} will have to be approximated, too.

[M. Gaultier, M. Lezaun 1996] Let $\Omega = (0, a) \times (0, b)$. Then

$$q_{km}(x, y) = \cos(\kappa x) \cos(\mu y), \quad \kappa = \frac{k\pi}{a}, \mu = \frac{m\pi}{b}, \quad k, m \geq 0, k + m > 0$$

defines an orthogonal basis of $L^2_{\circ}(\Omega)$. The Schur complement operator $\mathcal{S} = \operatorname{div} \Delta^{-1} \nabla = \partial_x \Delta^{-1} \partial_x + \partial_y \Delta^{-1} \partial_y$ can be computed analytically by solving 1D Dirichlet problems on $(0, a)$ and $(0, b)$

$$\mathcal{S} q_{km} = -\kappa^2 \cos \kappa x (\partial_y^2 - \kappa^2)^{-1} [\cos \mu y] - \mu^2 \cos \mu y (\partial_x^2 - \mu^2)^{-1} [\cos \kappa x]$$

[M. Gaultier, M. Lezaun 1996] Let $\Omega = (0, a) \times (0, b)$. Then

$$q_{km}(x, y) = \cos(\kappa x) \cos(\mu y), \quad \kappa = \frac{k\pi}{a}, \mu = \frac{m\pi}{b}, \quad k, m \geq 0, k + m > 0$$

defines an orthogonal basis of $L^2_{\circ}(\Omega)$. The Schur complement operator $\mathcal{S} = \operatorname{div} \Delta^{-1} \nabla = \partial_x \Delta^{-1} \partial_x + \partial_y \Delta^{-1} \partial_y$ can be computed analytically by solving 1D Dirichlet problems on $(0, a)$ and $(0, b)$

$$\mathcal{S} q_{km} = -\kappa^2 \cos \kappa x (\partial_y^2 - \kappa^2)^{-1} [\cos \mu y] - \mu^2 \cos \mu y (\partial_x^2 - \mu^2)^{-1} [\cos \kappa x]$$

Numerical results. — We have performed a few numerical tests. Let K be a positive integer. We have computed an approximate value of the smallest eigenvalue α_K of the matrix A_K by means of the power of Mises [2, pp. 226-227]. We stopped this calculation when the relative error was less than 10^{-9} . We have ascertained that sequence $\{\alpha_K\}_{K>0}$ converges quickly.

The above mentioned values of the constant $P(\Omega)^{-1}$ have been rounded up to the 3-th decimal place.

$$L = 1, \quad \ell = 1 : P(\Omega)^{-1} = 0.226$$

$$L = 2, \quad \ell = 1 : P(\Omega)^{-1} = 0.151$$

$$L = 4, \quad \ell = 1 : P(\Omega)^{-1} = 0.047.$$

[M. Gaultier, M. Lezaun 1996] Let $\Omega = (0, a) \times (0, b)$. Then

$$q_{km}(x, y) = \cos(\kappa x) \cos(\mu y), \quad \kappa = \frac{k\pi}{a}, \mu = \frac{m\pi}{b}, \quad k, m \geq 0, k + m > 0$$

defines an orthogonal basis of $L^2_{\circ}(\Omega)$. The Schur complement operator $\mathcal{S} = \operatorname{div} \Delta^{-1} \nabla = \partial_x \Delta^{-1} \partial_x + \partial_y \Delta^{-1} \partial_y$ can be computed analytically by solving 1D Dirichlet problems on $(0, a)$ and $(0, b)$

$$\mathcal{S} q_{km} = -\kappa^2 \cos \kappa x (\partial_y^2 - \kappa^2)^{-1} [\cos \mu y] - \mu^2 \cos \mu y (\partial_x^2 - \mu^2)^{-1} [\cos \kappa x]$$

Numerical results. — We have performed a few numerical tests. Let K be a positive integer. We have computed an approximate value of the smallest eigenvalue α_K of the matrix A_K by means of the power of Mises [2, pp. 226-227]. We stopped this calculation when the relative error was less than 10^{-9} . We have ascertained that sequence $\{\alpha_K\}_{K>0}$ converges quickly.

The above mentioned values of the constant $P(\Omega)^{-1}$ have been rounded up to the 3-th decimal place.

$$L = 1, \quad \ell = 1 : P(\Omega)^{-1} = 0.226$$

$$L = 2, \quad \ell = 1 : P(\Omega)^{-1} = 0.151$$

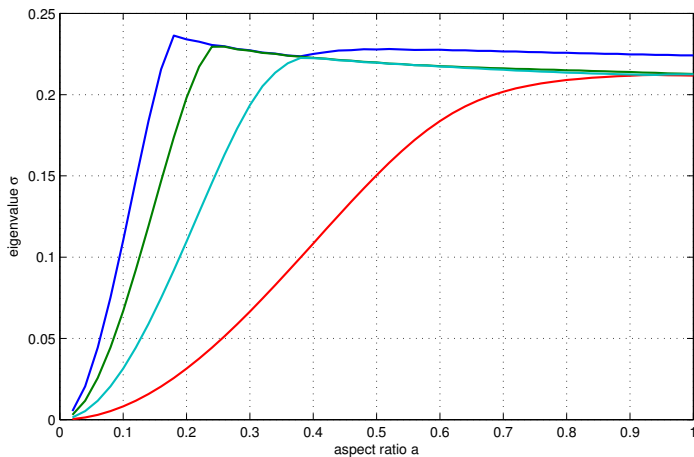
$$L = 4, \quad \ell = 1 : P(\Omega)^{-1} = 0.047.$$

$$(L, \ell) = (a, b)$$

$$K = N$$

$$P(\Omega)^{-1} = \sigma(\Omega) = \beta(\Omega)^2$$

The rectangle: First 4 Cosserat eigenvalues, Gaultier-Lezaun method



Cosserat eigenvalue problem

Find $\mathbf{u} \in H_0^1(\Omega)^d \setminus \{0\}$, $\sigma \in \mathbb{C}$ such that

$$\sigma \Delta \mathbf{u} - \nabla \operatorname{div} \mathbf{u} = 0.$$

The Cosserat eigenvalue problem is a Stokes eigenvalue problem

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega) \setminus \{0\}$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = 0 & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = \sigma p & \text{in } \Omega \end{array}$$

Variational form: Find $\mathbf{u} \in X$, $p \in M$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} (\nabla \mathbf{u}, \nabla \mathbf{v}) - (\operatorname{div} \mathbf{u}, \mathbf{q}) = 0 & \forall \mathbf{v} \in X \\ (\operatorname{div} \mathbf{u}, \mathbf{q}) - \sigma(p, \mathbf{q}) = 0 & \forall \mathbf{q} \in M \end{array}$$

Galerkin discretization: $X \hookrightarrow X_h$, $M \hookrightarrow M_h \implies \min \sigma = \beta_h^2$

Cosserat eigenvalue problem

Find $\mathbf{u} \in H_0^1(\Omega)^d \setminus \{0\}$, $\sigma \in \mathbb{C}$ such that

$$\sigma \Delta \mathbf{u} - \nabla \operatorname{div} \mathbf{u} = 0.$$

The Cosserat eigenvalue problem is a Stokes eigenvalue problem

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega) \setminus \{0\}$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = 0 & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = \sigma p & \text{in } \Omega \end{array}$$

Variational form: Find $\mathbf{u} \in X$, $p \in M$, $\sigma \in \mathbb{C}$:

$$\begin{aligned} \langle \nabla \mathbf{u}, \nabla \mathbf{v} \rangle - \langle \operatorname{div} \mathbf{v}, p \rangle &= 0 & \forall \mathbf{v} \in X \\ \langle \operatorname{div} \mathbf{u}, q \rangle &= \sigma \langle p, q \rangle & \forall q \in M \end{aligned}$$

Galerkin discretization: $X \rightsquigarrow X_N$, $M \rightsquigarrow M_N \implies \min \sigma = \beta_N^2$

Stokes eigenvalue problem, first kind

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = \sigma \mathbf{u} & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = 0 & \text{in } \Omega \end{array}$$

Stokes eigenvalue problem, second kind

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = 0 & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = \sigma p & \text{in } \Omega \end{array}$$

- 1st kind:
 - Appears in dynamic problems (time stepping, Laplace transform)
 - Elliptic eigenvalue problem, compact resolvent.
 - Known conditions for convergence of numerical algorithms (discrete LBB condition...)
- 2nd kind:
 - Provides the (continuous and discrete) inf-sup constant:
 $\beta_h^2 = \min_{\mathbf{u}_h, p_h} \sigma_h(\mathbf{u}_h, p_h)$
 - Not an elliptic eigenvalue problem
 - Not covered by any general theory of numerical approximation of eigenvalue problems
- Both eigenvalue problems are discretized with the same code
- Standard code available: Stokes + matrix eigenvalue problem

Stokes eigenvalue problem, first kind

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = \sigma \mathbf{u} & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = 0 & \text{in } \Omega \end{array}$$

Stokes eigenvalue problem, second kind

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = 0 & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = \sigma p & \text{in } \Omega \end{array}$$

1st kind:

- Appears in dynamic problems (time stepping, Laplace transform)
- Elliptic eigenvalue problem, compact resolvent,
- Known conditions for convergence of numerical algorithms
(discrete LBB condition...)

