

Diff:

Differences between given skeleton and solution

In order to make the sample solution easier to understand, the differences between it and the given skeleton source code were highlighted with the help of the program `diff`.

Legend:

- Gray: unchanged text (only excerpts).
- Green: new lines
- Yellow: changed lines
- Red: deleted lines

Note: Files not listed have not been changed.

This document was created with the help of [diff2html](#) erstellt.


```

56
57
58 # task 11.1.5
59 # limit input characters (only float numbers should be allowed)
60 # ...
61
62 # task 11.1.6
63 # set alignment
64 # ....
65
66
67 # optional: set focus to the exit button
68
69
70
71
72
73
74
75
76
77
78
79
80
81
82
83
84
85
86 # Create ConfigParser and pass data
87 c = configparser.ConfigParser()
88 c.set("XXX", "XXX", mass1_edit.text())
89 c.XXX
90
91 # write config file
92 with open(filename, 'w') as fid:
93
94
95
96
97
98
99
100
101
102
103
104
105
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107
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109
110
111
112
113
114
115
116
117
118 # pass values to the according QLineEdit instances
119 # mass1_edit.setText(...).
120
121
122
123
124 def simulate():
125
126
127
128
129
130
131
132 # fetch values from the gui
133 m1 = float(mass1_edit.text())
134 # ...

```

```

81
82
83 # task 11.1.5
84 # limit input characters (only float numbers should be allowed)
85 length_edit.setValidator(QtGui.QDoubleValidator(length_edit)).
86 mass1_edit.setValidator(QtGui.QDoubleValidator(mass1_edit))
87 mass2_edit.setValidator(QtGui.QDoubleValidator(mass2_edit))
88 step_size_edit.setValidator(QtGui.QDoubleValidator(step_size_edit))
89 duration_edit.setValidator(QtGui.QDoubleValidator(duration_edit))
90
91
92 # task 11.1.6
93 # set alignment
94 length_edit.setAlignment(QtCore.Qt.AlignRight).
95 mass1_edit.setAlignment(QtCore.Qt.AlignRight)
96 mass2_edit.setAlignment(QtCore.Qt.AlignRight)
97 step_size_edit.setAlignment(QtCore.Qt.AlignRight)
98 duration_edit.setAlignment(QtCore.Qt.AlignRight)
99
100
101 # optional: set focus to the exit button
102
103
104
105
106
107
108
109 # Create ConfigParser and pass data
110 c = configparser.ConfigParser()
111
112
113
114
115
116
117
118
119
120
121
122 c.add_section('Parameter')
123 c.set('Parameter', 'm1', str(mass1_edit.text()))
124 c.set('Parameter', 'm2', str(mass2_edit.text()))
125 c.set('Parameter', 'l', str(duration_edit.text()))
126
127 c.add_section('Simulation')
128 c.set('Simulation', 'dt', str(step_size_edit.text()))
129 c.set('Simulation', 't_end', str(duration_edit.text()))
130
131 # write config file
132 with open(filename, 'w') as fid:
133
134
135
136
137
138
139
140
141
142
143
144
145
146
147
148
149
150
151
152
153
154
155
156
157
158 # pass values to the according QLineEdit instances
159 mass1_edit.setText(c.get('Parameter', 'm1')).
160 mass2_edit.setText(c.get('Parameter', 'm2')).
161 duration_edit.setText(c.get('Parameter', 'l'))
162
163 step_size_edit.setText(c.get('Simulation', 'dt'))
164 duration_edit.setText(c.get('Simulation', 't_end'))
165
166
167 def simulate():
168
169
170
171
172
173
174
175 # fetch values from the gui
176 m1 = float(mass1_edit.text())
177 m2 = float(mass2_edit.text()).
178 l = float(duration_edit.text())

```

```

179 dx = float(step_size_edit.text())
180 t_end = float(duration_edit.text())
181
182 # alternatively:
183 # m1 = mass1_edit.text().toDouble()[0] # returns tuple like (value, OK)
184
135 # create time array
136 # t = ...
137
138 # execute simulation (todo: use solve_ivp here) see task description.
139 # res ...
140
141 # Plot the results
142 # Here we have to do some trickery: we create a new dialog on which
143
144
151 # result for the trolley
152 ax1 = fig.add_subplot(2, 1, 1)
153 # ...
154
155
156 # result for the load
157 # ax2 = ...
158
159
160 # Here now the dialog is displayed and no longer the show function of
161 # matplotlib is called
162 plot_dialog.show().
163
164
165 # task 11.1.7
166 # connect button
167 # simulation_button.clicked.XXX.
168
169 # task 11.2.1
170 # ...
171
172 #-----
173
184
185 # create time array
186 t = arange(0, t_end, dx).
187
188 # execute simulation (todo: use solve_ivp here).
189 res = odeint(rhs, [0, 0.3, 0, 0], t, args=(m1, m2, l)).
190
191 # Plot the results
192 # Here we have to do some trickery: we create a new dialog on which
193
194
200 # result for the trolley
201 ax1 = fig.add_subplot(2, 1, 1)
202 ax1.plot(t, res[:, 0], label='x').
203 ax1.plot(t, res[:, 2], label='dx')
204
205
206 ax1.grid(True)
207 ax1.legend()
208 ax1.set_ylabel('trolley')
209
210 # result for the load
211 ax2 = fig.add_subplot(2, 1, 2).
212 ax2.plot(t, res[:, 1], label=r"$\varphi$")
213 ax2.plot(t, res[:, 3], label=r"$\dot{\varphi}$")
214
215 ax2.grid(True)
216 ax2.legend()
217 ax2.set_xlabel('time [s]')
218 ax2.set_ylabel('load')
219
220 # Here now the dialog is displayed and no longer the show function of
221 # matplotlib is called
222 plotDialog.show().
223
224
225 # task 11.1.7
226 # connect button
227 simulation_button.clicked.connect(simulate).
228
229 # task 11.2.1
230 .
231 open_button = QtWidgets.QPushButton('Open', dialog)
232 save_button = QtWidgets.QPushButton('Save', dialog)
233
234 open_button.clicked.connect(openFile)
235 save_button.clicked.connect(saveFile)
236
237 layout.addWidget(open_button, 7, 1, QtCore.Qt.AlignRight)
238 layout.addWidget(save_button, 8, 1, QtCore.Qt.AlignRight)
239
240
241 #-----
242

```