2nd kind:

- Provides the (continuous and discrete) inf-sup constant:
 $\beta_N^2 = \min \sigma_{X_N, M_N}$
- Not an elliptic eigenvalue problem
- Not covered by any general theory of numerical approximation of eigenvalue problems

- Both eigenvalue problems are discretized with the same code
- Standard code available: Stokes + matrix eigenvalue problem

Stokes eigenvalue problem, first kind

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = \sigma \mathbf{u} & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = 0 & \text{in } \Omega \end{array}$$

Stokes eigenvalue problem, second kind

Find $\mathbf{u} \in H_0^1(\Omega)^d$, $p \in L_0^2(\Omega)$, $\sigma \in \mathbb{C}$:

$$\begin{array}{ll} -\Delta \mathbf{u} + \nabla p = 0 & \text{in } \Omega \\ \operatorname{div} \mathbf{u} = \sigma p & \text{in } \Omega \end{array}$$

1st kind:

- Appears in dynamic problems (time stepping, Laplace transform)
- Elliptic eigenvalue problem, compact resolvent,
- Known conditions for convergence of numerical algorithms
(discrete LBB condition...)

2nd kind:

- Provides the (continuous and discrete) inf-sup constant:
 $\beta_N^2 = \min \sigma_{X_N, M_N}$
- Not an elliptic eigenvalue problem
- Not covered by any general theory of numerical approximation of eigenvalue problems

- Both eigenvalue problems are discretized with the same code!
- Standard code available: Stokes + matrix eigenvalue problem

A general approximation result: **Convergence**

We now assume two conditions for the function spaces, with some s satisfying $0 < s < \frac{1}{2}$

- 1 An **inverse inequality** for M_N

$$\forall q \in M_N : \|q\|_s \leq \eta_{N,s} \|q\|_0$$

- 2 An **approximation property** for X_N

$$\forall \mathbf{u} \in H^{1+s}(\Omega) \cap H_0^1(\Omega) : \inf_{\mathbf{v} \in X_N} \|\mathbf{u} - \mathbf{v}\|_1 \leq \varepsilon_{N,s} \|\mathbf{u}\|_{1+s}$$

Theorem [BCDG 2016]

Let Ω have H^{1+s} regularity for the Dirichlet problem for some $0 < s < \frac{1}{2}$, with an estimate

$$\|\Delta^{-1}\|_{H^{-1+s} \rightarrow H^{1+s}} \leq C_s$$

and let conditions 1 and 2 be satisfied. Then

$$\beta_N \geq \beta(\Omega) - C_s \eta_{N,s} \varepsilon_{N,s}.$$

In particular, if $\eta_{N,s} \varepsilon_{N,s} \rightarrow 0$ and M_N is asymptotically dense, then

$$\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega).$$

Proof. For $q \in M_N$, let $\mathbf{w} = \Delta^{-1} \nabla q$ and $\mathbf{w}_N = \Delta_N^{-1} \nabla q$. Then

$$\|\mathbf{w} - \mathbf{w}_N\|_1 = \inf_{\mathbf{v} \in X_N} \|\mathbf{w} - \mathbf{v}\|_1$$

hence

$$\begin{aligned} J(q) - J_N(q) &= \|\mathbf{w}\|_1 - \|\mathbf{w}_N\|_1 \leq \|\mathbf{w} - \mathbf{w}_N\|_1 \\ &\leq \varepsilon_{N,s} \|\mathbf{w}\|_{1+s} \\ &\leq C_s \varepsilon_{N,s} \|\nabla q\|_{-1+s} \leq C_s \varepsilon_{N,s} \|q\|_s \\ &\leq \eta_{N,s} C_s \varepsilon_{N,s} \|q\|_0 \end{aligned}$$

For $\|q\|_0 = 1$:

$$\begin{aligned} \beta(\Omega) &\leq J(q) = J_N(q) + (J(q) - J_N(q)) \\ &\leq J_N(q) + \eta_{N,s} C_s \varepsilon_{N,s} \end{aligned}$$

Minimizing over $q \in M_N$ gives the result

$$\beta(\Omega) \leq \beta_N + \eta_{N,s} C_s \varepsilon_{N,s}.$$

A. h version of the FEM

Let X_N and M_N be conforming finite element spaces defined on quasi-regular meshes with meshwidths h_{X_N} and h_{M_N} . Direct and inverse estimates are well known:

$$\eta_{N,s} = Ch_{M_N}^{-s}; \quad \varepsilon_{N,s} = Ch_{X_N}^s \quad (\text{any } s \in (0, \frac{1}{2}))$$

Corollary, h version

If $\lim_{N \rightarrow \infty} \frac{h_{X_N}}{h_{M_N}} = 0$, then $\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega)$.

B. p version of the FEM

Let X_N and M_N be finite element spaces of degrees p_{X_N} and p_{M_N} on fixed meshes. The known direct and inverse estimates are

$$\eta_{N,s} = C(p_{M_N})^{2s}; \quad \varepsilon_{N,s} = C(p_{X_N})^{-s}.$$

If $\lim_{N \rightarrow \infty} \frac{p_{X_N}}{p_{M_N}} = 0$, then $\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega)$.

A. h version of the FEM

Let X_N and M_N be conforming finite element spaces defined on quasi-regular meshes with meshwidths h_{X_N} and h_{M_N} . Direct and inverse estimates are well known:

$$\eta_{N,s} = C h_{M_N}^{-s}; \quad \varepsilon_{N,s} = C h_{X_N}^s \quad (\text{any } s \in (0, \frac{1}{2}))$$

Corollary, h version

If $\lim_{N \rightarrow \infty} \frac{h_{X_N}}{h_{M_N}} = 0$, then $\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega)$.

B. p version of the FEM

Let X_N and M_N be finite element spaces of degrees p_{X_N} and p_{M_N} on fixed meshes. The known direct and inverse estimates are

$$\eta_{N,s} = C (p_{M_N})^{2s}; \quad \varepsilon_{N,s} = C (p_{X_N})^{-s}.$$

Corollary, p version

If $\lim_{N \rightarrow \infty} \frac{p_{M_N}^2}{p_{X_N}} = 0$, then $\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega)$.

Are these conditions necessary?

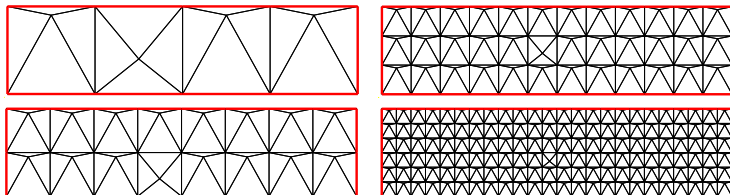
A. h version: Yes, sort of

Theorem [BCDG2016]

(iii) Given a polygon Ω , there exists $\beta_0 > 0$ such that for arbitrary $\beta_\infty \in (0, \beta_0)$ one can construct a finite element method with $h_{X_N} = h_{M_N}$ for which

$$\lim_{N \rightarrow \infty} \beta_N = \beta_\infty$$

Exemple: Scott-Vogelius P_4 - P_3^{dc} elements on “near-singular meshes”



B. p version: Probably not

Numerical observations:

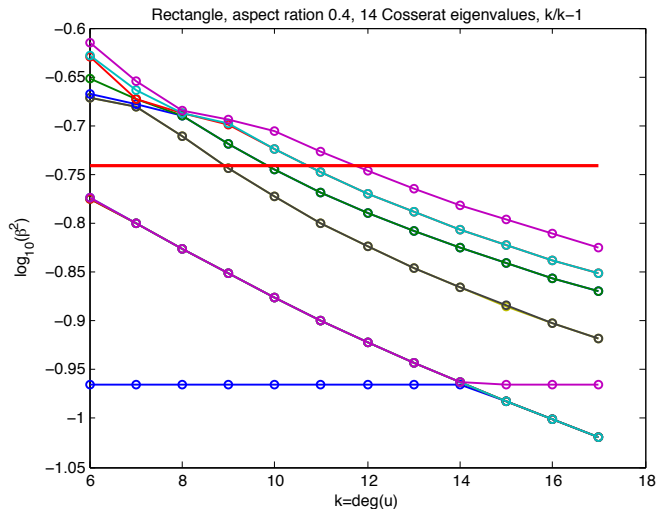
- 1 $p_{X_N} \sim p_{M_N} + k$: No convergence
(Known [Bernardi-Maday 1999]: $\beta_N \sim p^{-1/2} \rightarrow 0$)
- 2 $p_{X_N} \sim k \cdot p_{M_N}$, $k > 1$: Probably convergence
(Known [Bernardi-Maday 1999]: inf-sup stable)

Conjecture for the p version

As soon as the method is inf-sup stable, $\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega)$

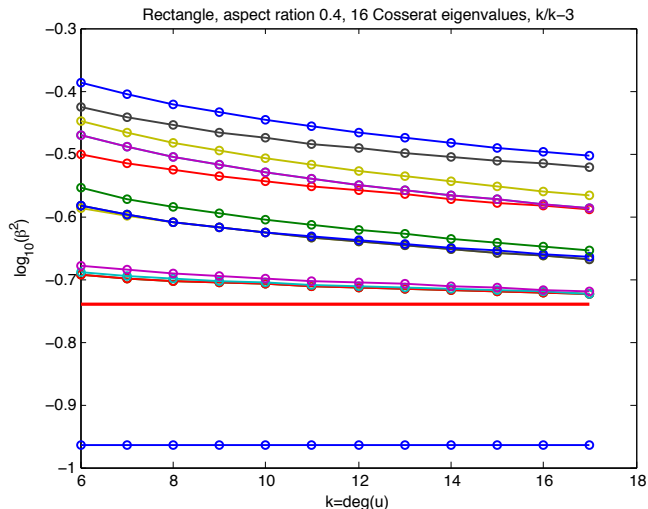
Rectangle, aspect ratio 0.4

First 13 Cosserat eigenvalues, (Q_k, Q_{k-1}) "Taylor-Hood"



Rectangle, aspect ratio 0.4

First 13 Cosserat eigenvalues, (Q_k, Q_{k-3})



Are these conditions necessary?

B. p version: Probably not

Numerical observations:

- 1 $p_{X_N} \sim p_{M_N} + k$: No convergence
(Known [Bernardi-Maday]: $\beta_N \sim p^{-1/2} \rightarrow 0$)
- 2 $p_{X_N} \sim k \cdot p_{M_N}$, $k > 1$: Probably convergence
(Known [Bernardi-Maday]: inf-sup stable)

Conjecture for the p version

As soon as the method is inf-sup stable, $\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega)$

And the convergence rates ?

Let us look at the rectangle again...

Are these conditions necessary?

B. p version: Probably not

Numerical observations:

- 1 $p_{X_N} \sim p_{M_N} + k$: No convergence
(Known [Bernardi-Maday]: $\beta_N \sim p^{-1/2} \rightarrow 0$)
- 2 $p_{X_N} \sim k \cdot p_{M_N}$, $k > 1$: Probably convergence
(Known [Bernardi-Maday]: inf-sup stable)

Conjecture for the p version

As soon as the method is inf-sup stable, $\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega)$

And the convergence rates ?

Let us look at the rectangle again

Are these conditions necessary?

B. p version: Probably not

Numerical observations:

- 1 $p_{X_N} \sim p_{M_N} + k$: No convergence
(Known [Bernardi-Maday]: $\beta_N \sim p^{-1/2} \rightarrow 0$)
- 2 $p_{X_N} \sim k \cdot p_{M_N}$, $k > 1$: Probably convergence
(Known [Bernardi-Maday]: inf-sup stable)

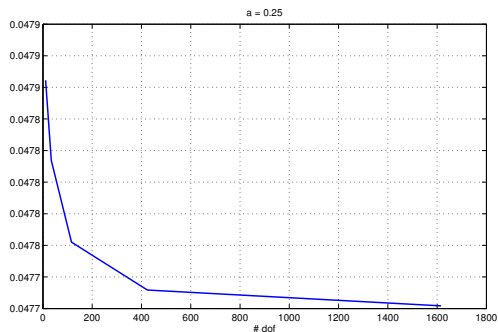
Conjecture for the p version

As soon as the method is inf-sup stable, $\lim_{N \rightarrow \infty} \beta_N = \beta(\Omega)$

And the convergence rates ?

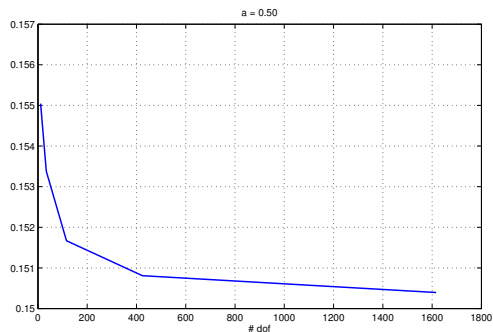
Let us look at the rectangle again...

The rectangle: Convergence of 1st Cosserat eigenvalue, $a = 0.25$



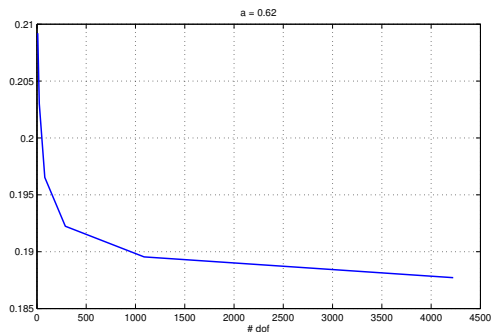
calc	extr	err	ord
0.047864495			
0.047813740			
0.047762043	0.050601250	0.002839206	1.233
0.047731711	0.047688648	0.000043063	1.661
0.047721678	0.047716719	0.000004959	1.653

The rectangle: Convergence of 1st Cosserat eigenvalue, $a = 0.5$



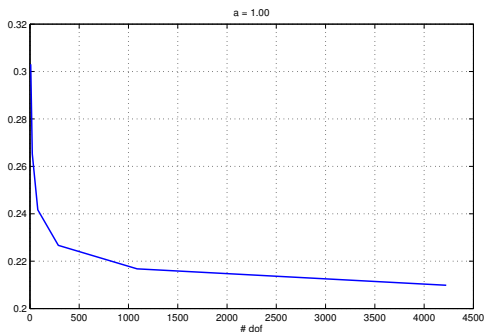
calc	extr	err	ord
0.155045590			
0.153379211			
0.151668328	0.217441888	0.065773559	0.572
0.150808779	0.149940934	0.000867845	1.165
0.150394460	0.150008906	0.000385553	1.064

The rectangle: Convergence of 1st Cosserat eigenvalue, $a = 0.62$



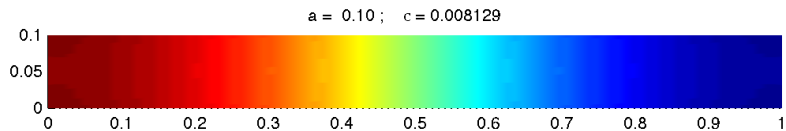
calc	extr	err	ord
0.209208446			
0.203020937			
0.196526729	0.334039166	0.137512437	0.452
0.192239043	0.183907261	0.008331782	0.845
0.189536554	0.184929274	0.004607279	0.769
0.187710936	0.183910061	0.003800875	0.667

The rectangle: Convergence of 1st Cosserat eigenvalue, $a = 1$

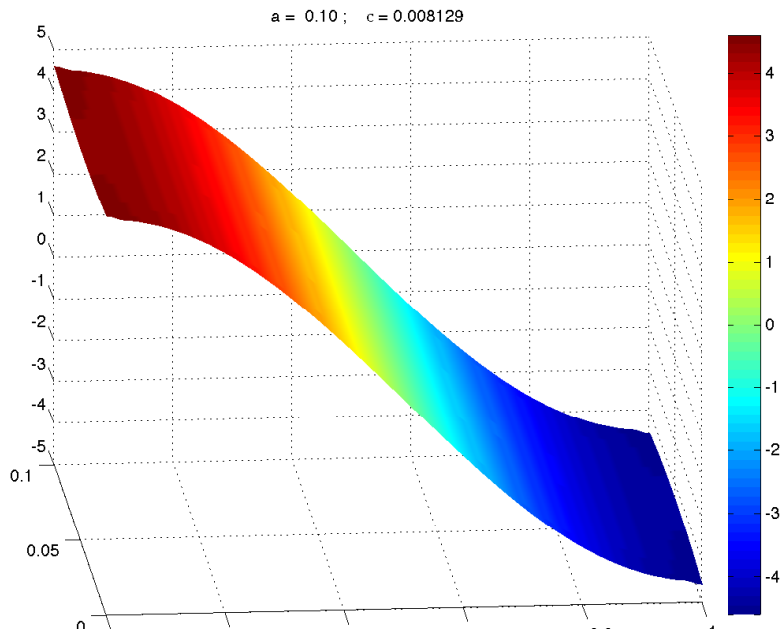


calc	extr	err	ord
0.303075403			
0.265273420			
0.241665485	0.202400120	0.039265365	0.738
0.226676132	0.200606788	0.026069343	0.644
0.216753160	0.197318117	0.019435043	0.563
0.209836989	0.193928572	0.015908412	0.496

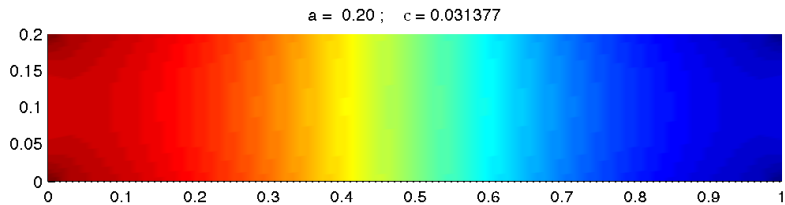
First Cosserat eigenfunction on rectangles : $a=0.10$



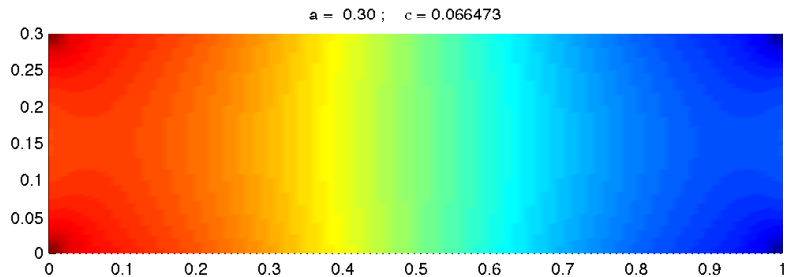
First Cosserat eigenfunction on rectangles : $a=0.10$



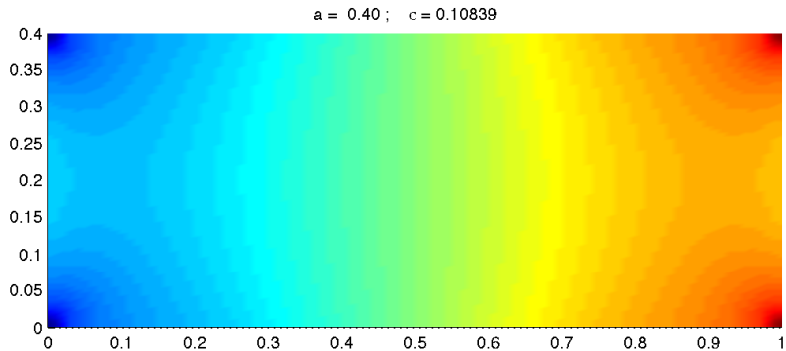
First Cosserat eigenfunction on rectangles : $a=0.20$



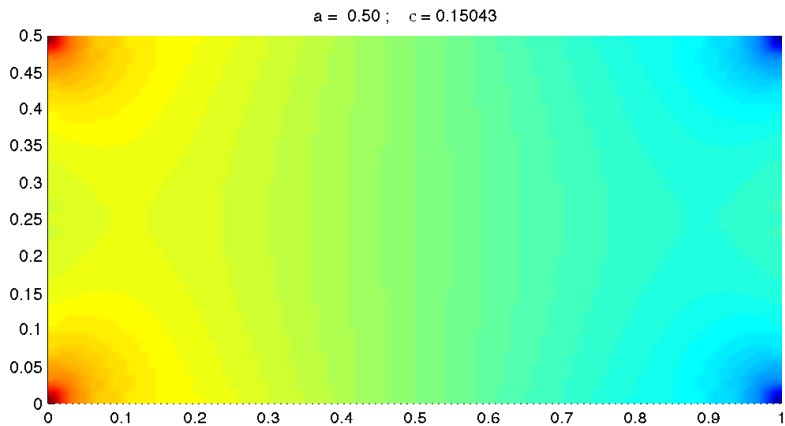
First Cosserat eigenfunction on rectangles : $a=0.30$



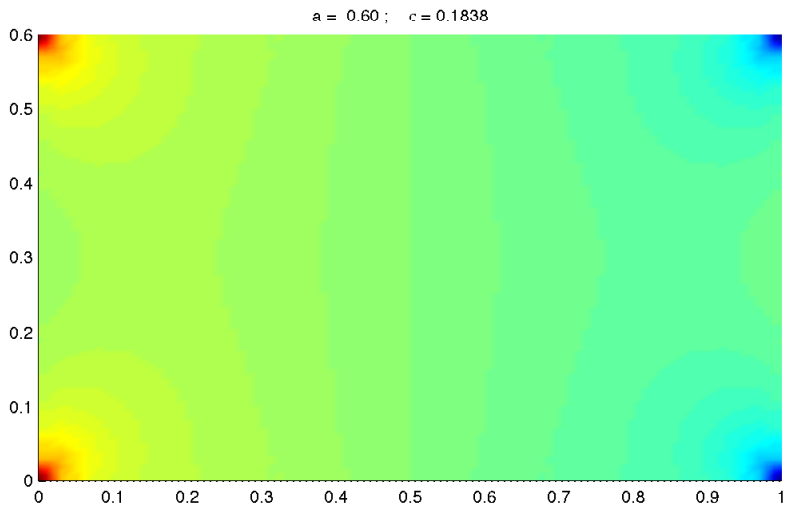
First Cosserat eigenfunction on rectangles : $a=0.40$



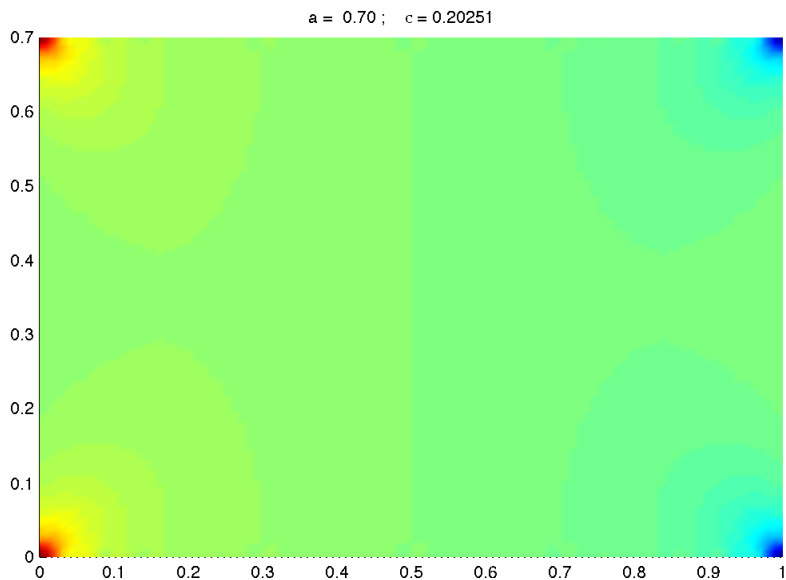
First Cosserat eigenfunction on rectangles : $a=0.50$



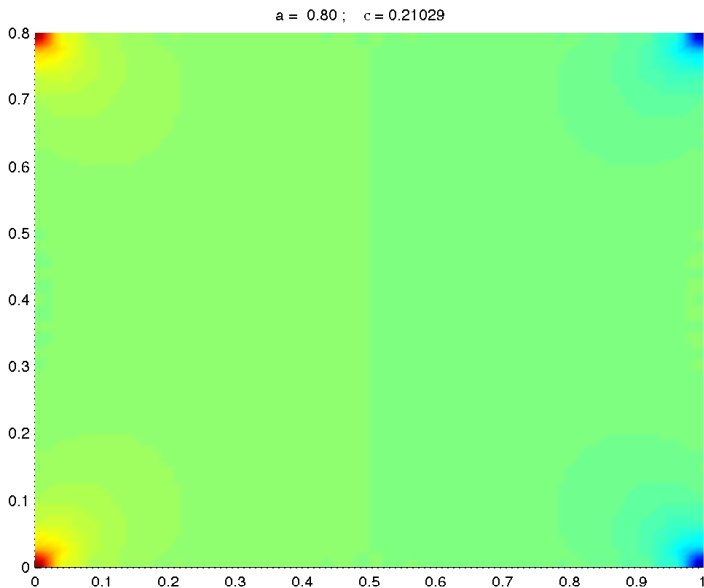
First Cosserat eigenfunction on rectangles : $a=0.60$



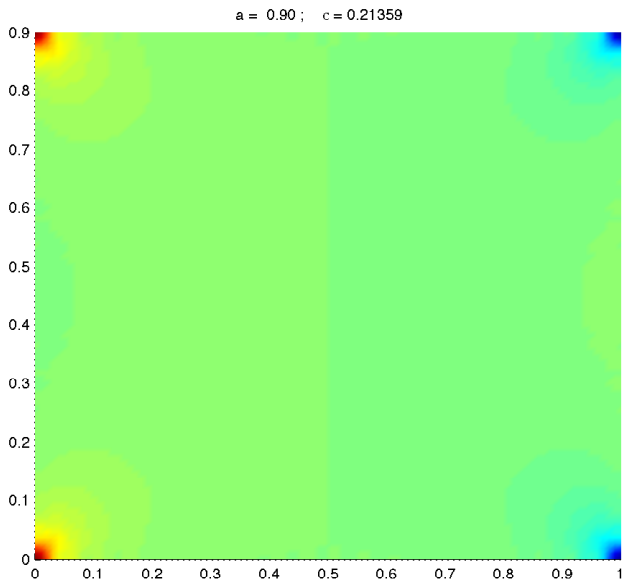
First Cosserat eigenfunction on rectangles : $a=0.70$



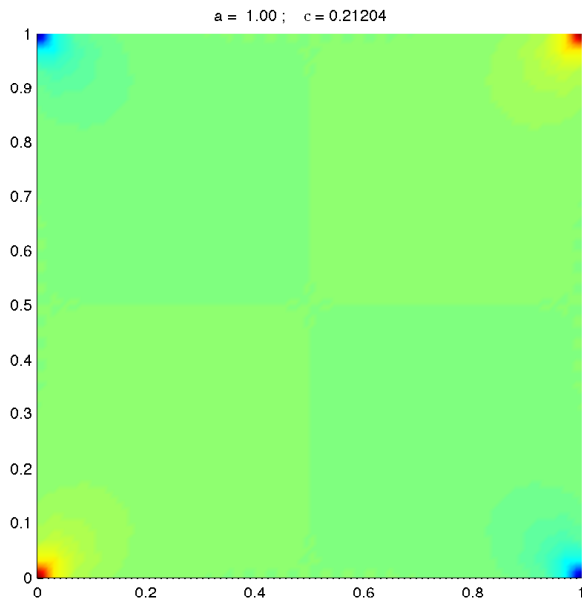
First Cosserat eigenfunction on rectangles : $a=0.80$



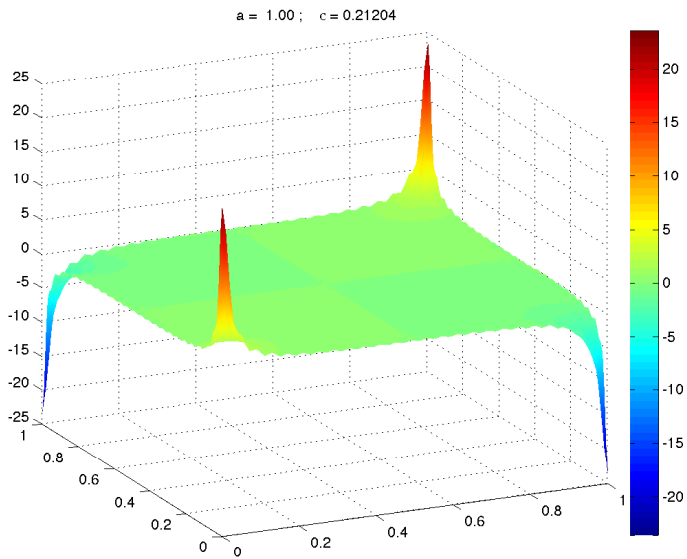
First Cosserat eigenfunction on rectangles : $a=0.90$



First Cosserat eigenfunction on rectangles : $a=1.00$



First Cosserat eigenfunction on rectangles : $a=1.00$



For $\sigma \notin \{0, \frac{1}{2}, 1\}$, the operator $A_\sigma = -\sigma\Delta + \nabla \operatorname{div}$ is **elliptic**.

If $\Omega \subset \mathbb{R}^2$ has a corner of opening ω , one can therefore determine the corner singularities via **Kondrat'ev's** method of **Mellin transformation**:

Look for solutions \mathbf{u} of the form $r^\lambda \phi(\theta)$ in a sector. $\rightarrow q \sim r^{\lambda-1} \phi(\theta)$

Characteristic equation (Lamé system, known!) for a corner of opening ω :

$$(*) \quad (1 - 2\sigma)\omega \frac{\sin \lambda \omega}{\lambda \omega} = \pm \sin \omega.$$

Theorem [Kondrat'ev 1967]

For $\sigma \in [0, 1] \setminus \{0, \frac{1}{2}, 1\}$, $A_\sigma : H_0^1(\Omega) \rightarrow \mathbf{H}^{-1}(\Omega)$ is **Fredholm** iff the equation (*) has no solution on the line **$\operatorname{Re} \lambda = 0$** .

Result:

- (*) has roots on the line $\operatorname{Re} \lambda = 0$ iff $(1 - 2\sigma)\omega \leq |\sin \omega|$
- if $(1 - 2\sigma)\omega > |\sin \omega|$, there is a real root $\lambda \in (0, 1)$

For $\sigma \notin \{0, \frac{1}{2}, 1\}$, the operator $A_\sigma = -\sigma\Delta + \nabla \operatorname{div}$ is **elliptic**.

If $\Omega \subset \mathbb{R}^2$ has a corner of opening ω , one can therefore determine the corner singularities via **Kondrat'ev's** method of **Mellin transformation**:

Look for solutions \mathbf{u} of the form $r^\lambda \phi(\theta)$ in a sector. $\rightarrow \mathbf{q} \sim r^{\lambda-1} \phi(\theta)$

Characteristic equation (Lamé system, known!) for a corner of opening ω :

$$(*) \quad (1 - 2\sigma)\omega \frac{\sin \lambda \omega}{\lambda \omega} = \pm \sin \omega.$$

Theorem [Kondrat'ev 1967]

For $\sigma \in [0, 1] \setminus \{0, \frac{1}{2}, 1\}$, $A_\sigma : H_0^1(\Omega) \rightarrow \mathbf{H}^{-1}(\Omega)$ is **Fredholm** iff the equation (*) has no solution on the line **$\operatorname{Re} \lambda = 0$** .

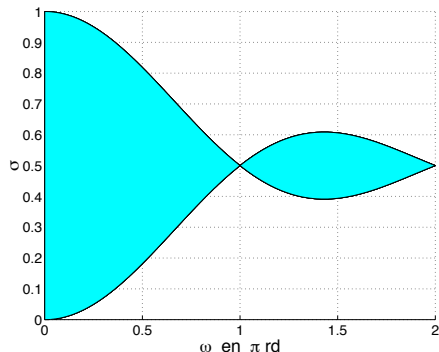
Result :

- (*) has roots on the line $\operatorname{Re} \lambda = 0$ iff $|1 - 2\sigma|\omega \leq |\sin \omega|$
- If $|1 - 2\sigma|\omega > |\sin \omega|$, there is a real root $\lambda \in (0, 1)$

Result [Co-Crouzeix-Dauge-Lafranche 2015]

$\Omega \subset \mathbb{R}^2$ piecewise smooth with corners of opening ω_j .

$$\text{Sp}_{\text{Ess}}(\mathcal{L}) = \bigcup_{\text{corners } j} \left[\frac{1}{2} - \frac{|\sin \omega_j|}{2\omega_j}, \frac{1}{2} + \frac{|\sin \omega_j|}{2\omega_j} \right] \cup \{1\}$$



Essential spectrum: σ vs. opening ω

Example : Rectangle, $\omega = \frac{\pi}{2}$

$$\text{Sp}_{\text{Ess}}(\mathcal{L} \Big|_M) = \left[\frac{1}{2} - \frac{1}{\pi}, \frac{1}{2} + \frac{1}{\pi} \right] \\ \approx [0.181, 0.818]$$

Corollary: Square $\Omega = \square$

$$\beta(\square)^2 \leq \frac{1}{2} - \frac{1}{\pi}$$


 Ω_1

 Ω_2

 Ω_5

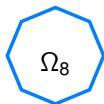
$\beta(\Omega_N) \leq \beta(\text{corner}) < \sqrt{\frac{1}{2}} = \beta(\Omega)$ (disc)
 \implies No convergence


 Ω_1

 Ω_2

 Ω

Cusps $0 < y < x^{1+1/N}$:
 $\beta(\Omega_N) = 0$, \rightarrow triangle $\beta(\Omega) > 0$
 \implies No convergence


 Ω_4

 Ω_8

 Ω_{16}

Regular polygons,
 $0 \leq \beta(\Omega) - \beta(\Omega_N) \leq \frac{\pi}{2N}$: Convergence

$\Omega_N \subset \Omega$ with $\text{meas}(\Omega \setminus \Omega_N) \rightarrow 0 \implies \limsup \beta(\Omega_N) \leq \beta(\Omega)$

Let Ω_N converge to Ω in Lipschitz norm, that is: $\tilde{\gamma}_N: \Omega_N \rightarrow \Omega$ is a b -Lipschitz homeomorphism such that $\|\nabla(\tilde{\gamma}_N - \text{Id})\|_{L^\infty} \rightarrow 0$.

Then $\lim_{N \rightarrow \infty} \beta(\Omega_N) = \beta(\Omega)$


 Ω_1

 Ω_2

 Ω_5

$\beta(\Omega_N) \leq \beta(\text{corner}) < \sqrt{\frac{1}{2}} = \beta(\Omega)$ (disc)
 \implies No convergence


 Ω_1

 Ω_2

 Ω

Cusps $0 < y < x^{1+1/N}$:
 $\beta(\Omega_N) = 0$, \rightarrow triangle $\beta(\Omega) > 0$
 \implies No convergence


 Ω_4

 Ω_8

 Ω_{16}

Regular polygons,
 $0 \leq \beta(\Omega) - \beta(\Omega_N) \leq \frac{\pi}{2N}$: Convergence

Inner approximation: Upper semicontinuity

$\Omega_N \subset \Omega$ with $\text{meas}(\Omega \setminus \Omega_N) \rightarrow 0 \implies \limsup \beta(\Omega_N) \leq \beta(\Omega)$

Let Ω_N converge to Ω in Lipschitz norm, that is: $\tilde{\gamma}_N: \Omega_N \rightarrow \Omega$ is a b -Lipschitz homeomorphism such that $\|\nabla(\tilde{\gamma}_N - \text{Id})\|_{L^\infty} \rightarrow 0$.

Then $\lim_{N \rightarrow \infty} \beta(\Omega_N) = \beta(\Omega)$


 Ω_1

 Ω_2

 Ω_5

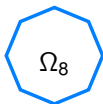
$\beta(\Omega_N) \leq \beta(\text{corner}) < \sqrt{\frac{1}{2}} = \beta(\Omega)$ (disc)
 \implies No convergence


 Ω_1

 Ω_2

 Ω

Cusps $0 < y < x^{1+1/N}$:
 $\beta(\Omega_N) = 0$, \rightarrow triangle $\beta(\Omega) > 0$
 \implies No convergence


 Ω_4

 Ω_8

 Ω_{16}

Regular polygons,
 $0 \leq \beta(\Omega) - \beta(\Omega_N) \leq \frac{\pi}{2N}$: Convergence

Inner approximation: Upper semicontinuity

$\Omega_N \subset \Omega$ with $\text{meas}(\Omega \setminus \Omega_N) \rightarrow 0 \implies \limsup \beta(\Omega_N) \leq \beta(\Omega)$

Approximation in Lipschitz norm: Continuity

Let Ω_N converge to Ω in Lipschitz norm, that is: $\mathfrak{F}_N : \Omega_N \rightarrow \Omega$ is a bi-Lipschitz homeomorphism such that $\|\nabla(\mathfrak{F}_N - \text{Id})\|_{L^\infty} \rightarrow 0$.

Then

$$\lim_{N \rightarrow \infty} \beta(\Omega_N) = \beta(\Omega)$$

Thank you for your attention!

Thank you for your attention!

Thank you for your attention!

Thank you for your attention!

Thank you for your attention!

Theorem [Acosta-Durán-Muschietti 2006], [Durán 2012]

Let $\Omega \subset \mathbb{R}^d$ be a bounded **John domain**. Then $\beta(\Omega) > 0$.

Theorem [Acosta-Durán-Muschietti 2006], [Durán 2012]

Let $\Omega \subset \mathbb{R}^d$ be a bounded **John domain**. Then $\beta(\Omega) > 0$.

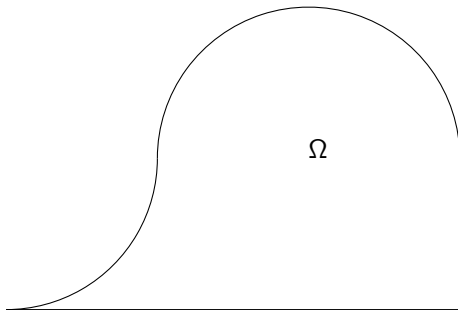


Figure: **Not a John domain**: Outward cusp, $\beta(\Omega) = 0$ [Friedrichs 1937]

Definition

A domain $\Omega \subset \mathbb{R}^d$ with a distinguished point \mathbf{x}_0 is called a **John domain** if it satisfies the following “**twisted cone**” condition:

There exists a constant $\delta > 0$ such that, for any \mathbf{y} in Ω , there is a rectifiable curve $\gamma: [0, \ell] \rightarrow \Omega$ parametrized by arclength such that

$$\gamma(0) = \mathbf{y}, \quad \gamma(\ell) = \mathbf{x}_0, \quad \text{and} \quad \forall t \in [0, \ell] : \text{dist}(\gamma(t), \partial\Omega) \geq \delta t.$$

Here $\text{dist}(\gamma(t), \partial\Omega)$ denotes the distance of $\gamma(t)$ to the boundary $\partial\Omega$.

Example: Every weakly Lipschitz domain is a John domain.

Definition

A domain $\Omega \subset \mathbb{R}^d$ with a distinguished point \mathbf{x}_0 is called a **John domain** if it satisfies the following “**twisted cone**” condition:

There exists a constant $\delta > 0$ such that, for any \mathbf{y} in Ω , there is a rectifiable curve $\gamma: [0, \ell] \rightarrow \Omega$ parametrized by arclength such that

$$\gamma(0) = \mathbf{y}, \quad \gamma(\ell) = \mathbf{x}_0, \quad \text{and} \quad \forall t \in [0, \ell] : \text{dist}(\gamma(t), \partial\Omega) \geq \delta t.$$

Here $\text{dist}(\gamma(t), \partial\Omega)$ denotes the distance of $\gamma(t)$ to the boundary $\partial\Omega$.

Example : Every weakly Lipschitz domain is a John domain.



San Juan de la Peña, Jaca 2013

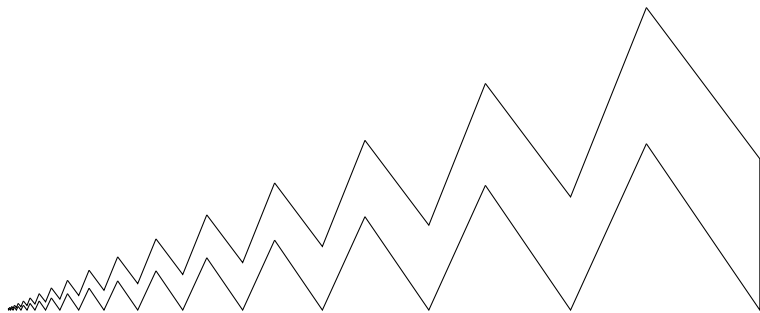


Figure: A weakly Lipschitz domain: the self-similar zigzag

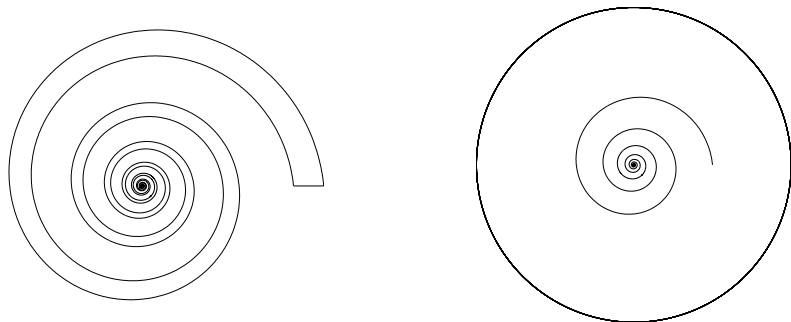
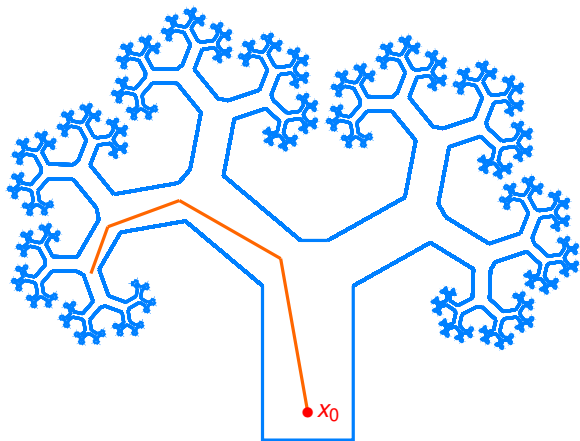


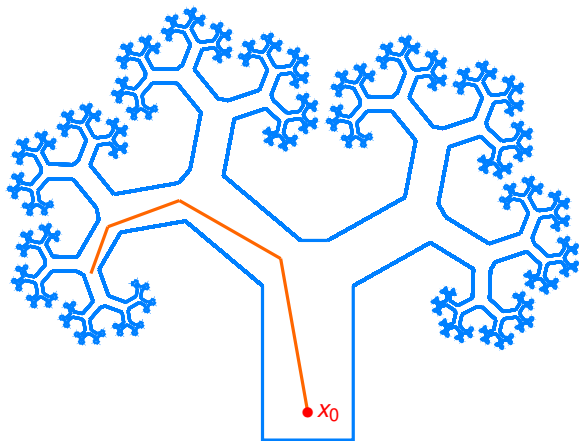
Figure: Weakly Lipschitz (left), John domain (right)

Fractal John domains: Tree or Lung



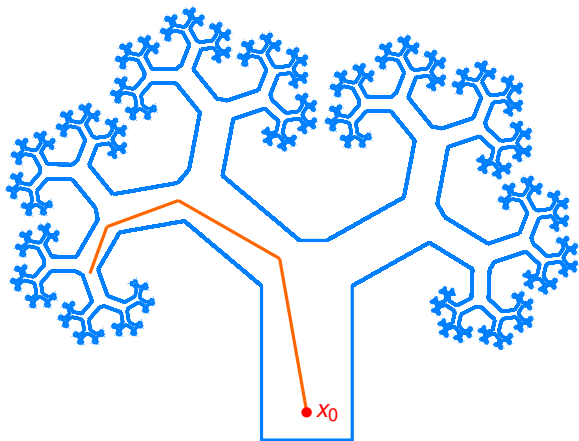
◀ back

Fractal John domains: Tree or Lung



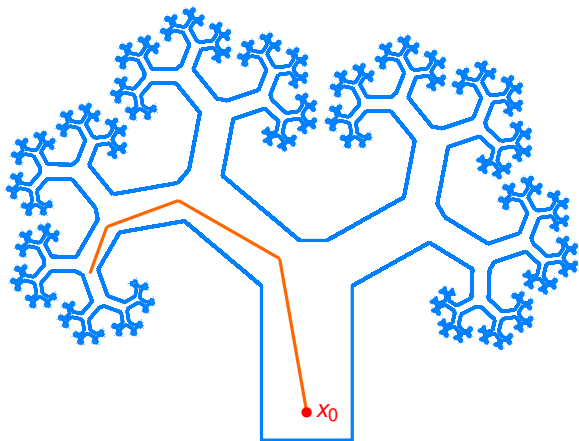
◀ back

Fractal John domains: Tree or Lung



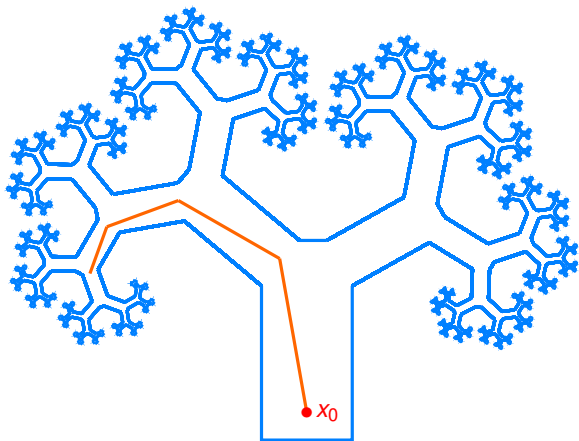
◀ back

Fractal John domains: Tree or Lung



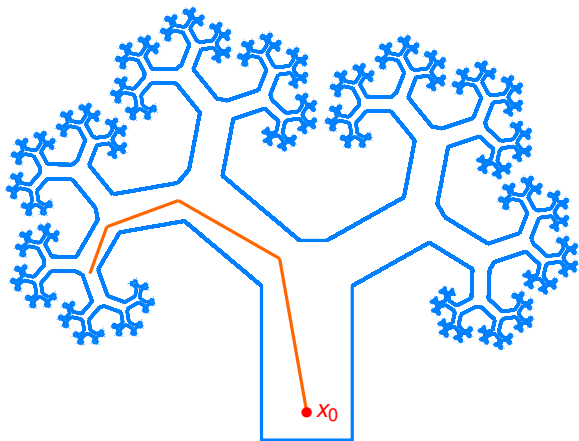
◀ back

Fractal John domains: Tree or Lung



◀ back

Fractal John domains: Tree or Lung



◀ back

inf-sup condition

$$\inf_{q \in L^2_\circ(\Omega)} \sup_{\mathbf{v} \in H_0^1(\Omega)^d} \frac{\langle \operatorname{div} \mathbf{v}, q \rangle}{|\mathbf{v}|_1 \|q\|_0} \geq \beta > 0$$

Lions' lemma [Lions 1958, Nečas 1965]

$$\forall q \in L^2_\circ(\Omega) : \|q\|_0 \leq C |\nabla q|_{-1}; \quad C = \frac{1}{\beta} < \infty$$

Babuška-Aziz inequality [B-A 1971, Bogovskiĭ 1979]

$$\forall q \in L^2_\circ(\Omega) \exists \mathbf{v} \in H_0^1(\Omega)^d : \operatorname{div} \mathbf{v} = q \text{ and } |\mathbf{v}|_1^2 \leq C \|q\|_0^2; \quad C = \frac{1}{\beta^2} < \infty$$

Linearized strain tensor $\mathbf{e}(u) = \frac{1}{2}(\nabla \mathbf{u} + (\nabla \mathbf{u})^\top)$

Korn's second inequality

If $\nabla \mathbf{u} - (\nabla \mathbf{u})^\top \in L^2_0(\Omega)$, then

$$\|\nabla \mathbf{u}\|_0^2 \leq K(\Omega) \|\mathbf{e}(u)\|_0^2$$

If the LBB condition is satisfied for Ω , Korn's inequality follows:

$$\partial_i \partial_j u_k = \partial_i e_{jk} + \partial_j e_{jk} - \partial_k e_{ij}, \quad \mathbf{e} = \mathbf{e}(u)$$

$$\implies |\nabla \nabla \mathbf{u}|_{-1} \sim |\nabla \mathbf{e}(u)|_{-1} \implies \|\nabla \mathbf{u}\|_0 \sim \|\mathbf{e}(u)\|_0$$

For $\Omega \subset \mathbb{R}^d$, LBB implies Korn: $K(\Omega) \leq 1 + \frac{2(d-1)}{\beta(\Omega)^2}$.

1 Any bounded domain $\Omega \subset \mathbb{R}^d$: ($C(\Omega) = \beta(\Omega)^{-2}$)
 LBB \implies Korn, $K(\Omega) \leq 1 + 2(d-1)C(\Omega)$.

2 $d = 2$, Ω simply connected:
 LBB \iff Korn, $C(\Omega) \leq K(\Omega) \leq 1 + 2C(\Omega)$

3 $d = 2$, Ω simply connected, Lipschitz: $K(\Omega) = 2C(\Omega)$

For smooth domains:

C.O. HORGAN, L.E. PAYNE, *On Inequalities of Korn, Friedrichs and Babuška-Aziz*. ARMA 82 (1983), 165–179.

For Lipschitz domains: [Costabel-Dauge 201?]

4 $d = 2$, $\Omega = B_+ \setminus \bar{B}_-$ (not simply connected): $K(\Omega) \neq 2C(\Omega)$
 [Dattner 1988 (Korn), Chirilus-Brukner–Chirilus-Brukner 2000 (LBB)]

- ① Any bounded domain $\Omega \subset \mathbb{R}^d$: ($C(\Omega) = \beta(\Omega)^{-2}$)
LBB \implies Korn, $K(\Omega) \leq 1 + 2(d-1)C(\Omega)$.
- ② $d = 2$, Ω simply connected:
LBB \iff Korn, $C(\Omega) \leq K(\Omega) \leq 1 + 2C(\Omega)$
- ③ $d = 2$, Ω simply connected, Lipschitz: $K(\Omega) = 2C(\Omega)$
For smooth domains:
C.O. HORGAN, L.E. PAYNE, *On Inequalities of Korn, Friedrichs and Babuška-Aziz*. ARMA 82 (1983), 165–179.
For Lipschitz domains: [Costabel-Dauge 201?]
- ④ $d = 2$, $\Omega = B_{r_2} \setminus \overline{B_{r_1}}$ (not simply connected): $K(\Omega) \neq 2C(\Omega)$
[Dafermos 1968 (Korn), Chizhonkov–Olshanskii 2000 (LBB)]

- 1 Any bounded domain $\Omega \subset \mathbb{R}^d$:
LBB \implies Korn, $K(\Omega) \leq 1 + 2(d-1) C(\Omega)$.
- 2 $d = 2$, Ω simply connected:
LBB \iff Korn, $C(\Omega) \leq K(\Omega) \leq 1 + 2 C(\Omega)$
- 3 $d = 2$, Ω simply connected, Lipschitz: $K(\Omega) = 2 C(\Omega)$
For smooth domains:
C.O. HORGAN, L.E. PAYNE, *On Inequalities of Korn, Friedrichs and Babuška-Aziz*. ARMA 82 (1983), 165–179.
For Lipschitz domains: [Costabel-Dauge 201?]
- 4 $d = 2$, $\Omega = B_{r_2} \setminus \overline{B_{r_1}}$ (not simply connected): $K(\Omega) \neq 2 C(\Omega)$
[Dafermos 1968 (Korn), Chizhonkov–Olshanskii 2000 (LBB)]

Currently open problems:

- 1 Is Korn \implies LBB true for arbitrary domains?
- 2 What are the optimal bounds between Korn and LBB?
- 3 Is $K(\Omega) = 2 C(\Omega)$ true for arbitrary simply connected domains in \mathbb{R}^2 ?

Friedrichs' inequality [named by Horgan-Payne 1983]

There exists a constant Γ such that for any holomorphic $f + ig \in L^2_\circ(\Omega)$

$$\|f\|_0^2 \leq \Gamma \|g\|_0^2$$

Theorem [Friedrichs 1937]

True for piecewise smooth domains $\Omega \subset \mathbb{R}^2$ with no outward cusps.

Definition: $\Gamma(\Omega) = \inf \Gamma$.

Theorem

[Horgan-Payne 1983] Let $\Omega \subset \mathbb{R}^2$ be bounded, simply connected, and C^2 . Then

$$\frac{1}{\beta(\Omega)^2} = \Gamma(\Omega) + 1.$$

[Costabel-Dauge 2015] This is true for any bounded domain $\Omega \subset \mathbb{R}^2$.

Friedrichs-Velte inequality [Velte 1998]

Let $\Omega \subset \mathbb{R}^3$ be a bounded smooth domain. There exists a constant Γ_1 such that for any

$$f \in L^2_0(\Omega), \mathbf{g} \in L^2(\Omega)^3 \text{ such that } \nabla f = \mathbf{curl} \mathbf{g} : \quad \|f\|_0^2 \leq \Gamma_1 \|\mathbf{g}\|_0^2.$$

Definition: $\Gamma_1(\Omega) = \inf \Gamma_1$.

Theorem

[Velte 1998] Let $\Omega \subset \mathbb{R}^3$ be bounded, simply connected, and C^2 . Then

$$\frac{1}{\beta(\Omega)^2} = \Gamma_1(\Omega) + 1.$$

[Costabel 2015] This is true for any bounded domain $\Omega \subset \mathbb{R}^3$.

◀ back

Friedrichs-Velte inequality [Velte 1998]

Let $\Omega \subset \mathbb{R}^3$ be a bounded smooth domain. There exists a constant Γ_1 such that for any

$$f \in L^2_\circ(\Omega), \mathbf{g} \in L^2(\Omega)^3 \text{ such that } \nabla f = \mathbf{curl} \mathbf{g} : \quad \|f\|_0^2 \leq \Gamma_1 \|\mathbf{g}\|_0^2.$$

Definition: $\Gamma_1(\Omega) = \inf \Gamma_1$.

Theorem

[Velte 1998] Let $\Omega \subset \mathbb{R}^3$ be bounded, simply connected, and C^2 . Then

$$\frac{1}{\beta(\Omega)^2} = \Gamma_1(\Omega) + 1.$$

[Costabel 2015] This is true for any bounded domain $\Omega \subset \mathbb{R}^3$.

◀ back

Friedrichs-Velte inequality [Velte 1998]

Let $\Omega \subset \mathbb{R}^3$ be a bounded smooth domain. There exists a constant Γ_1 such that for any

$$f \in L^2_0(\Omega), \mathbf{g} \in L^2(\Omega)^3 \text{ such that } \nabla f = \mathbf{curl} \mathbf{g} : \quad \|f\|_0^2 \leq \Gamma_1 \|\mathbf{g}\|_0^2.$$

Definition: $\Gamma_1(\Omega) = \inf \Gamma_1$.

Theorem

[Velte 1998] Let $\Omega \subset \mathbb{R}^3$ be bounded, simply connected, and C^2 . Then

$$\frac{1}{\beta(\Omega)^2} = \Gamma_1(\Omega) + 1.$$

[Costabel 2015] This is true for any bounded domain $\Omega \subset \mathbb{R}^3$.

Friedrichs-Velte inequality [Velte 1998]

Let $\Omega \subset \mathbb{R}^3$ be a bounded smooth domain. There exists a constant Γ_1 such that for any

$$f \in L^2_\circ(\Omega), \mathbf{g} \in L^2(\Omega)^3 \text{ such that } \nabla f = \mathbf{curl} \mathbf{g} : \quad \|f\|_0^2 \leq \Gamma_1 \|\mathbf{g}\|_0^2.$$

Definition: $\Gamma_1(\Omega) = \inf \Gamma_1$.

Theorem

[Velte 1998] Let $\Omega \subset \mathbb{R}^3$ be bounded, simply connected, and C^2 . Then

$$\frac{1}{\beta(\Omega)^2} = \Gamma_1(\Omega) + 1.$$

[Costabel 2015] This is true for any bounded domain $\Omega \subset \mathbb{R}^3$.

Friedrichs-Velte inequality [Velte 1998]

Let $\Omega \subset \mathbb{R}^3$ be a bounded smooth domain. There exists a constant Γ_1 such that for any

$$f \in L^2_\circ(\Omega), \mathbf{g} \in L^2(\Omega)^3 \text{ such that } \nabla f = \mathbf{curl} \mathbf{g} : \quad \|f\|_0^2 \leq \Gamma_1 \|\mathbf{g}\|_0^2.$$

Definition: $\Gamma_1(\Omega) = \inf \Gamma_1$.

Theorem

[Velte 1998] Let $\Omega \subset \mathbb{R}^3$ be bounded, simply connected, and C^2 . Then

$$\frac{1}{\beta(\Omega)^2} = \Gamma_1(\Omega) + 1.$$

[Costabel 2015] This is true for any bounded domain $\Omega \subset \mathbb{R}^3$.